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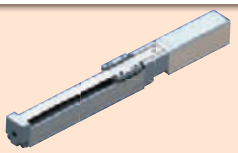
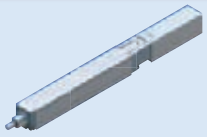
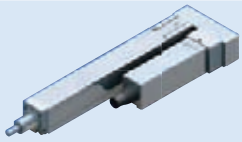
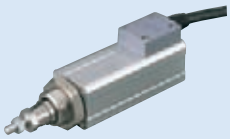
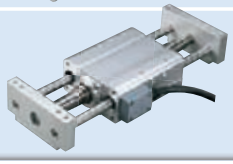
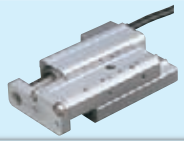
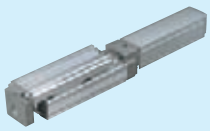
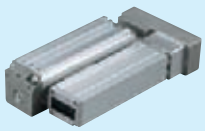
Mini RoboCylinder

RCP3
RCA2
RCL

www.robocylinder.de

Product Overview

Category	Type	Title / External view	Model: Series Name	Model: Actuator width	Model: Type name	Reference Page
Mini Slider type	Motor Unit type	Coupling type 	RCP3	22mm	SA2AC	→P.13
				28mm	SA2BC	→P.15
		Reversing type 	RCP3	58mm	SA2AR	→P.17
				59.5mm	SA2BR	→P.19
Mini Rod type	Without guide / Motor Unit type	Coupling type 	RCP3	22mm	RA2AC	→P.21
				28mm	RA2BC	→P.23
		Reversing type 	RCP3	58mm	RA2AR	→P.25
				59.5mm	RA2BR	→P.27
	Without guide / Short Length type	Fixed Nut type 	RCA2	28mm	RN3N	→P.29
				34mm	RN4N	→P.31
		Tapped Hole type 	RCA2	28mm	RP3N	→P.33
				34mm	RP4N	→P.35
	With guide / Short Length type	Single Guide Free Mount type 	RCA2	28mm	GS3N	→P.37
				34mm	GS4N	→P.39
		Double Guide Free Mount type 	RCA2	28mm	GD3N	→P.41
				34mm	GD4N	→P.43
		Double Guide Slide Unit type 	RCA2	60mm	SD3N	→P.45
				72mm	SD4N	→P.47

Category	Type	Title / External view		Model: Series Name	Model: Actuator width	Model: Type name	Reference Page
Mini Table type	Short Length type	Compact type		RCA2	32mm	TC3N	→P.49
					36mm	TC4N	→P.51
		Wide type		RCA2	50mm	TW3N	→P.53
					58mm	TW4N	→P.55
		Flat type		RCA2	61mm	TF3N	→P.57
					71mm	TF4N	→P.59
	Motor Unit type	Coupling type		RCP3	36mm	TA3C	→P.61
					40mm	TA4C	→P.63
				RCA2	40mm	TA4C	→P.65
		Reversing type		RCP3	72mm	TA3R	→P.67
					81mm	TA4R	→P.69
				RCA2	81mm	TA4R	→P.71
Mini Linear Motor type	Micro Slider	Slim type		RCL	20mm	SA1L	→P.73
					24mm	SA2L	→P.75
					28mm	SA3L	→P.77
		Long Stroke type: Single slider			40mm	SA4L	→P.79
					48mm	SA5L	→P.83
					58mm	SA6L	→P.87
		Long Stroke type: Multi-slider			40mm	SM4L	→P.81
					48mm	SM5L	→P.85
					58mm	SM6L	→P.89
	Micro Cylinder	Slim type		RCL	ø16mm	RA1L	→P.91
					ø20mm	RA2L	→P.93
					ø25mm	RA3L	→P.95
Controller		RCP2/RCP3 3-position Controller		PSEP			→P.101
		RCA/RCA2/RCL 3-position Controller		ASEP			→P.101

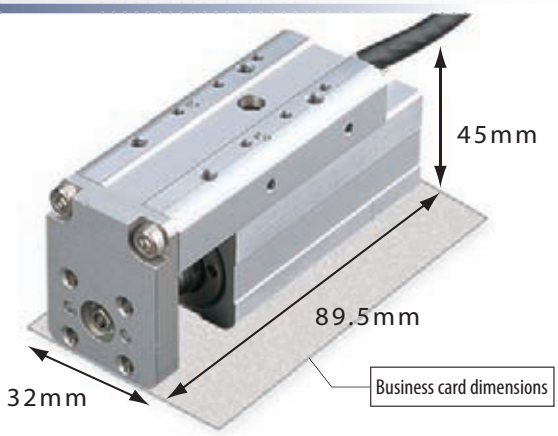
The compact, next-generation electric actuator

Mini RoboCylinder

ROBO CYLINDER

Mini RoboCylinder (space-saving)

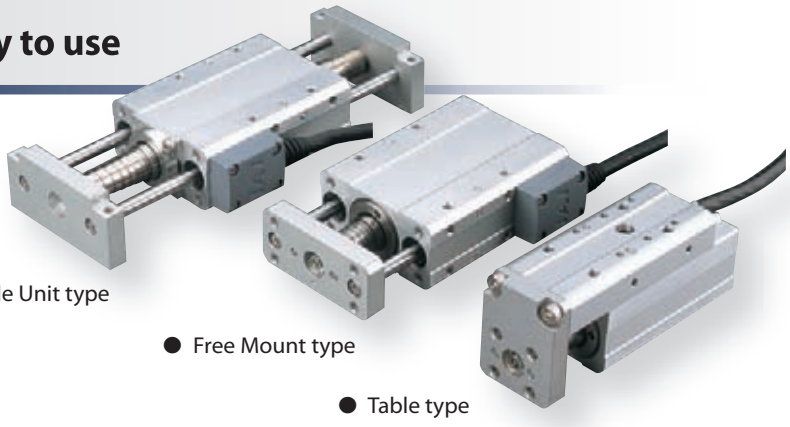
The new Mini RoboCylinder is an achievement in small electromechanical cylinders. It incorporates a newly developed motor, and its significantly reduced length, width and height make it comparable in size to air cylinders.
The Mini RoboCylinder is the perfect replacement for air cylinders in systems that previously could only use air cylinders due to size constraints.



The Mini Table Compact type RCA2-TC3N has dimensions smaller than a business card.

Shaped like an air cylinder and easy to use

The new RoboCylinder is available in shapes similar to air cylinders.
Users accustomed to the operation of pneumatic systems are able to use the new RoboCylinder effortlessly.



- Slide Unit type
- Free Mount type
- Table type

Abundant variations

Choose from such models as the Slider type, Rod type, Table type, and Linear Motor type that best fit your manufacturing needs. (See page on right.)

<List of existing RoboCylinder models and new RoboCylinder models>

		Mini RoboCylinder	Existing Models			
Slider type	Type	Motor unit type	Motor unit type	Coupling type	Coupling type	Coupling type
	Model	SA2AC/SA2BC	SA3C/SA4C/SA5C/SA6C	SA5C/SA6C/SA7C/SS7C/SS8C	SA4C/SA5C/SA6C	SA4C/SA5C/SA6C/SA7C/SS7C/SS8C
	Series	RCP3	RCP3 RCA2	RCP2	RCA	RCS2
	Type	Motor reversing type	Motor reversing type	Motor reversing type	Motor reversing type	Motor reversing type
	Model	SA2AR/SA2BR	SA3R/SA4R/SA5R/SA6R	SA5R/SA6R/SA7R/SS7R/SS8R	SA4R/SA5R/SA6R	SA4R/SA5R/SA6R/SA7R/SS7R/SS8R
	Series	RCP3	RCP3 RCA2	RCP2	RCA	RCS2
Rod type	Type	Coupling type	Coupling type	Coupling type	Full length short type	High thrust type
	Model	RA2AC/RA2BC	RA3C/RA4C/RA6C	RA3C/RA4C/RA5C	SRA7BD	RA10C
	Series	RCP3	RCP2	RCA RCS2	RCS2	RCP2
	Type	Motor reversing type	Motor reversing type	Motor reversing type	Motor reversing short type	Ultra high thrust type
	Model	RA2AR/RA2BR	RA3R/RA4R	RA5R	SRA4R	RA13R
	Series	RCP3	RCA RCS2	RCS2	RCP2 RCA	RCS2
	Type	Single-guide	Single-guide	Single-guide	Single-guide	Short single-guide
	Model	GS3N/GS4N	RGS4C/RGS6C	RGS3C/RGS4C	RGS5C	SRGS4R/SRGS7BD
	Series	RCA2	RCP2 RCS2	RCA RCS2	RCS2	RCP2 RCA RCS2
	Type	Double-guide	Double-guide	Double-guide	Double-guide	Short double-guide
	Model	GD3N/GD4N	RGD4C/RGD6C	RGD3C/RGD4C	RGD5C	SRGD4R/SRGD7BD
	Series	RCA2	RCP2	RCA RCS2	RCS2	RCP2 RCA RCS2
	Type	Slide unit				
	Model	SD3N/SD4N				
	Series	RCA2				
Table type	Type	Motor unit type	Motor unit type			
	Model	TA3C/TA4C	TA5C/TA6C/TA7C			
	Series	RCP3 RCA2	RCP3 RCA2			
	Type	Motor reversing type	Motor reversing type			
	Model	TA3R/TA4R	TA5R/TA6R/TA7R			
	Series	RCP3 RCA2	RCP3 RCA2			
	Type	Compact type	Wide type	Flat type		
	Model	TC3N/TC4N	TW3N/TW4N	TF3N/TF4N		
	Series	RCA2	RCA2	RCA2		
Linear Motor type	Type	Micro cylinder	Micro slider	Micro slider	Micro multi-slider	
	Model	RA1L/RA2L/RA3L	SA1L/SA2L/SA3L	SA4L/SA5L/SA6L	SM4L/SM5L/SM6L	
	Series	RCL	RCL	RCL	RCL	

* The model number means the width of actuators.
The exact dimensions differ according to type.
Please see details in drawings of each type.

Model	Width
2A	22mm
2B	28mm
3	28~36mm
4	34~45mm
5	48~55mm
6	58~64mm
7	71~75mm
8	80mm
10	100mm
13	130mm

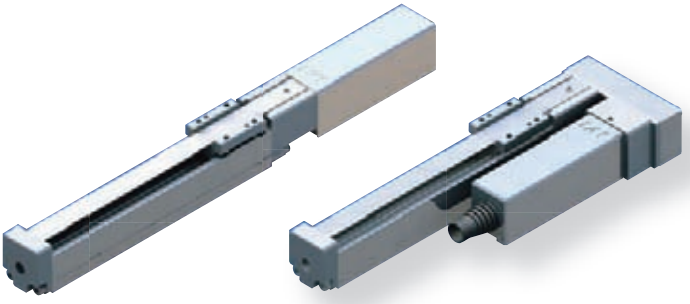
Pulse motor 24 VDC -> RCP2/RCP3 series
Servo motor 24 VDC -> RCA/RCA2 series
Linear motor 24 VDC -> RCL series
Servo motor 230 VAC -> RCS2 series

Mini Slider type

The slider on the main body moves back and forth until it is positioned.

Features
- The motor can easily perform switching operations for the unit model.
- Select from Reversing type with a reduced total length and Slim Straight type (Coupling type).

Usage
Used for jig and workpiece positioning, table travel, etc



Motor Unit Coupling type

Motor Unit Reversing type

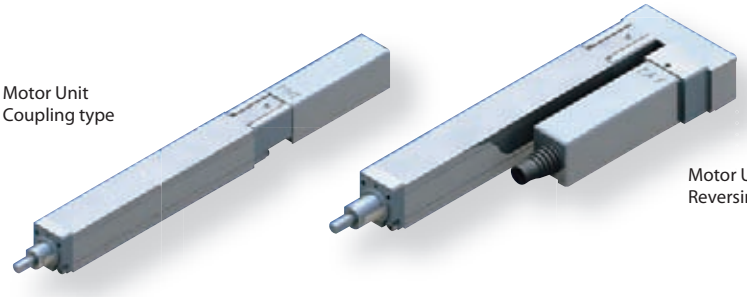
Mini Rod type

The rod extends and retracts from the main body, gets into position and presses.

Features
- Select from Slim Motor Unit types and Short Length types having greatly reduced overall length.
- Select from Guide types with highly rigid/ linear built-in guides and Non-Guide types having drastically miniaturized main body sizes.

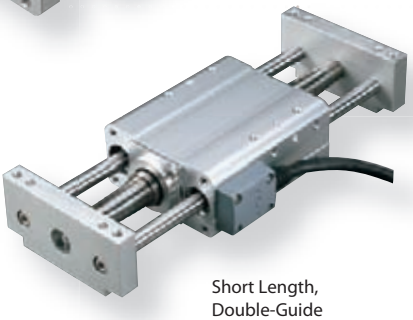
Usage
Used for raising/lowering products and jigs, pushing, clamping, etc.

Short Length, Double-Guide Free Mount type

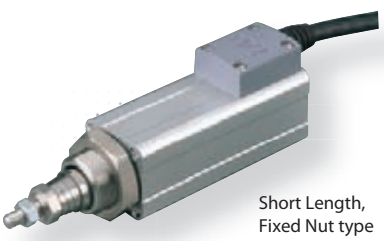


Motor Unit Coupling type

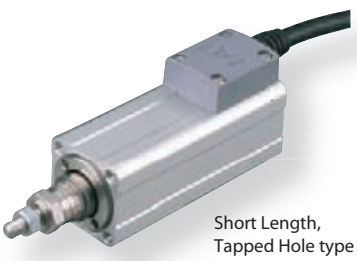
Motor Unit Reversing type



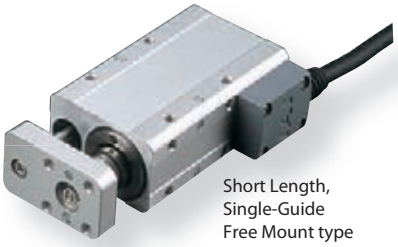
Short Length, Double-Guide Slide Unit type



Short Length, Fixed Nut type



Short Length, Tapped Hole type



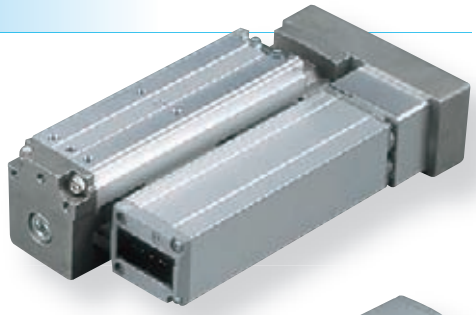
Short Length, Single-Guide Free Mount type

Mini Table type

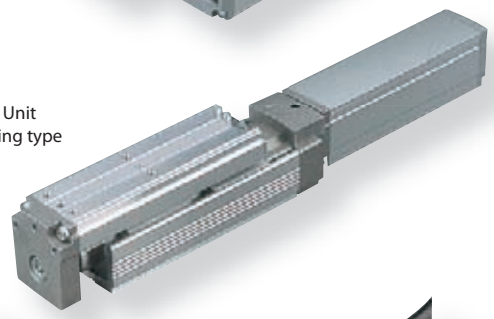
The table on the main body slides until it is positioned.

Features
- Comes equipped with an integrated guide that keeps overhung loads balanced.
- Select from Compact, Short Length types and Long Stroke Motor Unit types.

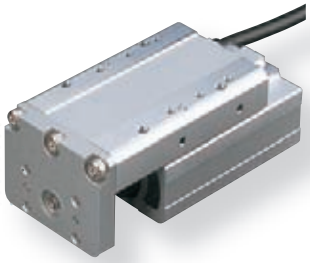
Usage
Used for raising/lowering products and jigs, horizontal moving, and pushing (handles overhung loads from the main unit).



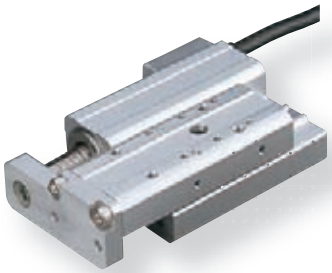
Motor Unit
Reversing type



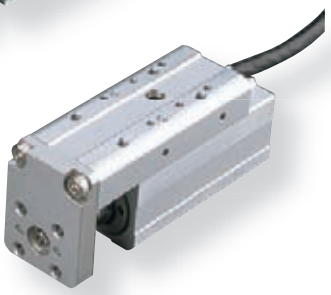
Motor Unit
Coupling type



Short Length
Wide type



Short Length
Flat type



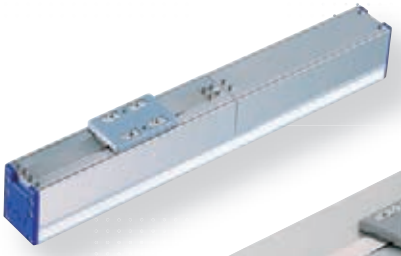
Short Length
Compact type

Mini Linear Motor type

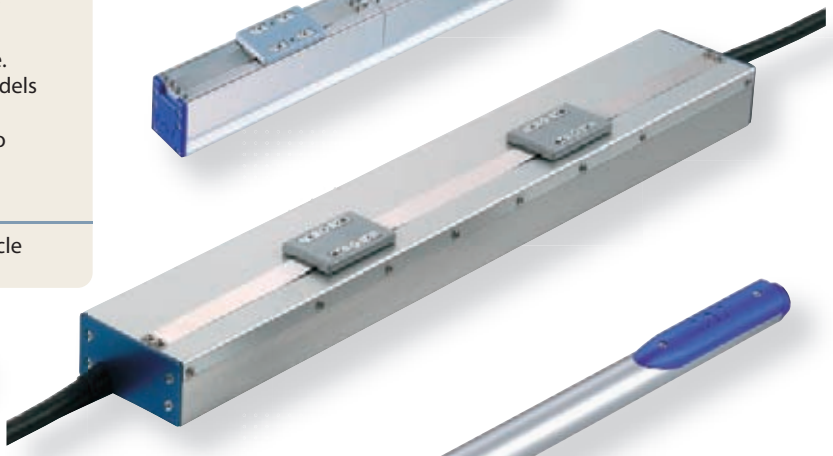
High speed, lightweight parts transfer.

Features
- Equipped with a high acceleration/ deceleration linear motor capable of operation at up to 2G.
- Available in Slider type and Rod type. Slider type comes in six different models for each size and stroke.
- The Multi-slider type comes with two sliders on one axis that can be independently operated.

Usage
Used for transfers requiring short cycle times, etc.



Micro Slider
Slim type



Micro Slider
Long Stroke Type
Multi-slider

Micro Slider
Long Stroke Type
single slider

Micro Cylinder
Slim type

Controller

ROBO CYLINDER

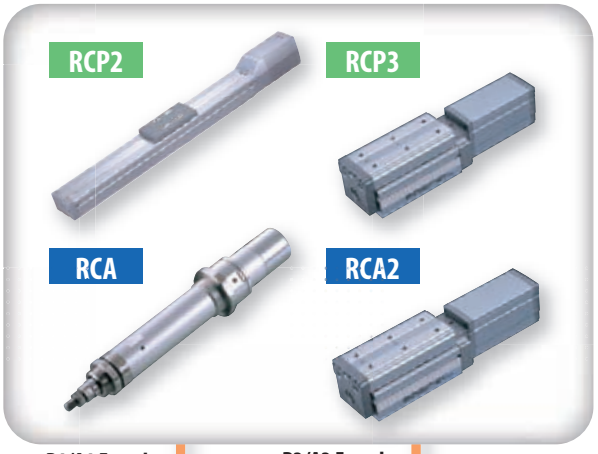
New PSEP/ASEP controllers designed exclusively for 2-point and 3-point positioning

Unlike conventional controllers, the PSEP/ASEP require only a few movement positions. These "**S**imple, **E**asy **P**ositioner" controllers are for applications where the actuator travels only between two or three points, which is usually the case with air cylinders.

If you have been using air cylinders and are unhappy with the long time needed to change movement positions or want to stop actuator movement between two points, you can use the RoboCylinder with PSEP/ASEP controllers. We also have an IP53 rated dustproof type that can be placed near the actuator for operation as is done with solenoid valves.

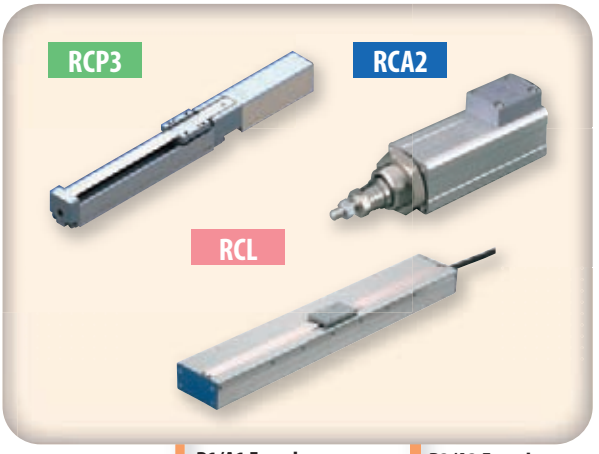
PSEP/ASEP controllers are not just for the new Mini RoboCylinder lineup. They can also be used with existing RoboCylinders. Existing controllers can also be used with the new Robo Mini Cylinders. Please use them according to the application.

Existing models

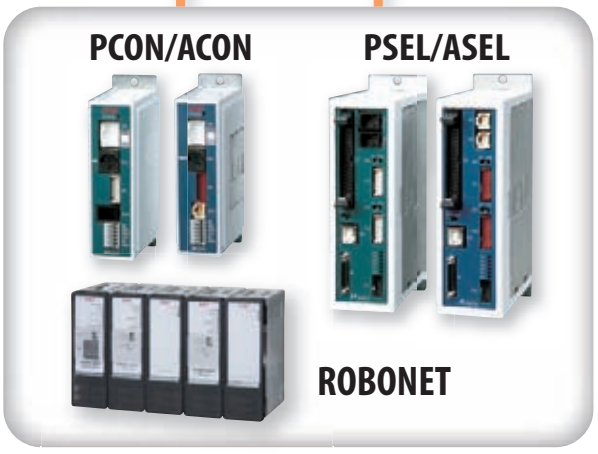


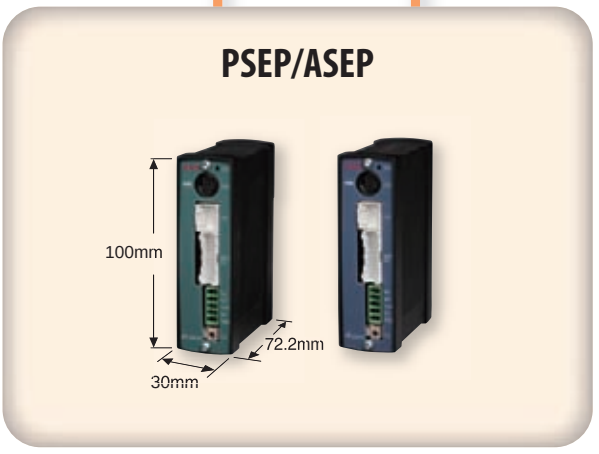
P1/A1 Encoder　P3/A3 Encoder

New Mini RoboCylinder



P1/A1 Encoder　P3/A3 Encoder





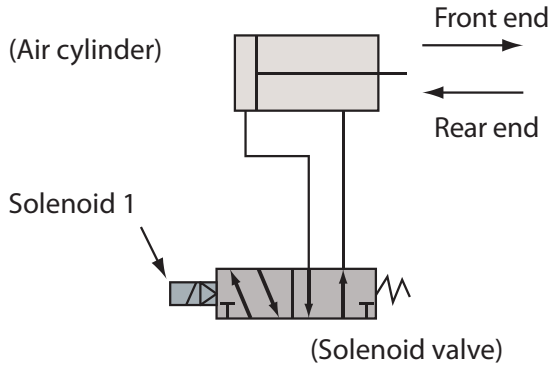
Operates using the same signals used for air cylinder solenoid valves.

PSEP/ASEP operating methods

PSEP/ASEP controllers can be operated with the same signals used for air cylinder solenoid valves.
Solenoid valves come in two types: Single solenoids and Double solenoids. The PSEP/ASEP supports signals for both.

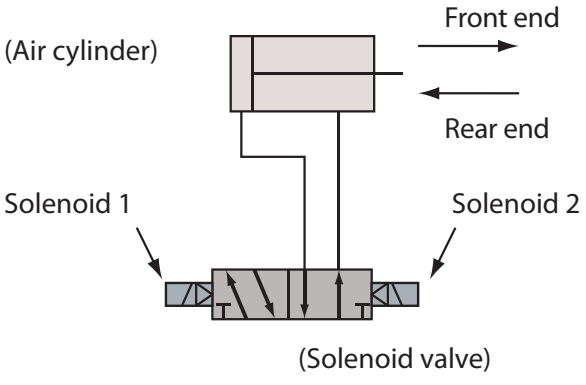
■ When using an air cylinder solenoid valve:

<Single solenoid>



Signal to solenoid 1	Rod movement
ON	Front end
OFF	Rear end

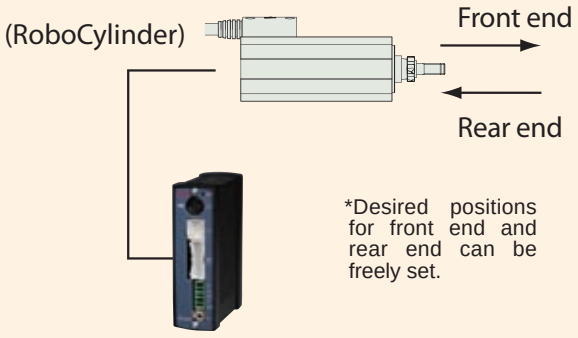
<Double solenoid>



Signal to solenoid 1	Signal to solenoid 2	Rod movement
ON	OFF	Front end
OFF	ON	Rear end

■ PSEP/ASEP:

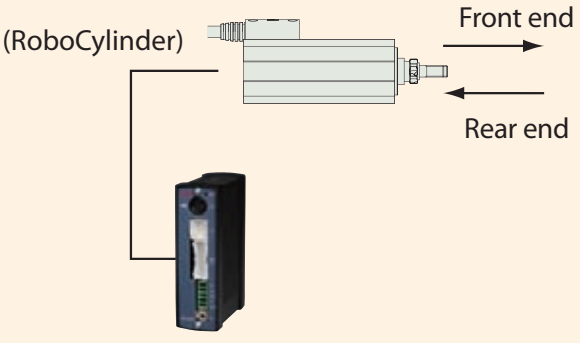
<Replacement of single solenoid>



*Desired positions for front end and rear end can be freely set.

Signal to controller Input 0	Rod movement
ON	Front end
OFF	Rear end

<Replacement of double solenoid>



Signal to controller Input 1	Signal to controller Input 0	Rod movement
ON	OFF	Front end
OFF	ON	Rear end

* The main body moves between the same two points listed above, but it can also travel between three points by switching the parameters.

Mini RoboCylinder Specification Table

Mini Slider Type

Motor Unit	Type Description	Model Series	Model Type	Encoder Type	Motor Type	Motor Size	Feed Screw	Lead (mm)	Rated Thrust (N)	Max. Load Capacity (kg) Horizontal	Max. Load Capacity (kg) Vertical	Max. Speed (mm/s)	Stroke (mm)	Repeat-ability (mm)	Reference Page
Separate Motor (Removable)	Tiny Coupling Slider Type 	RCP3	SA2AC	Incremental	Pulse Motor	20□	Lead Screw	4	—	0.25	—	200	25~100 (25-mm steps)	±0.05	P.13
								2	—	0.5	—	100			
								1	—	1	—	50			
			SA2BC					6	—	0.25	—	300	25~150 (25-mm steps)		P.15
								4	—	0.5	—	200			
								2	—	1	—	100			
	Tiny Motor-reversing Slider Type 	RCP3	SA2AR					4	—	0.25	—	200	25~100 (25-mm steps)		P.17
								2	—	0.5	—	100			
								1	—	1	—	50			
			SA2BR					6	—	0.25	—	300	25~150 (25-mm steps)		P.19
								4	—	0.5	—	200			
								2	—	1	—	100			

Mini Rod Type

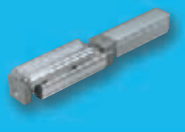
Motor Unit	Type Description	Model Series	Model Type	Encoder Type	Motor Type	Motor Size	Feed Screw	Lead (mm)	Rated Thrust (N)	Max. Load Capacity (kg) Horizontal	Max. Load Capacity (kg) Vertical	Max. Speed (mm/s)	Stroke (mm)	Repeat-ability (mm)	Reference Page
Separate Motor (Removable)	Tiny Coupling Rod Type 	RCP3	RA2AC	Incremental	Pulse Motor	20□	Lead Screw	4	—	0.25	0.125	200	25~100 (25-mm steps)	±0.05	P.21
								2	—	0.5	0.25	100			
								1	—	1	0.5	50			
			RA2BC					6	—	0.25	0.125	300	25~150 (25-mm steps)		P.23
								4	—	0.5	0.25	200			
								2	—	1	0.5	100			
	Tiny Motor-reversing Rod Type 	RCP3	RA2AR					4	—	0.25	0.125	200	25~100 (25-mm steps)		P.25
								2	—	0.5	0.25	100			
								1	—	1	0.5	50			
			RA2BR					6	—	0.25	0.125	300	25~150 (25-mm steps)		P.27
								4	—	0.5	0.25	200			
								2	—	1	0.5	100			
Built-in Motor (Direct-coupled)	Short Fixed Nut Rod Type 	RCA2	RN3N		Servo Motor	10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.29
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			RN4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.31
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Tapped Hole Rod Type 	RCA2	RP3N			10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.33
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			RP4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.35
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Free Mount Rod Type with Single-Guide 	RCA2	GS3N			10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.37
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			GS4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.39
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Free Mount Rod Type with Double-Guide 	RCA2	GD3N			10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.41
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			GD4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.43
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Slide Unit Rod Type with Double-Guide 	RCA2	SD3N			10W	Lead Screw	4	25.1	0.25	0.125	200	25 50	±0.05	P.45
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			SD4N			20W	Lead Screw	6	19.9	0.25	0.125	300	25 50 75	±0.05	P.47
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	300		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			

* < > : Max. speed of vertical application

■ Skillful use of "Lead Screw" type

(1) Lead screws are suitable for uses with infrequent operations. (As a guide, this would be approximately 5 years, for 1 operation every 10 seconds, 24-hour use, 240 days a year.)
(2) Lead screws are suitable for uses with small payloads, light loads. (1kg or less)
(3) Use when repeated positioning accuracy of less than ±0.05mm is needed.
(4) Please set up in a location where maintenance will be easy.

Mini Table Type

Motor Unit	Type Description	Model Series	Model Type	Encoder Type	Motor Type	Motor Size	Feed Screw	Lead (mm)	Rated Thrust (N)	Max. Load Capacity (kg) Horizontal	Max. Load Capacity (kg) Vertical	Max. Speed (mm/s)	Stroke (mm)	Repeat-ability (mm)	Reference Page
Built-in Motor (Direct-coupled)	Short Compact Table Type 	RCA2	TC3N	Incremental	Servo Motor	10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.49
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			TC4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.51
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Wide Table Type 	RCA2	TW3N			10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.53
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			TW4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.55
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
	Short Flat Table Type 	RCA2	TF3N			10W	Lead Screw	4	25.1	0.25	0.125	200	30	±0.05	P.57
								2	50.3	0.5	0.25	100			
								1	100.5	1.0	0.5	50			
			TF4N			20W	Lead Screw	6	19.9	0.25	0.125	220	30	±0.05	P.59
								4	29.8	0.5	0.25	200			
								2	59.7	1.0	0.5	100			
							Ball Screw	6	33.8	2	0.5	270〈220〉		±0.02	
								4	50.7	3	0.75	200			
								2	101.5	6	1.5	100			
Separate Motor (Removable)	Coupling Table Type 	RCP3	TA3C		Pulse Motor	20□	Ball Screw	6	-	~0.7	~0.3	300〈200〉	20~100 (10-mm steps)	±0.02	P.61
								4	-	~1.4	~0.6	200〈133〉			
								2	-	~2	~1	100〈67〉			
			TA4C			28□		6	-	~1	~0.5	300			P.63
								4	-	~2	~1	200			
								2	-	~3	~1.5	100			
		RCA2	TA4C		Servo Motor	10W		6	28	1	0.5	300			P.65
								4	43	2	1	200			
								2	85	3	1.5	100			
	Motor-reversing TableType 	RCP3	TA3R		Pulse Motor	20□	Ball Screw	6	-	~0.7	~0.3	300〈200〉			P.67
								4	-	~1.4	~0.6	200〈133〉			
								2	-	~2	~1	100〈67〉			
			TA4R			28□		6	-	~1	~0.5	300			P.69
								4	-	~2	~1	200			
								2	-	~3	~1.5	100			
		RCA2	TA4R		Servo Motor	10W		6	28	1	0.5	300			P.71
								4	43	2	1	200			
								2	85	3	1.5	100			

Mini Linear Motor Type

Motor Unit	Type Description	Model Series	Model Type	Encoder Type	Motor Type	Motor Size	Feed Screw	Lead (mm)	Rated Thrust (N)	Max. Load Capacity (kg) Horizontal	Max. Load Capacity (kg) Vertical	Max. Speed (mm/s)	Stroke (mm)	Repeat-ability (mm)	Reference Page
Combined Motor-to-Body System (Micro Slider)	Slim Linear Motor Slider Type 	RCL	SA1L	Incremental	Linear Motor	2W	-	-	2	0.5	-	420	40	±0.1	P.73
			SA2L			5W		-	4	1	-	460	48		P.75
			SA3L			10W		-	8	2	-	600	64		P.77
	Long-stroke Linear Motor Slider Type 		SA4L			2W		-	2.5	0.8	-	1200	30~180		P.79
			SM4L					-					30~120		P.81
			SA5L			5W		-	5	1.6	-	1400	36~216		P.83
			SM5L					-					36~144		P.85
			SA6L			10W		-	10	3.2	-	1600	48~288		P.87
			SM6L					-					48~192		P.89
Combined Motor-to-Body System (Micro Cylinder)	Slim Linear Motor Rod Type 	RCL	RA1L			2W		-	2.5	0.5	0.1	300	25		P.91
			RA2L			5W		-	5	1	0.2	340	30		P.93
			RA3L			10W		-	10	2	0.4	450	40		P.95

* < > : Max. speed of vertical application

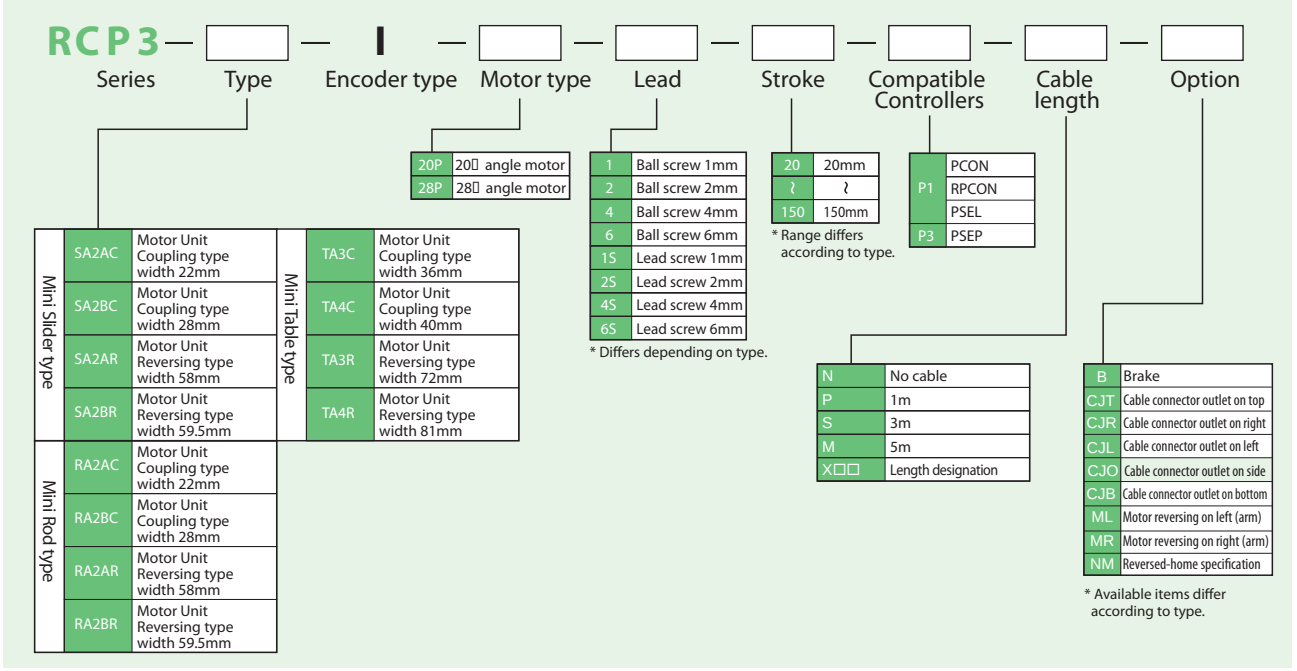
Model Descriptions

Models for each RoboCylinder series are designated by the items below.
See the explanations below for information on each item. The range of selections for each item (lead, stroke, etc.) varies by type, so refer to the page for each type for more information.

Explanation of Items

Series	–	Type	–	Encoder type	–	Motor type	–	Lead	–	Stroke	–	Compatible Controllers	–	Cable length	–	Option
①		②		③		④		⑤		⑥		⑦		⑧		⑨

① Series	This indicates the name of each series.
② Type	This indicates the shape (slider, rod, etc.), size (width 22mm, etc.) and motor connection method, etc.
③ Encoder type	This indicates whether the encoder installed in the actuator is an “absolute type” or an “incremental” type. * If the controller for the Simple Absolute Unit PCON-/ACON-ABU is used, use actuator encoder type “I” (incremental specification).
④ Motor type	This shows the wattage of the motor installed in the actuator. Since the RCP3 Series uses a pulse motor, the motor size (20P=20□ motor) is shown instead of the wattage.
⑤ Lead	This shows a feed screw lead (distance slider moves per revolution of ball screw). Ball screws are shown in numerals only. Lead screws have an S after the number.
⑥ Stroke	This indicates the stroke for the actuator (operating range). (Units in mm)
⑦ Compatible Controllers	This indicates the controller types that can be connected. (The motor encoder cable changes according to type of controller.)
⑧ Cable length	This indicates the length of the motor-encoder cable connecting the actuator and controller.
⑨ Option	This indicates options that can be installed on the actuator. * If multiple options are selected, specify them in alphabetical order. (Example: 3-B-ML)



RCA2 — □ — I — □ — □ — □ — □ — □ — □

Series | Type | Encoder type | Motor type | Lead | Stroke | Compatible Controllers | Cable length | Option

Type

Mini Rod type

RN3N	Short Length, Fixed Nut type width 28mm
RN4N	Short Length, Fixed Nut type width 34mm
RP3N	Short Length, Fixed Nut type width 28mm
RP4N	Short Length, Fixed Nut type width 34mm
GS3N	Short Length, Single-Guide Free Mount type width 28mm
GS4N	Short Length, Single-Guide Free Mount type width 34mm
GD3N	Short Length, Double-Guide Free Mount type width 28mm
GD4N	Short Length, Double-Guide Free Mount type width 34mm
SD3N	Short Length, Double-Guide Slide Unit type width 60mm
SD4N	Short Length, Double-Guide Slide Unit type width 72mm

Mini Table type

TC3N	Short Length, Compact type width 32mm
TC4N	Short Length, Compact type width 36mm
TW3N	Short Length, Wide type width 50mm
TW4N	Short Length, Wide type width 58mm
TF3N	Short Length, Flat type width 61mm
TF4N	Short Length, Flat type width 71mm
TA4C	Motor Unit Coupling type width 40mm
TA4R	Motor Unit Reversing type width 81mm

Encoder type

10	10W
20	20W

Motor type

Lead

1	Ball screw 1mm
2	Ball screw 2mm
4	Ball screw 4mm
6	Ball screw 6mm
1S	Lead screw 1mm
2S	Lead screw 2mm
4S	Lead screw 4mm
6S	Lead screw 6mm

* Differs depending on type.

Stroke

20	20mm
≀	≀
100	100mm

* Range differs according to type.

Compatible Controllers

A1	ACON
	RACON
	ASEL
A3	ASEP

Cable length

N	No cable
P	1m
S	3m
M	5m
X□□	Length designation

Option

K2	Change direction for connector cable exit
B	Brake
CJT	Cable connector outlet on top
CJR	Cable connector outlet on right
CJL	Cable connector outlet on left
CJO	Cable connector outlet on side
CJB	Cable connector outlet on bottom
LA	Power-saving feature
ML	Motor reversing on left (arm)
MR	Motor reversing on right (arm)
NM	Reversed-home specification

* Available items differ according to type.

RCL — □ — I — □ — N — □ — □ — □ — □

Series | Type | Encoder type | Corresponding driver output | Lead (none) | Stroke | Compatible Controllers | Cable length | Option

Type

Micro Slider

SA1L	Slim type width 20mm single slider spec.
SA2L	Slim type width 24mm single slider spec.
SA3L	Slim type width 28mm single slider spec.
SA4L	Long Stroke type width 40mm single slider spec.
SA5L	Long Stroke type width 48mm single slider spec.
SA6L	Long Stroke type width 58mm single slider spec.
SM4L	Long Stroke type width 40mm Multi-slider spec.
SM5L	Long Stroke type width 48mm Multi-slider spec.
SM6L	Long Stroke type width 58mm Multi-slider spec.

Micro Cylinder

RA1L	Slim type φ16mm
RA2L	Slim type φ20mm
RA3L	Slim type φ25mm

Corresponding driver output

2	2W
5	5W
10	10W

Lead (none)

Stroke

25	25mm
≀	≀
288	288mm

* Range differs according to type.

Compatible Controllers

A1	ACON
	RACON
	ASEL
A3	ASEP

Cable length

N	No cable
P	1m
S	3m
M	5m
X□□	Length designation

Option

B	Brake
BN	Brake w/o brake box
NM	Reversed-home spec.

* Available items differ according to type.

Notes on selection

■ Skillful use of "Lead Screw" type

(1) Lead screws are suitable for uses with infrequent operations. (As a guide, this would be approximately 5 years, for 1 operation every 10 seconds, 24-hour use, 240 days a year.)
(2) Lead screws are suitable for uses with small payloads, light loads. (1kg or less)
(3) Use when repeated positioning accuracy of less than ±0.05mm is needed.
(4) Please set up in a location where maintenance will be easy.

RCP3-SA2AC

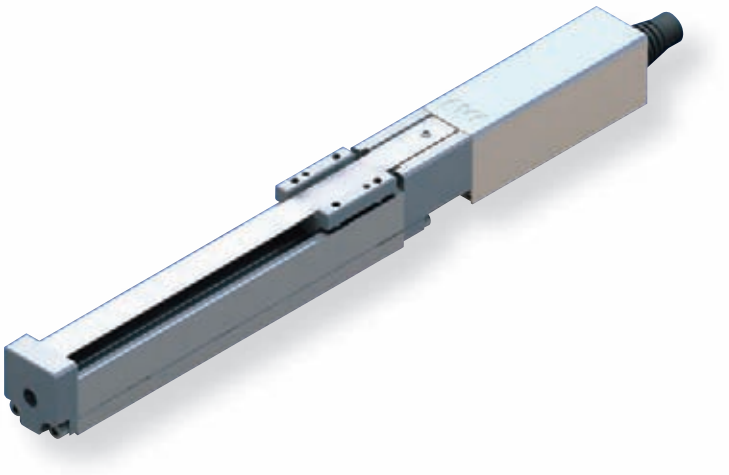
RoboCylinder Mini Slider Type Motor Unit Coupling Type Actuator Width 22mm Pulse Motor Lead Screw Specification

■Model Description

RCP3 – SA2AC – I – 20P – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

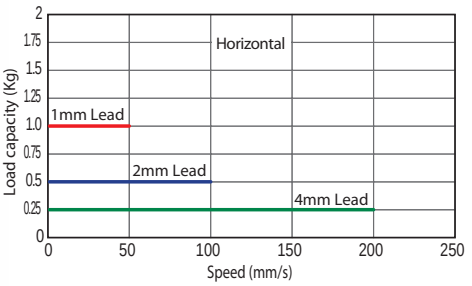
Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
RCP3	SA2AC	I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□ Size	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	25: 25mm ~ 100: 100mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
The acceleration upper limit is the value indicated above.

(2) Cannot be used in the horizontal orientation with the slider facing to the side or in the vertical orientation.

(3) Service life decreases significantly if used in a dusty environment.

Actuator Specification Table

■Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-SA2AC-I-20P-4S-①-②-③-④	Lead screw	4	0.25	–	±0.05	25 to 100 (every 25mm)
RCP3-SA2AC-I-20P-2S-①-②-③-④		2	0.5	–		
RCP3-SA2AC-I-20P-1S-①-②-③-④		1	1	–		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 to 100 (mm)
Lead screw 4	180	200
Lead screw 2	100	
Lead screw 1	50	

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **20** (20m)	

* The standard cable for the RCP3 is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

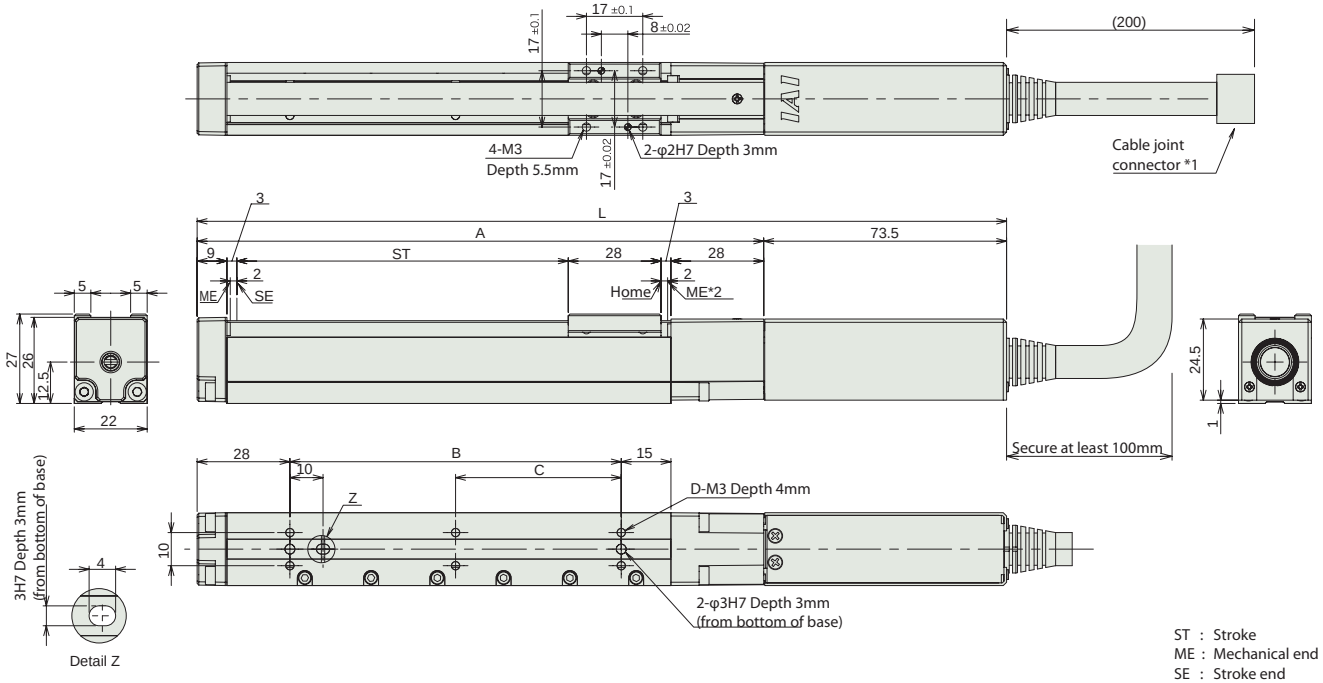
Title	Option code	See page	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

Stroke	25	50	75	100
L	169.5	194.5	219.5	244.5
A	96	121	146	171
B	25	50	75	100
C	0	0	0	50
D	4	4	4	6
Mass (kg)	0.25	0.27	0.29	0.3

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points of positioning possible Simple absolute unit (sold separately) By attaching, the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to the home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-SA2BC

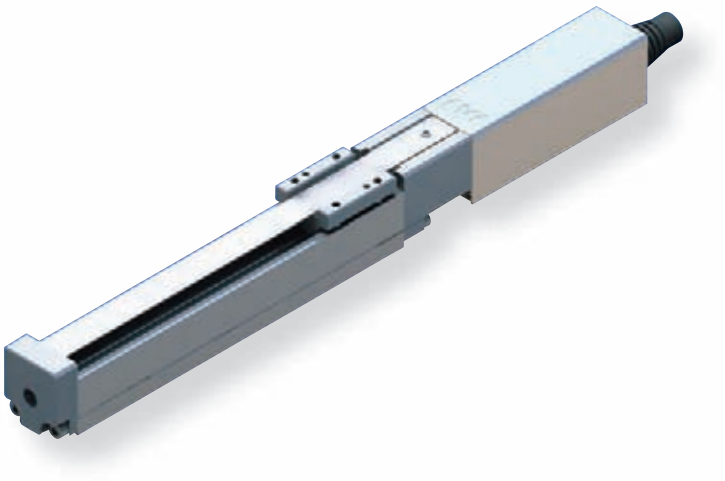
RoboCylinder Mini Slider Type Motor Unit Coupling Type Actuator Width 28mm Pulse Motor Lead Screw Specification

■Model Description

RCP3 – SA2BC – I – 20P – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

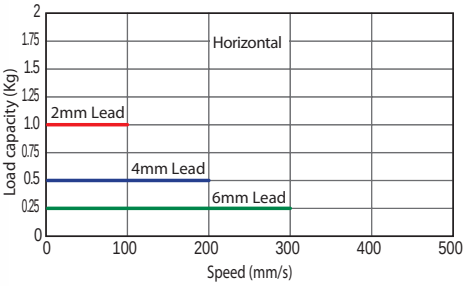
Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□Size	6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	25: 25mm ~ 150: 150mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
The acceleration upper limit is the value indicated above.

(2) Cannot be used in the horizontal orientation with the slider facing to the side or in the vertical orientation.

(3) Service life decreases significantly if used in a dusty environment.

Actuator Specification Table

■Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload		Positioning Repeatability (mm)	Stroke (mm)
			Horizontal (kg)	Vertical (kg)		
RCP3-SA2BC-I-20P-6S-①-②-③-④	Lead screw	6	0.25	–	±0.05	25 to 150 (every 25mm)
RCP3-SA2BC-I-20P-4S-①-②-③-④		4	0.5	–		
RCP3-SA2BC-I-20P-2S-①-②-③-④		2	1	–		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 (mm)	75 to 150 (mm)
Lead screw 6	180	280	300
Lead screw 4	180	200	
Lead screw 2	100		

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCP3 is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ6mm, rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

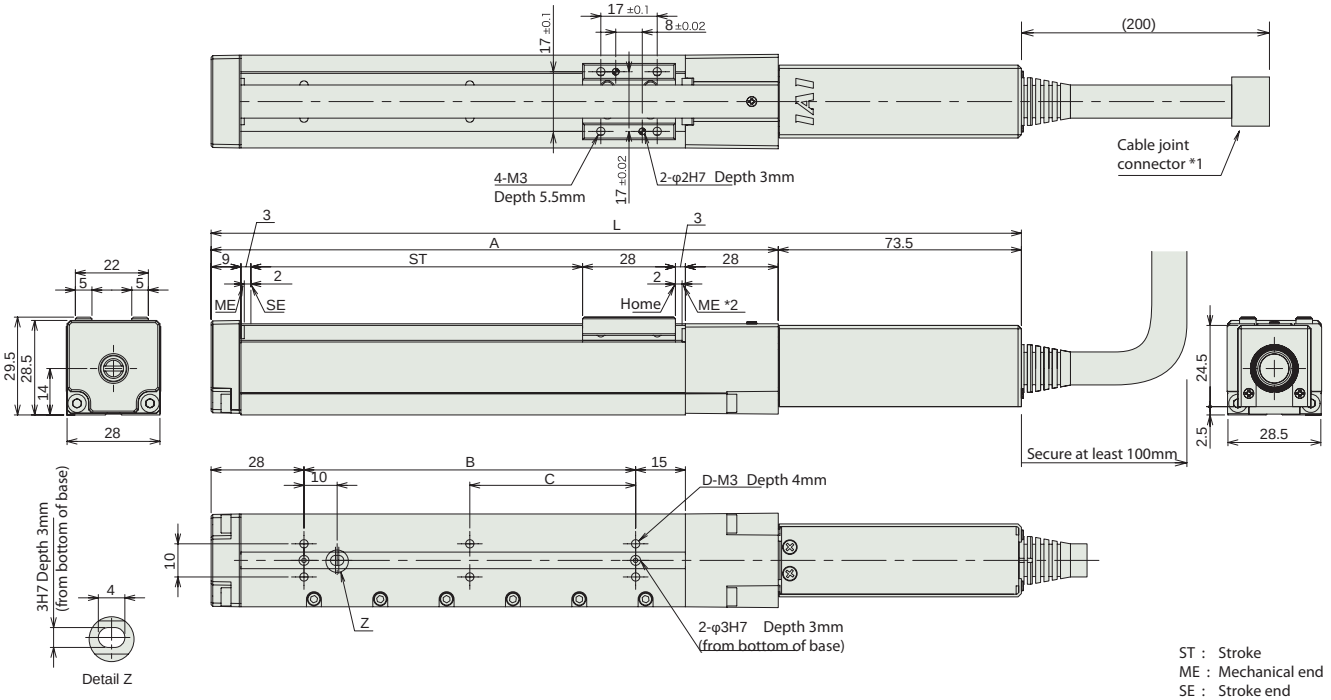
Title	Option code	See page	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

Stroke	25	50	75	100	125	150
L	169.5	194.5	219.5	244.5	269.5	294.5
A	96	121	146	171	196	221
B	25	50	75	100	125	150
C	0	0	0	50	62.5	75
D	4	4	4	6	6	6
Mass (kg)	0.3	0.32	0.35	0.37	0.4	0.42

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points of positioning possible Simple absolute unit (sold separately) By attaching, the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to the home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-SA2AR

RoboCylinder Mini Slider Type Motor Unit Reverse-mounted Type Actuator Width 58mm Pulse Motor Lead Screw Specification

■Model Description

RCP3 – SA2AR – I – 20P – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□Size	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	25: 25mm ↕ 100: 150mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

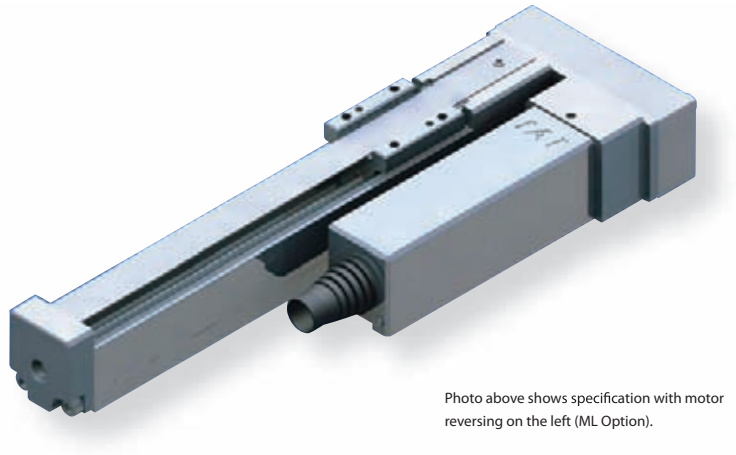
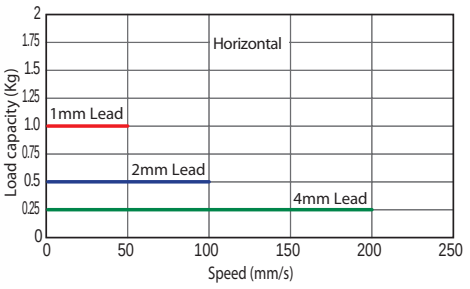


Photo above shows specification with motor reversing on the left (ML Option).

■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
The acceleration upper limit is the value indicated above.
(2) Cannot be used in the horizontal orientation with the slider facing to the side or in the vertical orientation.
(3) Service life decreases significantly if used in a dusty environment.

Actuator Specification Table

■Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-SA2AR-I-20P-4S-①-②-③-④	Lead screw	4	0.25	–	±0.05	25 to 100 (every 25mm)
RCP3-SA2AR-I-20P-2S-①-②-③-④		2	0.5	–		
RCP3-SA2AR-I-20P-1S-①-②-③-④		1	1	–		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 to 100 (mm)
Lead screw 4	180	200
Lead screw 2	100	
Lead screw 1	50	

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCP3 is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

Title	Option code	See page	
Specification with motor reversing on the left	**ML**	–	
Specification with motor reversing on the right	**MR**	–	
Reversed-home specification	**NM**	–	

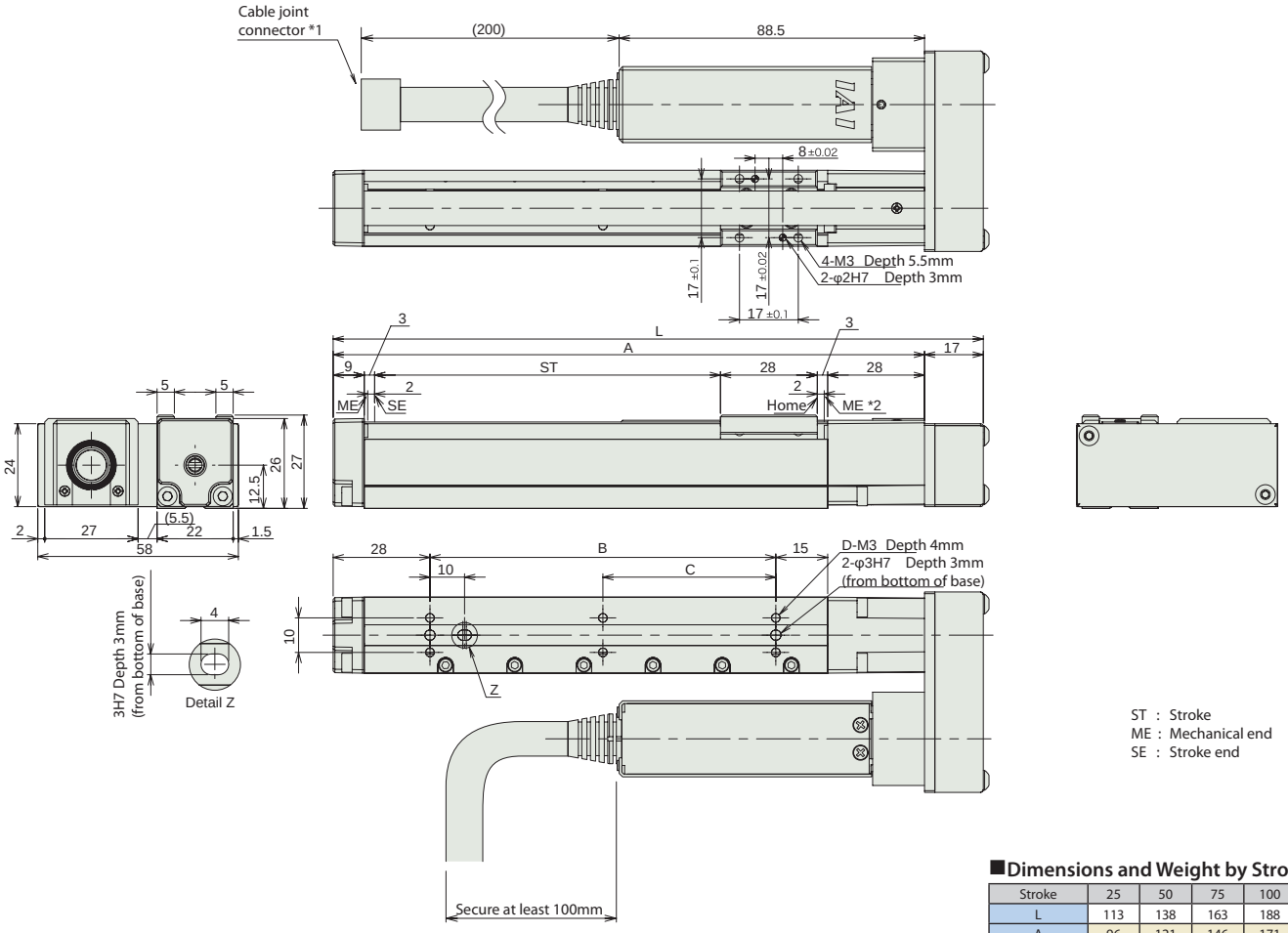
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*The drawing below shows the right reverse-mounted motor specification.

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

Stroke	25	50	75	100
L	113	138	163	188
A	96	121	146	171
B	25	50	75	100
C	0	0	0	50
D	4	4	4	6
Mass (kg)	0.28	0.3	0.32	0.33

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points of positioning possible Simple absolute unit (sold separately) By attaching, the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to the home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-SA2BR

RoboCylinder Mini Slider Type Motor Unit Reverse-mounted Type Actuator Width 59.5mm Pulse Motor Lead Screw Specification

■Model Description

RCP3 – SA2BR – I – 20P – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□Size	65: Lead screw 4mm 45: Lead screw 2mm 25: Lead screw 1mm	25: 25mm ↕ 100: 150mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

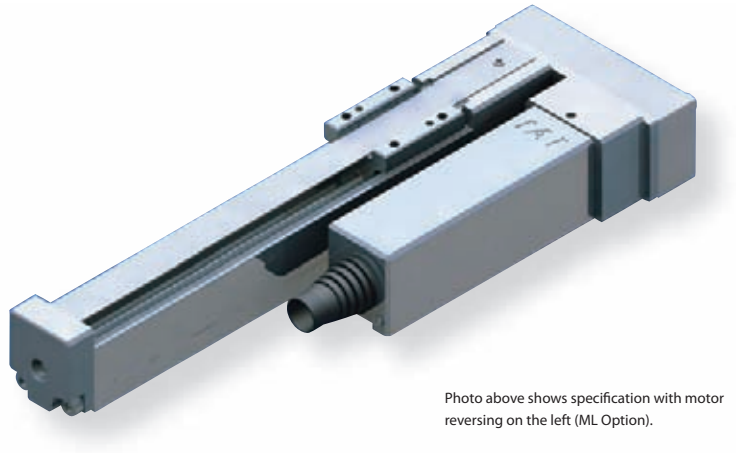
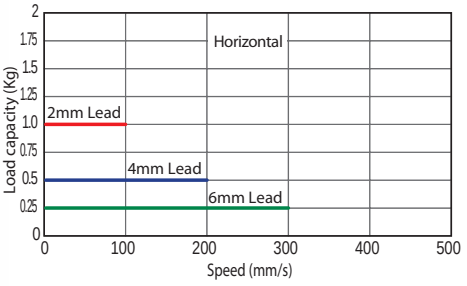


Photo above shows specification with motor reversing on the left (ML Option).

■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
The acceleration upper limit is the value indicated above.

(2) Cannot be used in the horizontal orientation with the slider facing to the side or in the vertical orientation.

(3) Service life decreases significantly if used in a dusty environment.

Actuator Specification Table

■Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload		Positioning Repeatability (mm)	Stroke (mm)
			Horizontal (kg)	Vertical (kg)		
RCP3-SA2BR-I-20P-6S-①-②-③-④	Lead screw	6	0.25	–	±0.05	25 to 150 (every 25mm)
RCP3-SA2BR-I-20P-4S-①-②-③-④		4	0.5	–		
RCP3-SA2BR-I-20P-2S-①-②-③-④		2	1	–		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 (mm)	75 to 150 (mm)
Lead screw 6	180	280	300
Lead screw 4	180	200	
Lead screw 2	100		

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCP3 is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ6mm, rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

Title	Option code	See page	
Specification with motor reversing on the left	**ML**	–	
Specification with motor reversing on the right	**MR**	–	
Reversed-home specification	**NM**	–	

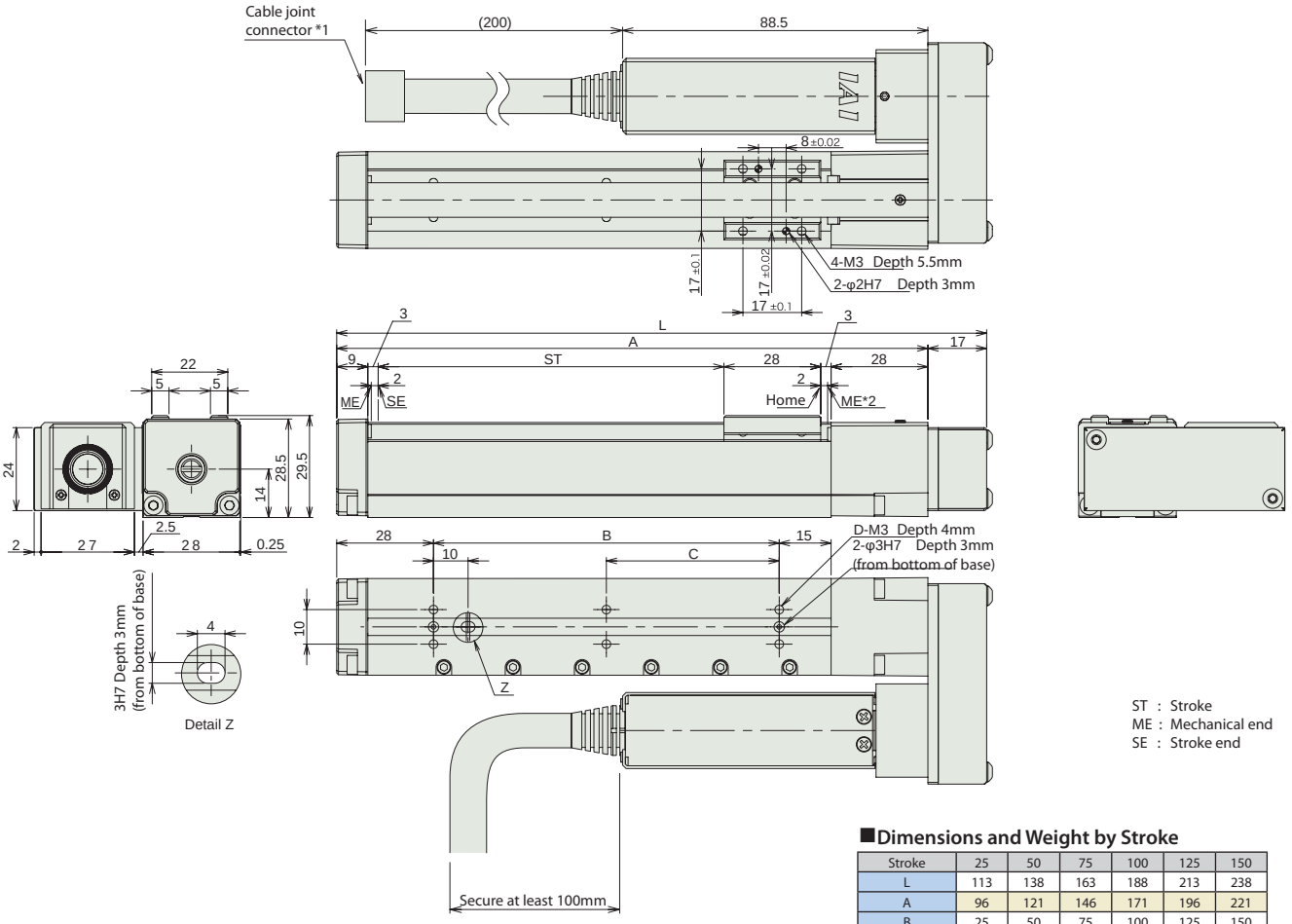
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*The drawing below shows the right reverse-mounted motor specification (MR option).

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

Stroke	25	50	75	100	125	150
L	113	138	163	188	213	238
A	96	121	146	171	196	221
B	25	50	75	100	125	150
C	0	0	0	50	62.5	75
D	4	4	4	6	6	6
Mass (kg)	0.32	0.34	0.37	0.39	0.42	0.46

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points of positioning possible Simple absolute unit (sold separately) By attaching, the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to the home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-RA2AC

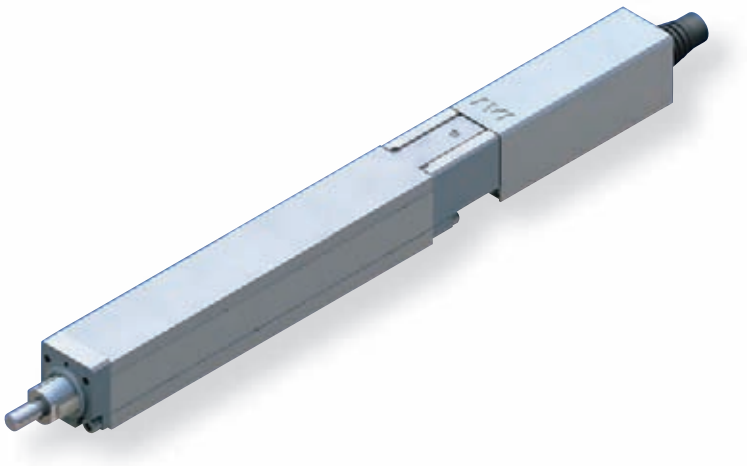
RoboCylinder Mini Rod type Motor Unit Coupling type Actuator Width 22mm Pulse Motor Lead Screw Specification

Model Description

RCP3 – RA2AC – I – 20P – □ – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□Size	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	25: 25 mm ↕ 100: 100 mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

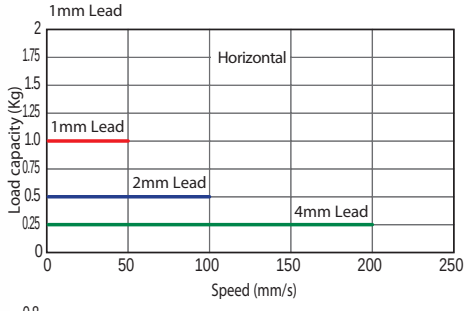


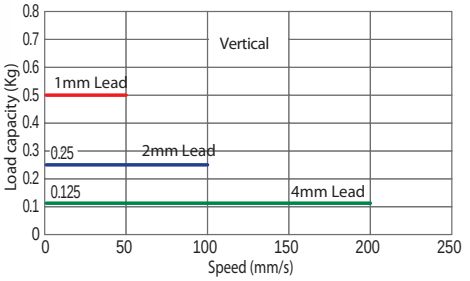
POINT Notes on selection

(1) The load capacity is the value when operated at 0.2G acceleration. The acceleration limit is the value indicated above.
(2) The horizontal payload is the value when used in combination with an external guide. Please note that if an external force is applied to the rod in a direction other than the proper direction the rod travels, the detent may get damaged.
(3) The maximum pushing force when the speed is 5mm/s.
(4) Service life decreases significantly if used in a dusty environment.

Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Maximum pushing force (N)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-RA2AC-I-20P-4S-①-②-③-④	Lead Screw	4	0.25	0.125	See page 97.	±0.05	25 to 100
RCP3-RA2AC-I-20P-2S-①-②-③-④		2	0.5	0.25			
RCP3-RA2AC-I-20P-1S-①-②-③-④		1	1	0.5			

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 to 100 (mm)
Lead screw 4	180	200
Lead screw 2	100	
Lead screw 1	50	

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot cable type comes standard on RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw φ4mm rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide Guide
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal: 10 million (number of cycles) Vertical: 5 million (number of cycles)

Options

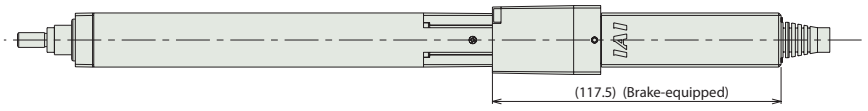
Title	Option code	See page	
Brake	**B**	→P22	
Reversed - home specification	**NM**	–	

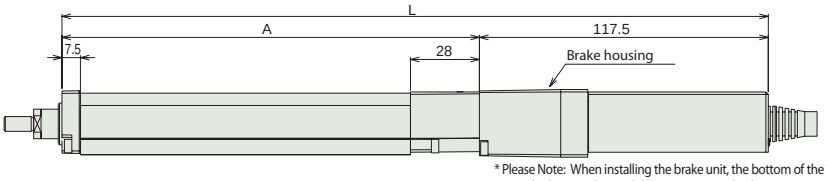
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

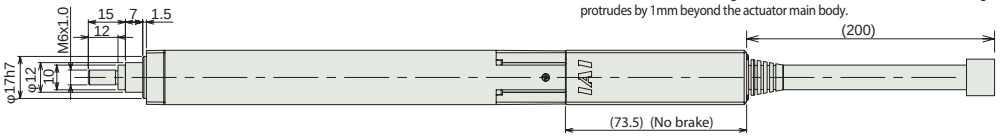
(Brake-equipped)

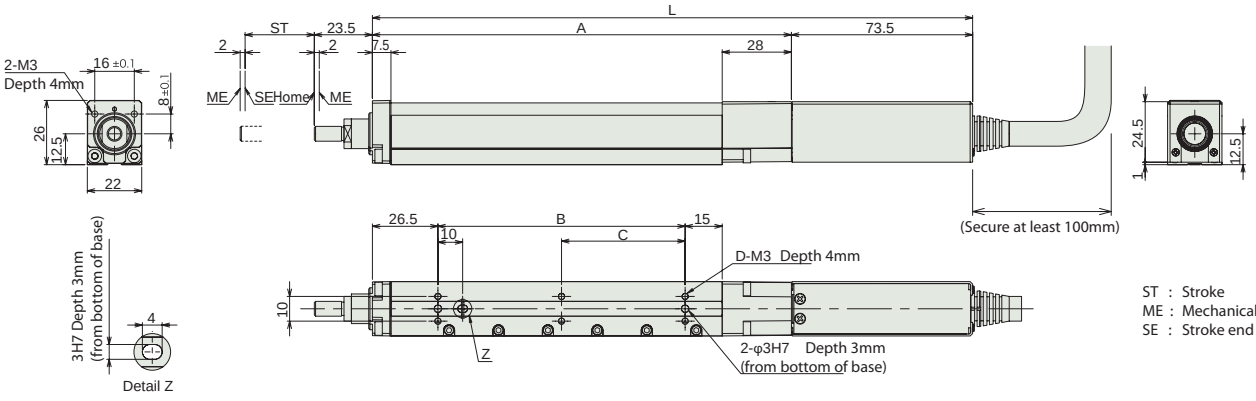




* Please Note: When installing the brake unit, the bottom of the brake housing protrudes by 1mm beyond the actuator main body.

(No brake)





ST : Stroke
ME : Mechanical end
SE : Stroke end

* Brake equipped models are 0.1kg heavier.

Dimensions and Weight by Stroke

Stroke		25	50	75	100
L	No brake	168	193	218	243
	Brake-equipped	212	237	262	287
A		94.5	119.5	144.5	169.5
B		25	50	75	100
C		0	0	0	50
D		4	4	4	6
Mass (kg)		0.27	0.29	0.31	0.33

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-RA2BC

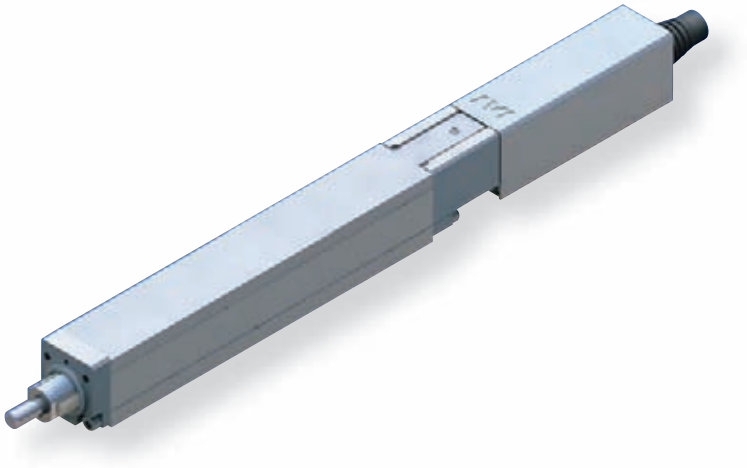
RoboCylinder Mini Rod type Motor Unit Coupling type Actuator Width 28mm Pulse Motor Lead Screw Specification

Model Description

RCP3 – RA2BC – I – 20P – □ – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20 □Size	6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	25: 25 mm ↓ 150: 150 mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

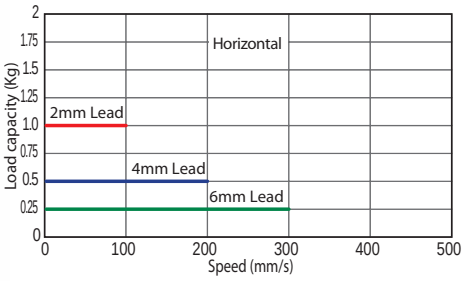


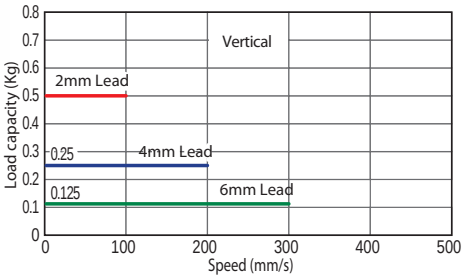
POINT Notes on selection

(1) The load capacity is the value when operated at 0.2G acceleration. The acceleration limit is the value indicated above.
(2) The horizontal payload is the value when used in combination with an external guide. Please note that if an external force is applied to the rod in a direction other than the proper direction the rod travels, the detent may get damaged.
(3) The maximum pushing force when the speed is 5mm/s.
(4) Service life decreases significantly if used in a dusty environment.

Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Maximum pushing force (N)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-RA2BC-I-20P-6S-①-②-③-④	Lead Screw	6	0.25	0.125	See page 97.	±0.05	25 to 150 (every 25mm)
RCP3-RA2BC-I-20P-4S-①-②-③-④		4	0.5	0.25			
RCP3-RA2BC-I-20P-2S-①-②-③-④		2	1	0.5			

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 (mm)	75 to 150 (mm)
Lead screw 6	180	280	300
Lead screw 4	180	200	
Lead screw 2	100		

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot cable type comes standard on RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw φ6mm rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal: 5 million (number of cycles) Vertical: 10 million (number of cycles)

Options

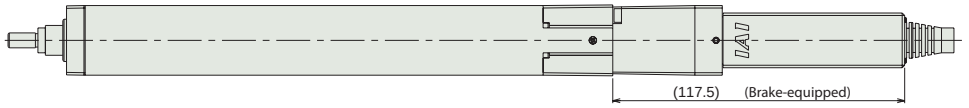
Title	Option code	See page	
Brake	**B**	→P24	
Reversed - home specification	**NM**	–	

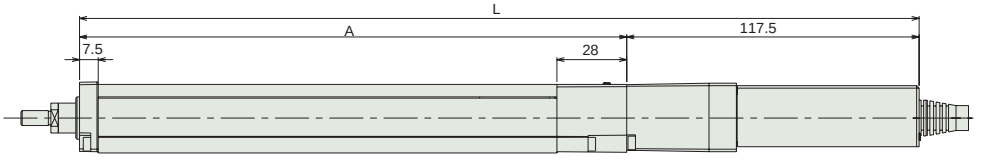
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

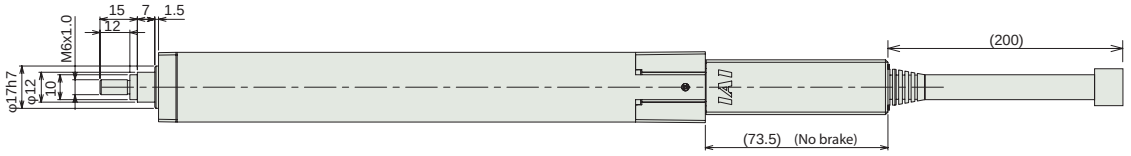
2D CAD

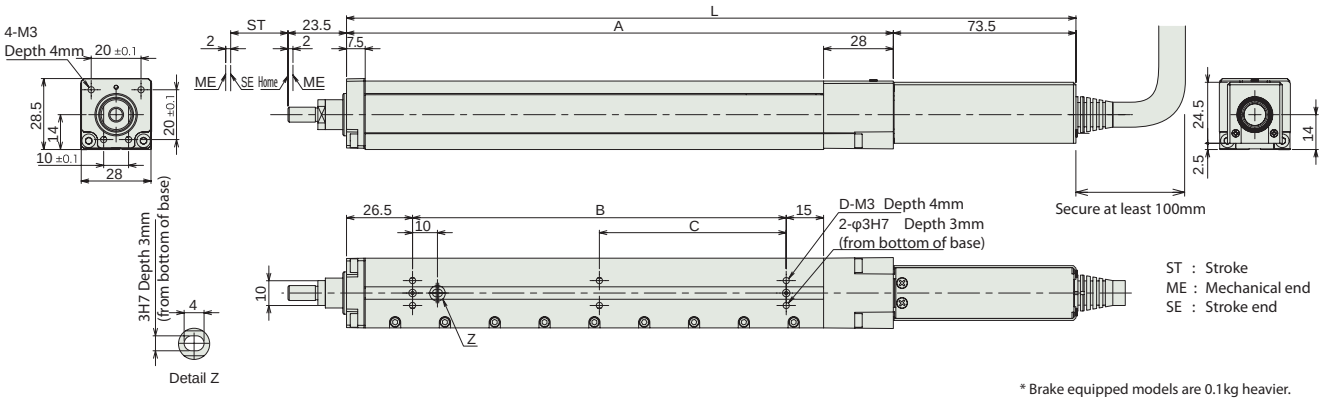
(Brake-equipped)





(No brake)





ST : Stroke
ME : Mechanical end
SE : Stroke end

* Brake equipped models are 0.1kg heavier.

Dimensions and Weight by Stroke

Stroke		25	50	75	100	125	150
L	No brake	168	193	218	243	268	293
	Brake-equipped	212	237	262	287	312	337
A		94.5	119.5	144.5	169.5	194.5	219.5
B		25	50	75	100	125	150
C		0	0	0	50	62.5	75
D		4	4	4	6	6	6
Mass (kg)		0.3	0.34	0.38	0.41	0.44	0.47

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-RA2AR

RoboCylinder Mini Rod type Motor Unit Reverse-mounted type Actuator Width 58mm Pulse Motor Lead Screw Specification

Model Description

RCP3 – RA2AR – I – 20P – □ – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□ Size	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	25:25 mm ↓ 100:100 mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

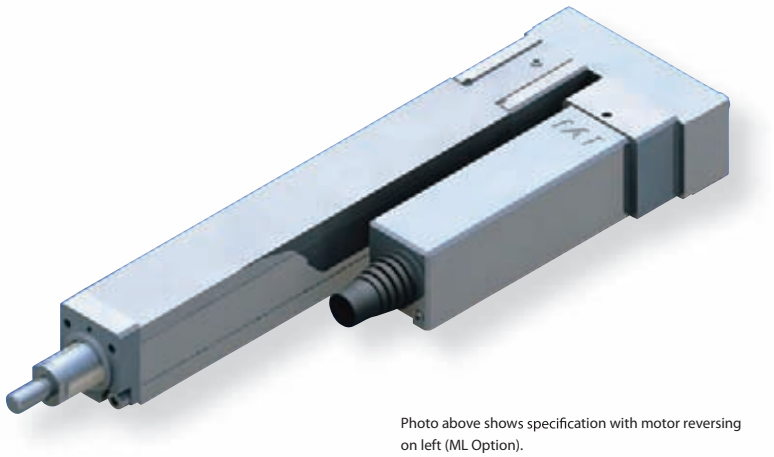


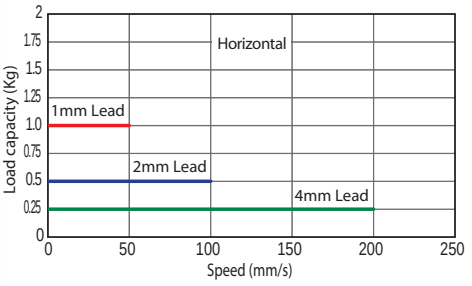
Photo above shows specification with motor reversing on left (ML Option).

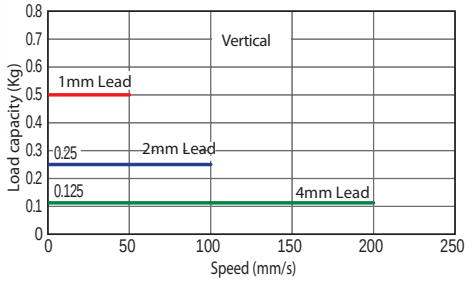
POINT Notes on selection

(1) The load capacity is the value when operated at 0.2G acceleration. The acceleration limit is the value indicated above.
(2) The horizontal payload is the value when used in combination with an external guide. Please note that if an external force is applied to the rod in a direction other than the proper direction the rod travels, the detent may get damaged.
(3) The maximum pushing force when the speed is 5mm/s.
(4) Service life decreases significantly if used in a dusty environment.

Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Maximum pushing force (N)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-RA2AR-I-20P-4S-①-②-③-④	Lead Screw	4	0.25	0.125	See page 97.	±0.05	25 to 100 (every 25mm)
RCP3-RA2AR-I-20P-2S-①-②-③-④		2	0.5	0.25			
RCP3-RA2AR-I-20P-1S-①-②-③-④		1	1	0.5			

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 to 100 (mm)
Lead screw 4	180	200
Lead screw 2	100	
Lead screw 1	50	

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot cable type comes standard on RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw φ4mm rolled C10
Backlash	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide	Slide guide
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal: 10 million (number of cycles) Vertical: 5 million (number of cycles)

Options

Title	Option code	See page	
Brake	**B**	–	
Specification with motor reversing on left	**ML**	–	
Specification with motor reversing on right	**MR**	–	
Reversed - home specification	**NM**	–	

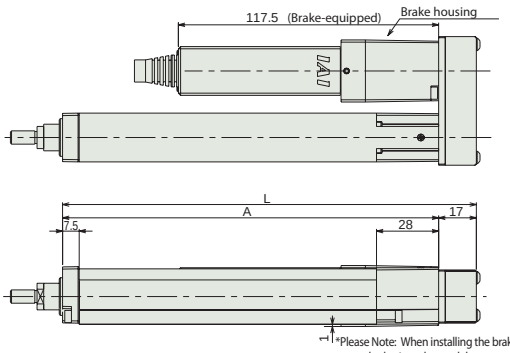
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

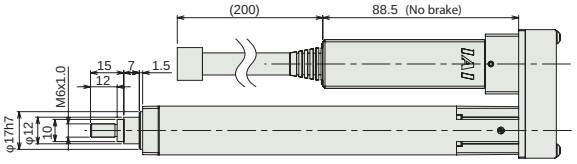
2D CAD

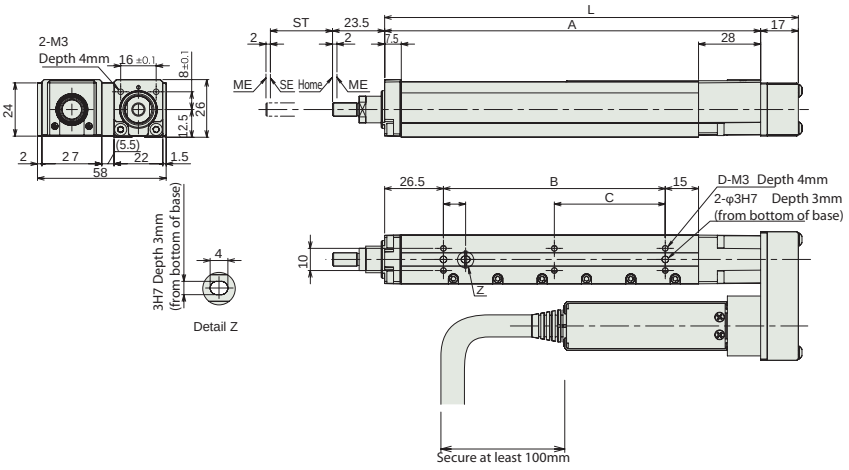
*The drawing below shows the specification with motor reversing on right.

(Brake-equipped)



(No brake)





ST : Stroke
ME : Mechanical end
SE : Stroke end

* Brake equipped models are 0.1kg heavier.

Dimensions and Weight by Stroke

Stroke	25	50	75	100
L	111.5	136.5	161.5	186.5
A	94.5	119.5	144.5	169.5
B	25	50	75	100
C	0	0	0	50
D	4	4	4	6
Mass (kg)	0.29	0.32	0.34	0.36

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-RA2BR

RoboCylinder Mini Rod type Motor Unit Reverse-mounted type Actuator Width 59.5mm Pulse Motor Lead Screw Specification

Model Description

RCP3 – RA2BR – I – 20P – □ – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable Length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20 □ Size	6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	25: 25 mm ↕ 150: 150 mm (every 25mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

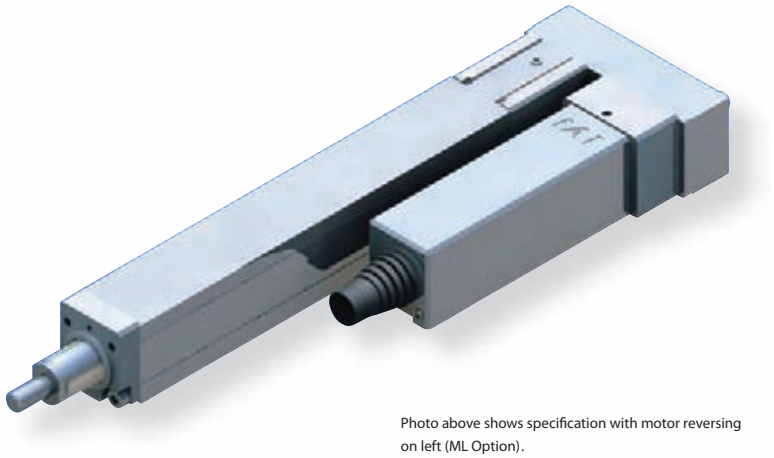


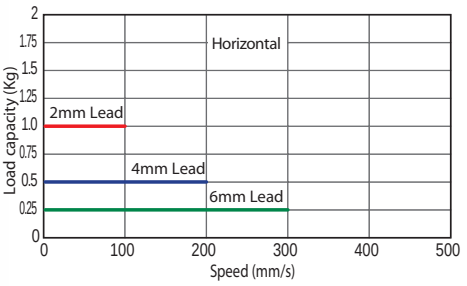
Photo above shows specification with motor reversing on left (ML Option).

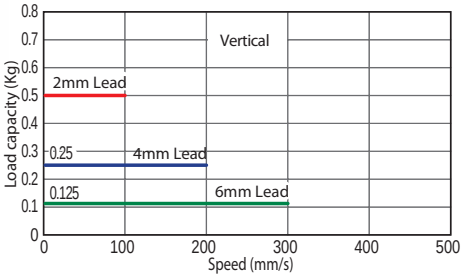
POINT Notes on selection

(1) The load capacity is the value when operated at 0.2G acceleration. The acceleration limit is the value indicated above.
(2) The horizontal payload is the value when used in combination with an external guide. Please note that if an external force is applied to the rod in a direction other than the proper direction the rod travels, the detent may get damaged.
(3) The maximum pushing force when the speed is 5mm/s.
(4) Service life decreases significantly if used in a dusty environment.

Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

Leads and Payloads

Model	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Maximum pushing force (N)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-RA2BR-I-20P-6S-①-②-③-④	Lead Screw	6	0.25	0.125	See page 97.	±0.05	25 to 150 (every 25mm)
RCP3-RA2BR-I-20P-4S-①-②-③-④		4	0.5	0.25			
RCP3-RA2BR-I-20P-2S-①-②-③-④		2	1	0.5			

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

Stroke and Maximum Speed

Lead \ Stroke	25 (mm)	50 (mm)	75 to 150 (mm)
Lead screw 6	180	280	300
Lead screw 4	180	200	
Lead screw 2	100		

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot cable type comes standard on RCA3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw φ6mm rolled C10
Backlash	0.3mm or less initial value
Base	Material: Aluminum, white alumite treated
Guide	Slide Guide
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal: 10 million (number of cycles) Vertical: 5 million (number of cycles)

Options

Title	Option code	See page	
Brake	**B**	–	
Specification with motor reversing on left	**ML**	–	
Specification with motor reversing on right	**MR**	–	
Reversed - home specification	**NM**	–	

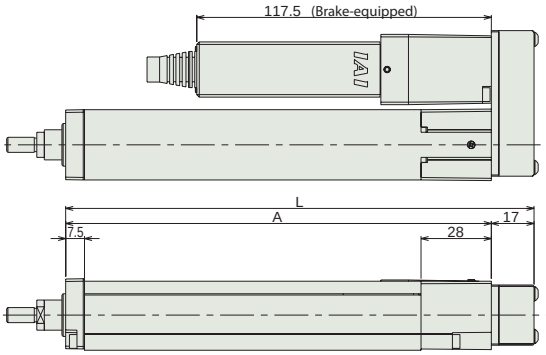
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

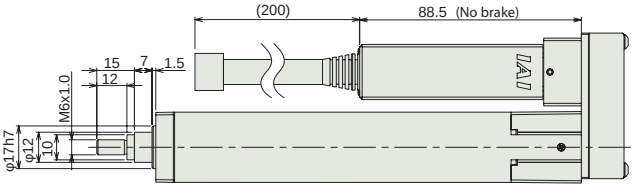
2D CAD

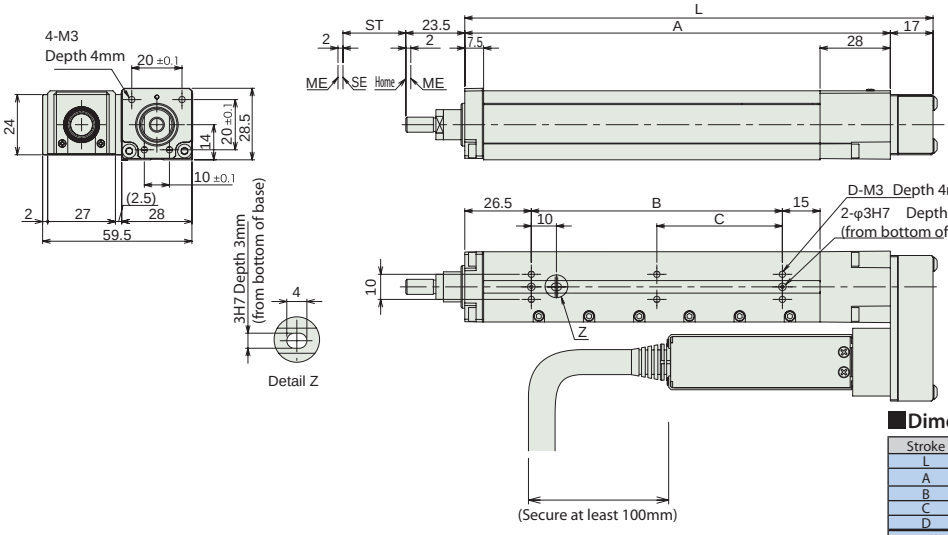
*The drawing below shows the specification with motor reversing on right.

(Brake-equipped)



(No brake)





ST : Stroke
ME : Mechanical end
SE : Stroke end

*With brake, the mass increases by 0.1kg.

Dimensions and Weight by Stroke

Stroke	25	50	75	100	125	150
L	111.5	136.5	161.5	186.5	211.5	236.5
A	94.5	119.5	144.5	169.5	194.5	219.5
B	25	50	75	100	125	150
C	0	0	0	50	62.5	75
D	4	4	4	6	6	6
Mass (kg)	0.33	0.37	0.4	0.43	0.46	0.49

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCA2-RN3N

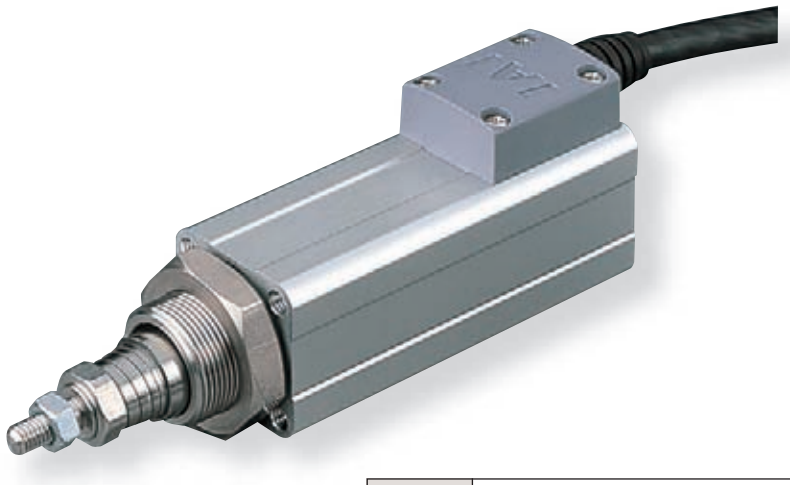
RoboCylinder Mini Rod type Short Length Fixed Nut type Actuator Width 28mm 24V servo motor Lead screw specification

■Model Description

RCA2 – RN3N – I – 10 – □ – 30 – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1 : ACON RACON ASEL A3 : ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The lead screw is not equipped with an anti-rotation device, so please attach a guide or similar locking device to the tip of the lead screw prior to use. (If there is no anti-rotation device attached, the lead screw cannot extend or retract.)
(2) The load capacity is the value when operated at 0.2G acceleration. Acceleration limit is value indicated above.
(3) Do not apply an external force on the rod in any direction other than the direction the rod is moving in.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-RN3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-RN3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-RN3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

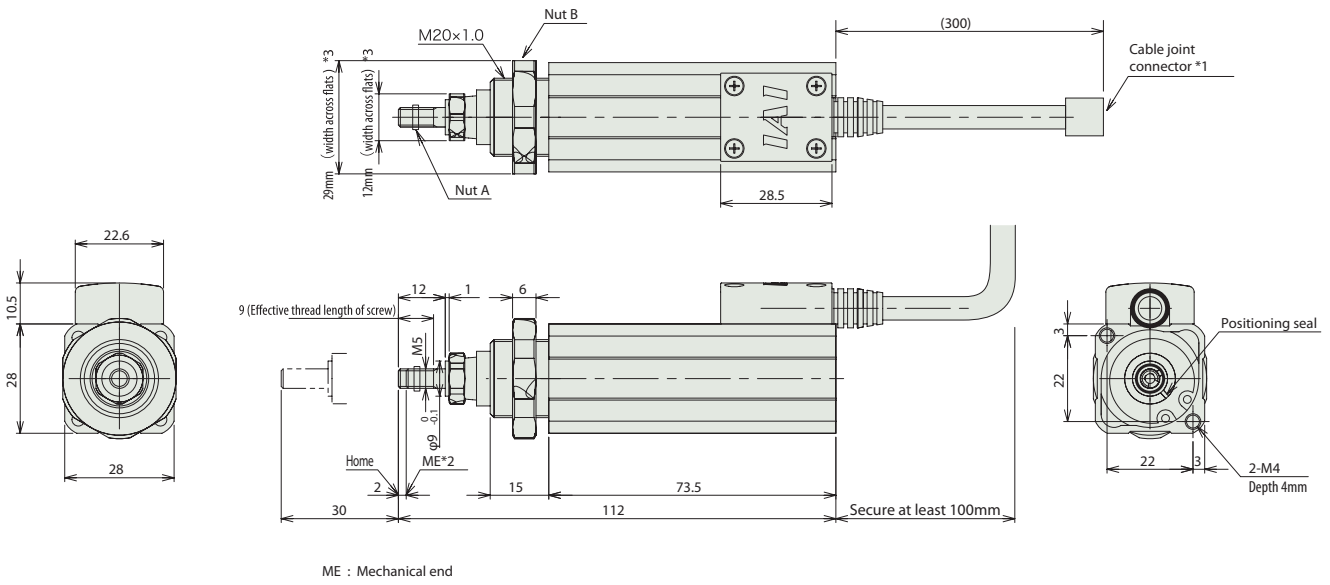
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P30	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

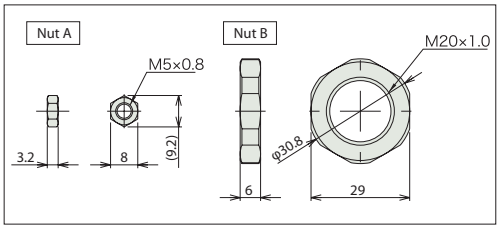
CAD drawings can be downloaded from the website. www.robocylinder.de

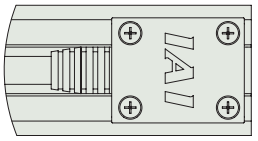
2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
*3 The direction of fixing nut varies according to the product.



ME : Mechanical end





Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.25

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-RN4N

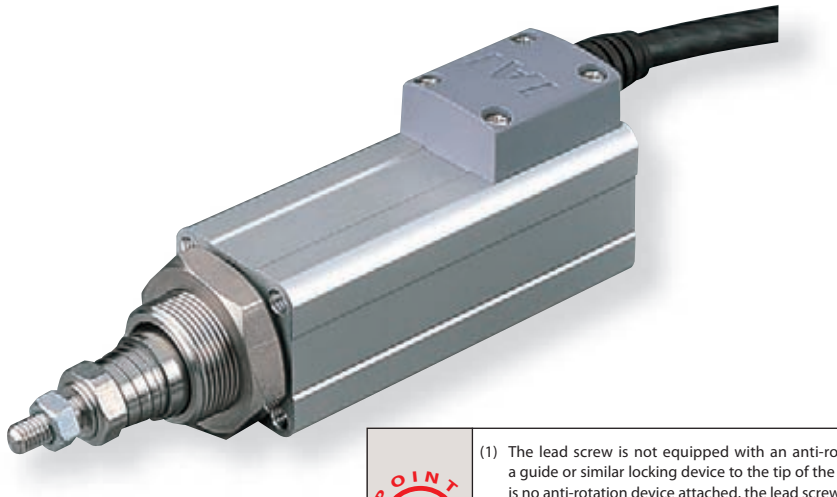
RoboCylinder Mini Rod type Short Length Fixed Nut type Actuator Width 34mm 24V servo motor
Ball screw specification/Lead screw specification

■Model Description

RCA2 – RN4N – I – 20 – | – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The lead screw is not equipped with an anti-rotation device, so please attach a guide or similar locking device to the tip of the lead screw prior to use. (If there is no anti-rotation device attached, the lead screw cannot extend or retract.)

(2) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use). Acceleration limit is value indicated above.

(3) Do not apply an external force on the rod in any direction other than the direction the rod is moving in.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-RN4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-RN4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-RN4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-RN4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-RN4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-RN4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead		Stroke 30 (mm)
Ball screw	6	270 <220>
	4	200
	2	100
Lead screw	6	220
	4	200
	2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Ambient operating temperature, humidity		0 to 40 °C , 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

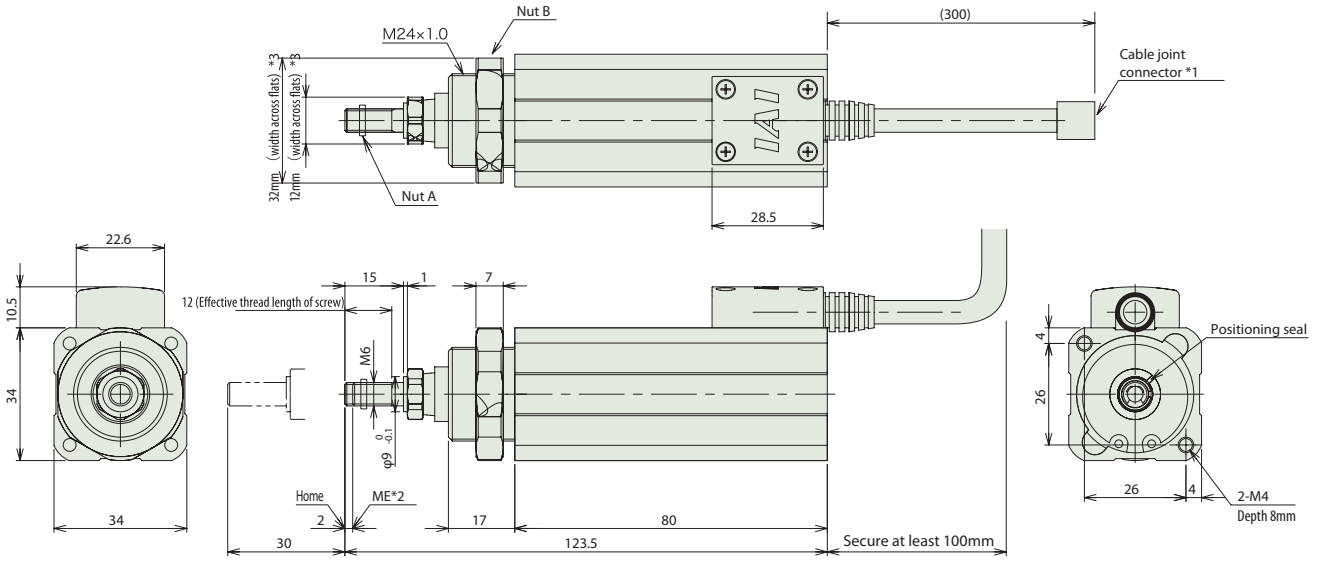
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P32	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

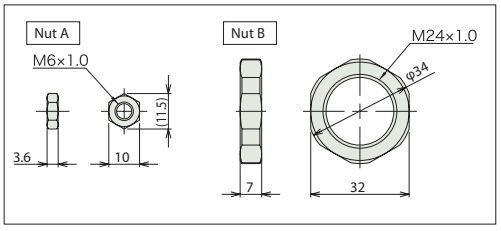
CAD drawings can be downloaded from the website. www.robocylinder.de

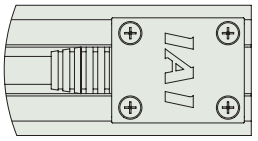
2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
*3 The direction of fixing nut varies according to the product.



ME : Mechanical end





Changing cable connector outlet direction
(Model : K2)

* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.5

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-RP3N

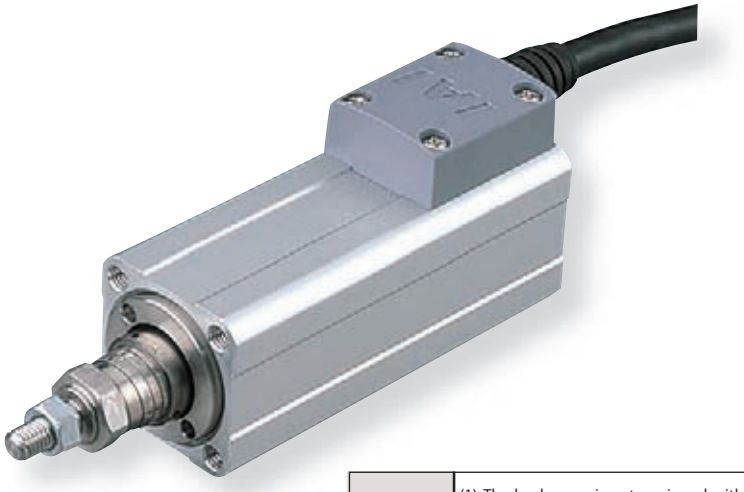
RoboCylinder Mini Rod type Short Length Tapped Hole type Actuator Width 28mm 24V servo motor Lead screw specification

■Model Description

RCA2 – RP3N – I – 10 – [ ] – 30 – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
—	—	I: Incremental specification * Model number is "I" when used with simple absolute unit	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The lead screw is not equipped with an anti-rotation device, so please attach a guide or similar locking device to the tip of the lead screw prior to use. (If there is no anti-rotation device attached, the lead screw cannot extend or retract.)

(2) The load capacity is the value when operated at 0.2G acceleration. Acceleration limit is value indicated above.

(3) Do not apply an external force on the rod in any direction other than the direction the rod is moving in.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-RP3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-RP3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-RP3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

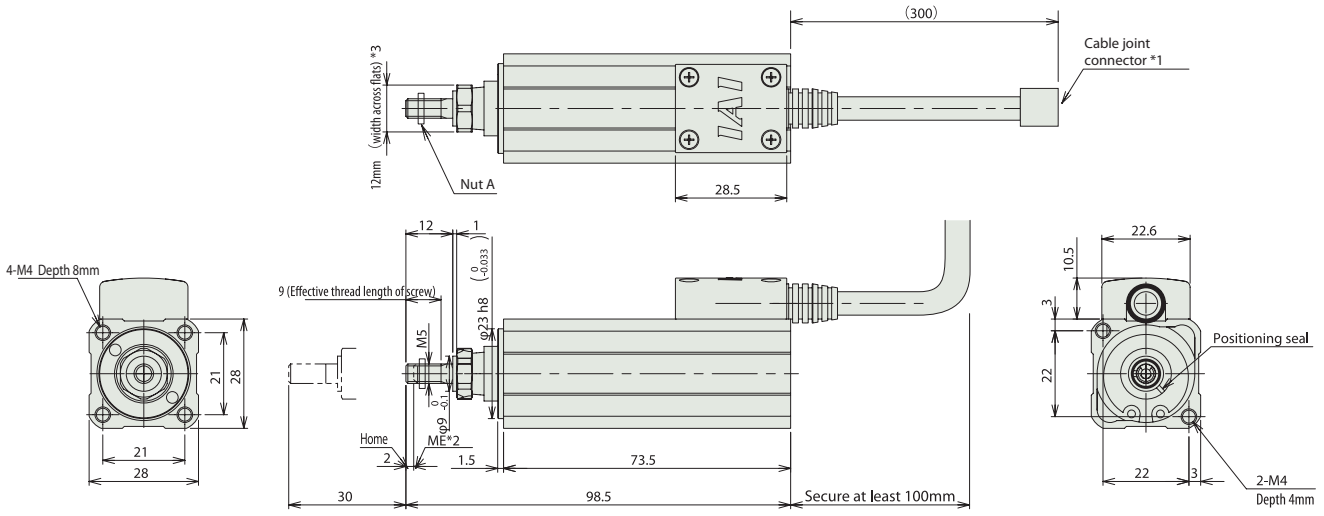
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P34	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

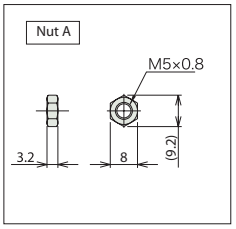
CAD drawings can be downloaded from the website. www.robocylinder.de

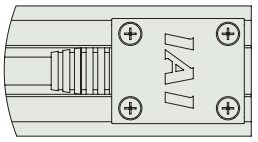
2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
*3 The direction of fixing nut varies according to the product.



ME : Mechanical end





Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.2

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1)) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-RP4N

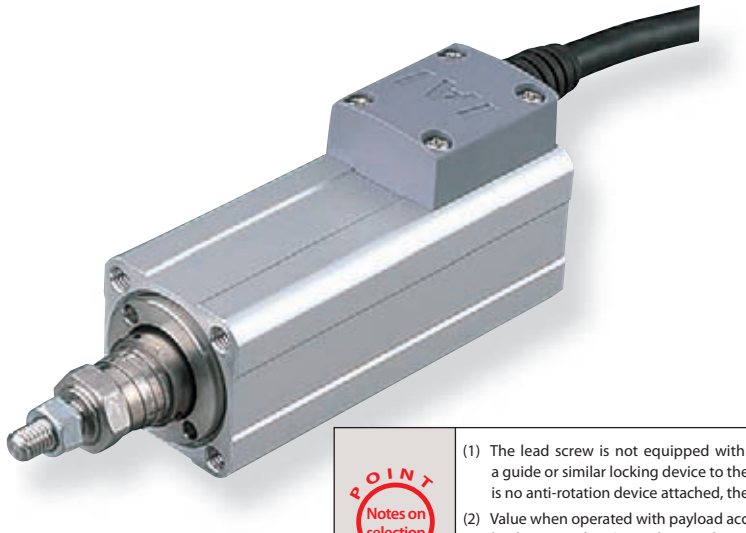
RoboCylinder Mini Rod type Short Length Tapped Hole type Actuator Width 34mm 24V servo motor Ball screw specification/ Lead screw specification

■Model Description

RCA2 – RP4N – I – 20 – [ ] – 30 – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The lead screw is not equipped with an anti-rotation device, so please attach a guide or similar locking device to the tip of the lead screw prior to use." (If there is no anti-rotation device attached, the lead screw cannot extend or retract.)

(2) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use). Acceleration limit is value indicated above.

(3) Do not apply an external force on the rod in any direction other than the direction the rod is moving in.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-RP4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-RP4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-RP4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-RP4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-RP4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-RP4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

	Lead \ Stroke	30 (mm)
Ball screw	6	270 <220>
	4	200
	2	100
Lead screw	6	220
	4	200
	2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Ambient operating temperature, humidity		0 to 40 °C ,85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles Vertical specification: 5 million cycles

Options

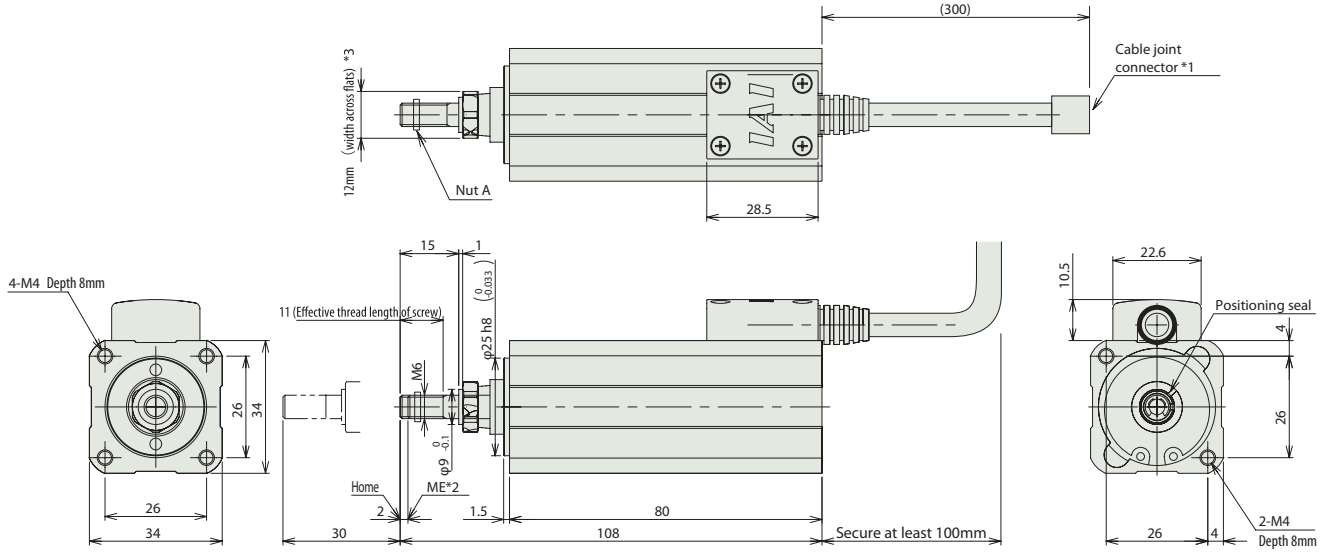
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P36	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

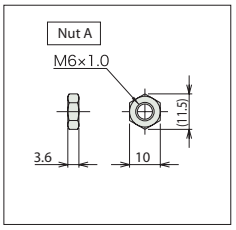
CAD drawings can be downloaded from the website. www.robocylinder.de

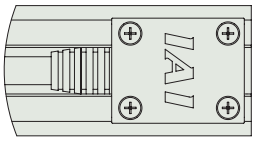
2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.
*3 The direction of fixing nut varies according to the product.



ME : Mechanical end





Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.42

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-GS3N

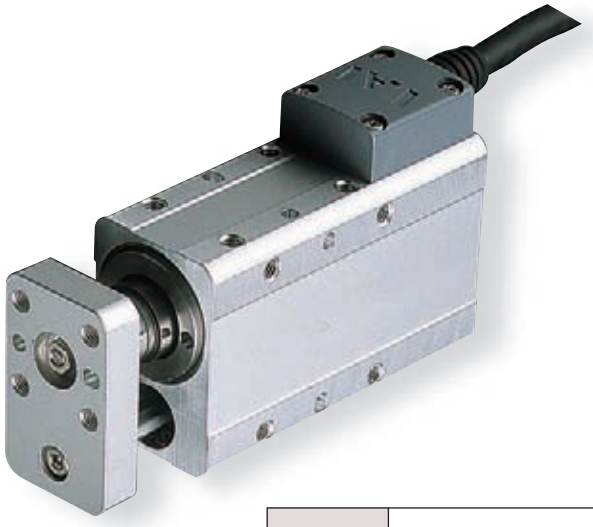
RoboCylinder Mini Rod type Short Length Single-Guide Free Mount type Actuator Width 28mm 24V servo motor Lead screw specification

■Model Description

RCA2 – GS3N – I – 10 – □ – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod.

(2) See P99 for correlation diagrams of the tip load and service life when a guide is not installed.

(3) The load capacity is the value when operated at 0.2G acceleration. Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-GS3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-GS3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-GS3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

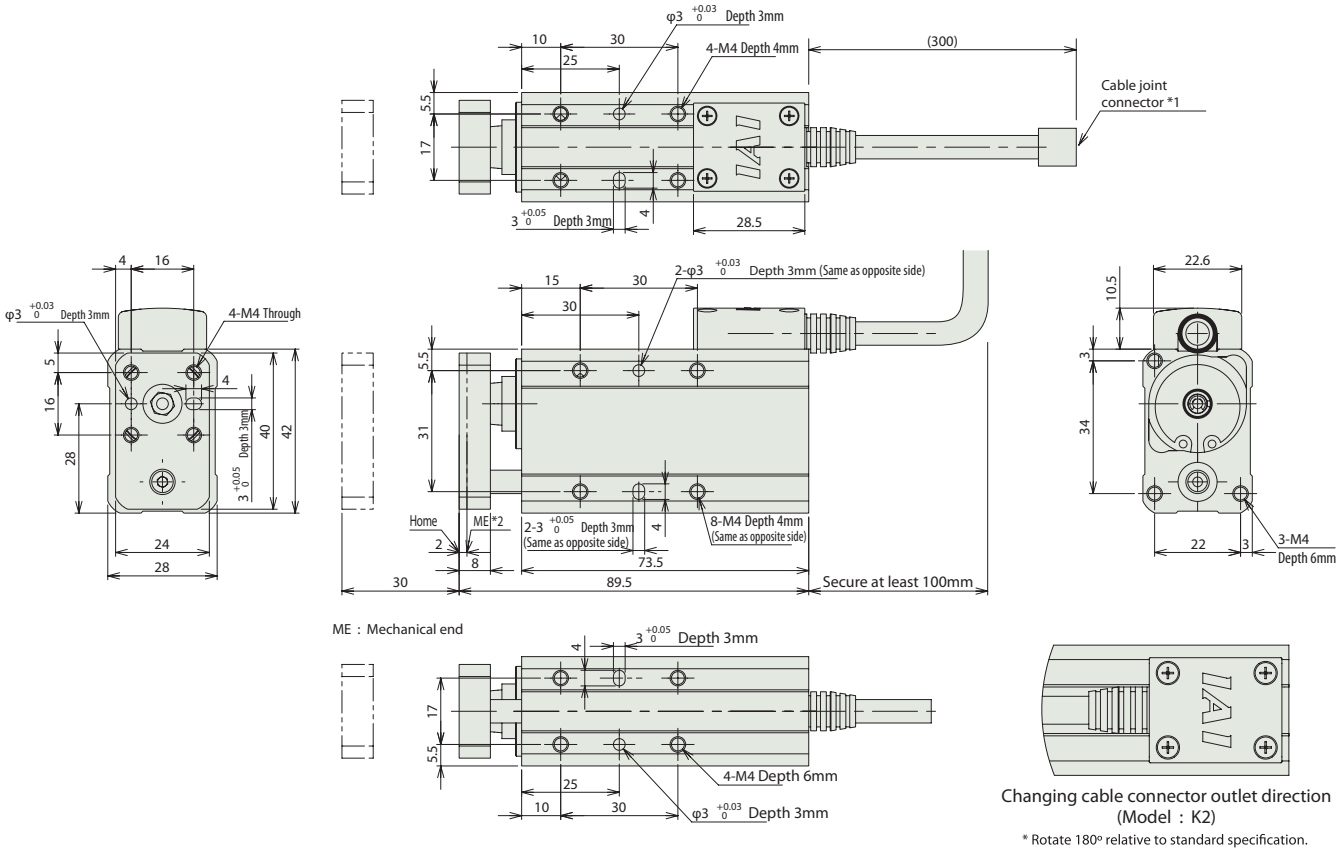
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P38	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction (Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.32

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-GS4N

RoboCylinder Mini Rod type Short Length Single-Guide Free Mount type Actuator Width 34mm 24V servo motor
Ball screw specification/ Lead screw specification

■Model Description

RCA2 – GS4N – I – 20 – □ – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod.
(2) See P99 for correlation diagrams of the tip load and service life when a guide is not installed.
(3) The load capacity is the value when operated at 0.3G acceleration (or 0.2G in the case of lead 2, vertical use).
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-GS4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-GS4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-GS4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-GS4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-GS4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-GS4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead	Stroke 30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Ambient operating temperature, humidity		0 to 40 ºC , 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles Vertical specification: 5 million cycles

Options

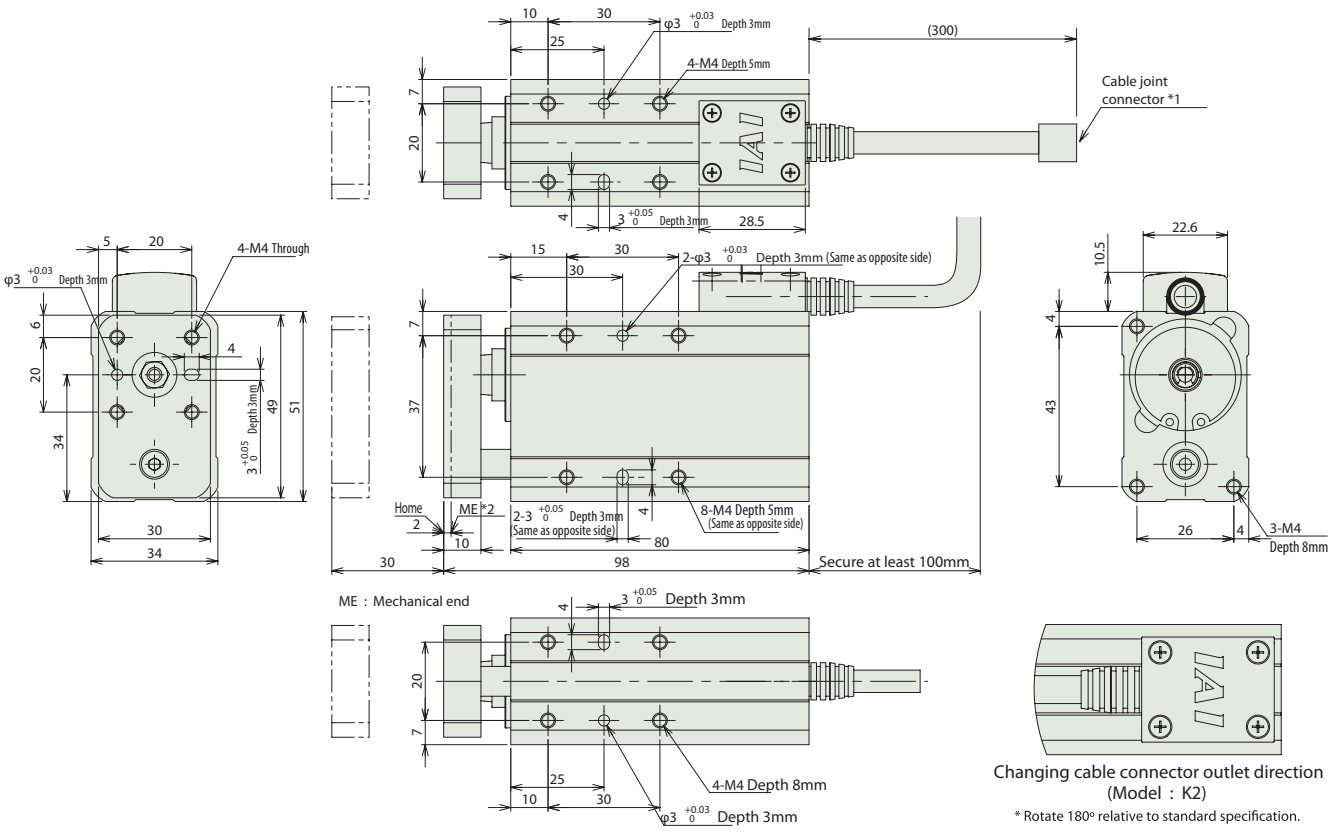
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P40	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.55

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-GD3N

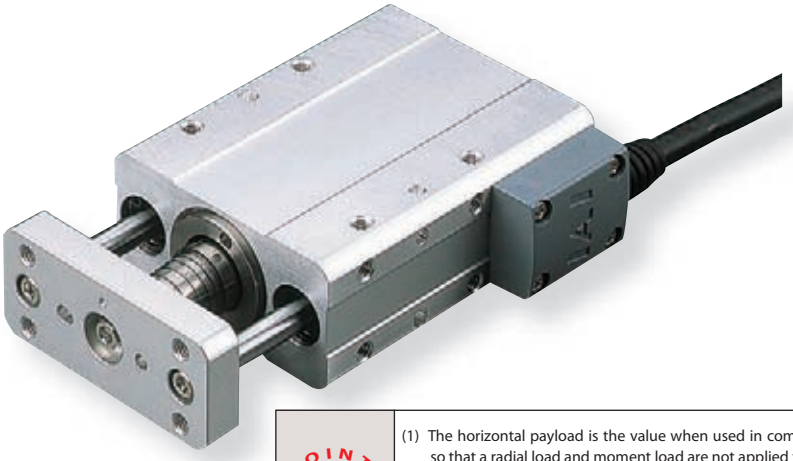
RoboCylinder Mini Rod type Short Length Double-Guide Free Mount type Actuator Width 28mm 24V servo motor/Lead screw specification

■Model Description

RCA2 – GD3N – I – 10 – [ ] – 30 – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
—	—	I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30 mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod.
(2) See P99 for correlation diagrams of the tip load and service life when a guide is not installed.
(3) The load capacity is the value when operated at 0.2G acceleration. Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-GD3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30
RCA2-GD3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-GD3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

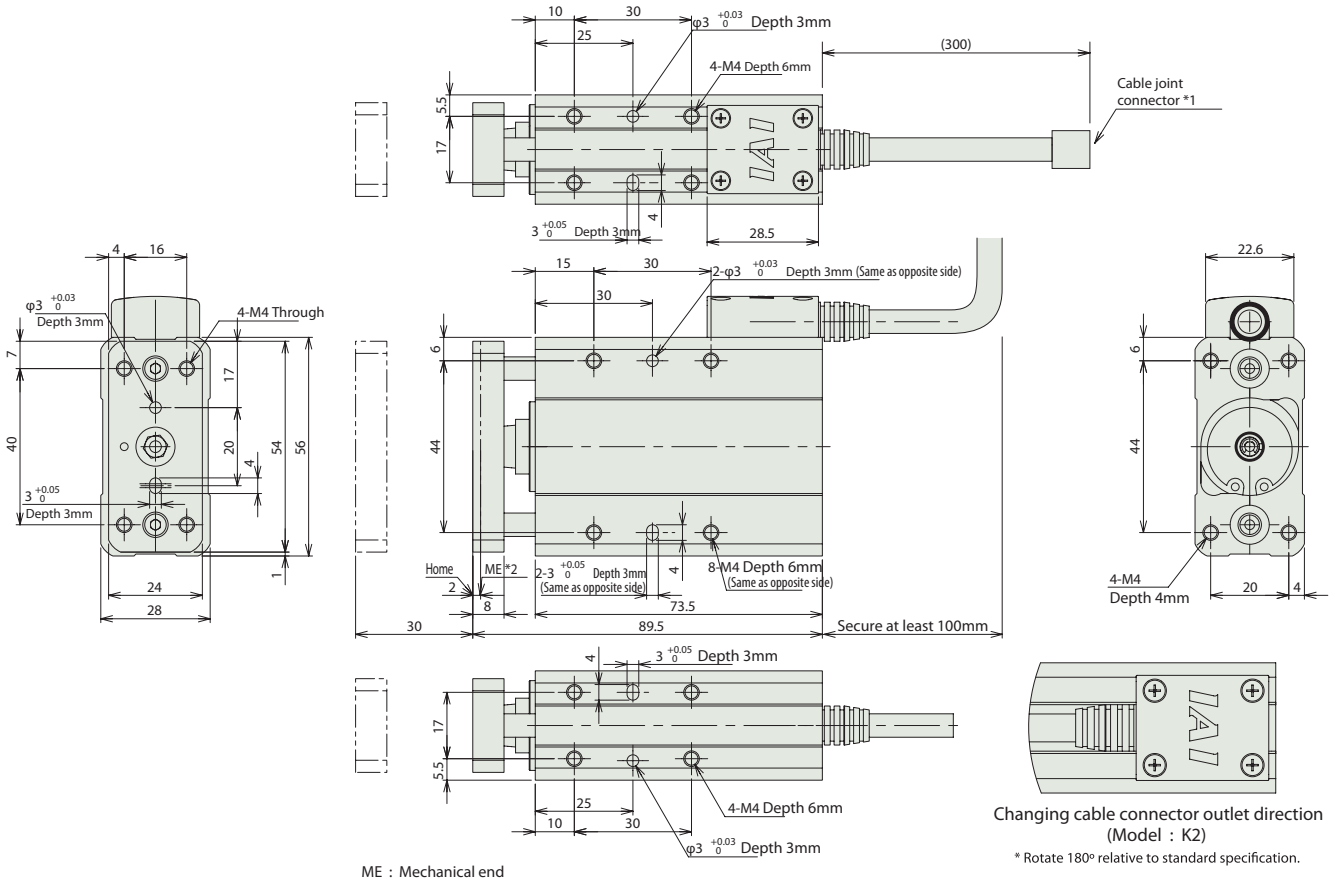
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P42	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



ME : Mechanical end
SE : Stroke end

Changing cable connector outlet direction (Model : K2)
* Rotate 180° relative to standard specification.

■Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.41

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-GD4N

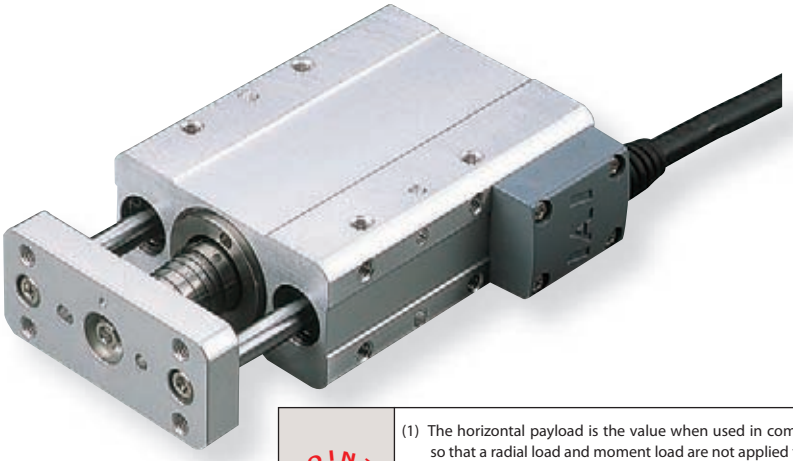
RoboCylinder Mini Rod type Short Length Double-Guide Free Mount type Actuator Width 34mm 24V servo motor
Ball screw specification/ Lead screw specification

■Model Description

RCA2 – GD4N – I – 20 – □ – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod.
(2) See P99 for correlation diagrams of the tip load and service life when a guide is not installed.
(3) The load capacity is the value when operated at 0.3G acceleration (or 0.2G in the case of lead 2, vertical use).
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-GD4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-GD4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-GD4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-GD4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-GD4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-GD4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead	Stroke 30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Ambient operating temperature, humidity		0 to 40 ºC, 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

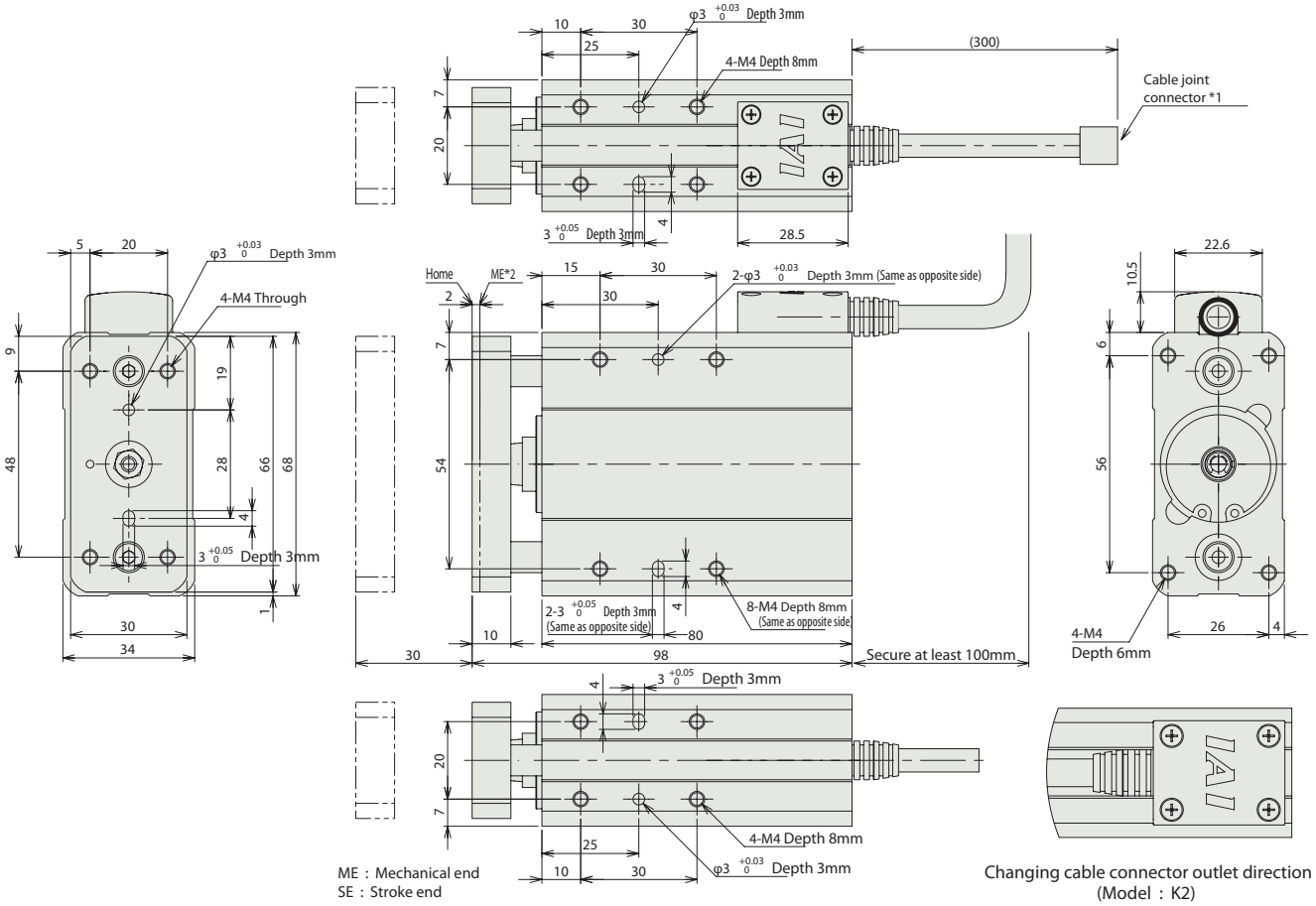
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P44	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction (Model : K2)

* Rotate 180° relative to standard specification.

■Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.64

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-SD3N

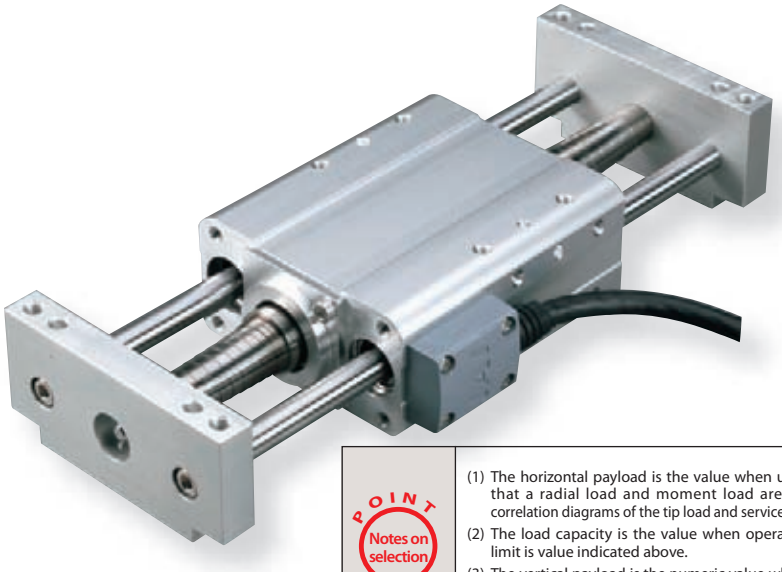
RoboCylinder Mini Rod type Short Length Double-Guide Slide Unit type Actuator Width 60mm 24V servo motor Lead screw specification

■Model Description

RCA2 – SD3N – I – 10 – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	25: 25mm 50: 50mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod. See P99 for correlation diagrams of the tip load and service life when a guide is not installed.
(2) The load capacity is the value when operated at 0.2G acceleration. Acceleration limit is value indicated above.
(3) The vertical payload is the numeric value when the main unit is fixed and the side bracket is moved. Please note that the main unit cannot be moved in the case of vertical operation.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-SD3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125 (*1)	25.1	±0.05	25 50
RCA2-SD3N-I-10-2S-30-①-②-③			2	0.5	0.25 (*1)	50.3		
RCA2-SD3N-I-10-1S-30-①-②-③			1	1	0.5 (*1)	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

(*1)When main unit side is fixed

■Stroke and Maximum Speed

Lead \ Stroke	25/50 (mm)
4	200
2	100
1	50

Lead screw

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles Vertical specification: 5 million cycles

Options

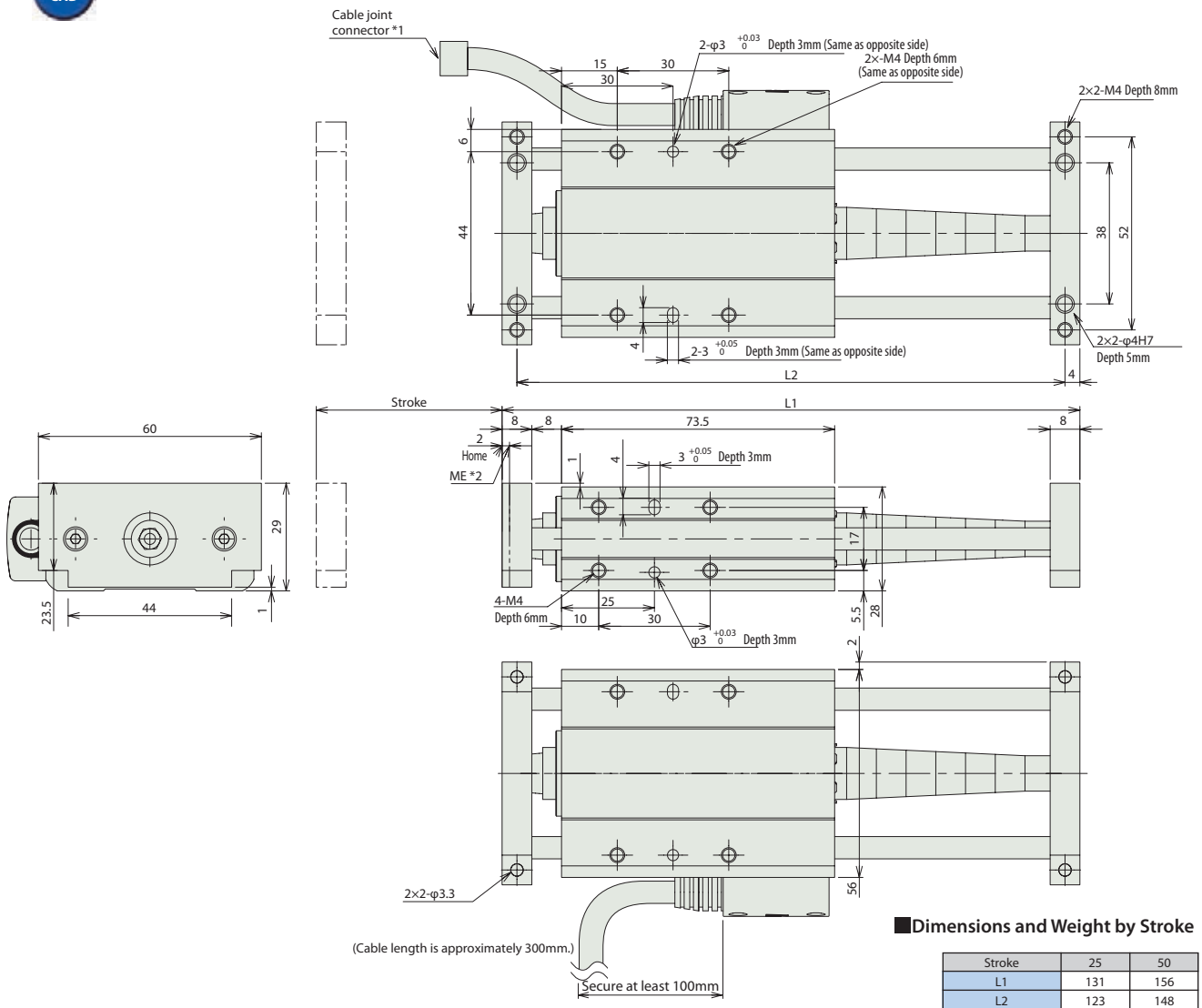
Title	Option code	See page	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Dimensions and Weight by Stroke

Stroke	25	50
L1	131	156
L2	123	148
Mass (kg)	0.48	0.5

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating w ith the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-SD4N

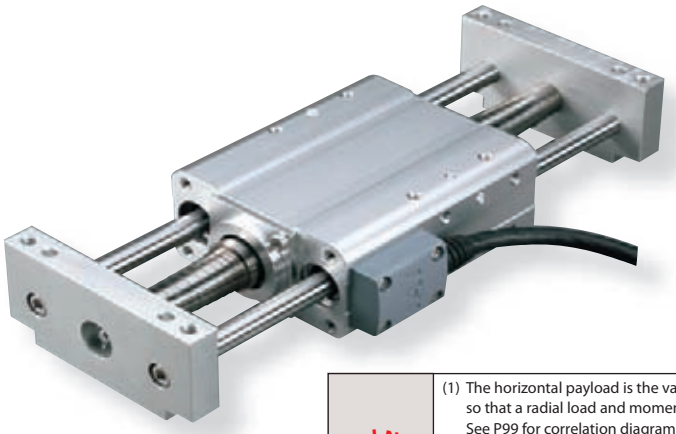
RoboCylinder Mini Rod type Short Length Double-Guide Slide Unit type Actuator Width 72mm 24V servo motor
Ball screw specification/ Lead screw specification

■Model Description

RCA2 – SD4N – I – 20 – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	25: 25mm 50: 50mm 75: 75mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The horizontal payload is the value when used in combination with the guide so that a radial load and moment load are not applied to the rod.
See P99 for correlation diagrams of the tip load and service life when a guide is not installed.

(2) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use). Acceleration limit is value indicated above.

(3) The vertical payload is the numeric value when the main unit is fixed and the side bracket is moved. Please note that the main unit cannot be moved in the case of vertical operation.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-SD4N-I-20-6- ① - ② - ③	20	Ball screw	6	2	0.5 (*1)	33.8	±0.02	25 50 75
RCA2-SD4N-I-20-4- ① - ② - ③			4	3	0.75 (*1)	50.7		
RCA2-SD4N-I-20-2- ① - ② - ③			2	6	1.5 (*1)	101.5		
RCA2-SD4N-I-20-6S- ① - ② - ③	20	Lead screw	6	0.25	0.125 (*1)	19.9	±0.05	25 50 75
RCA2-SD4N-I-20-4S- ① - ② - ③			4	0.5	0.25 (*1)	29.8		
RCA2-SD4N-I-20-2S- ① - ② - ③			2	1	0.5 (*1)	59.7		

Legend ① Stroke ② Compatible Controllers ③ Cable length

(*1) When main unit side is fixed

■Stroke and Maximum Speed

Lead \ Stroke		25 (mm)	50 to 75 (mm)
Ball screw	6	240 <200>	300
	4	200	200
	2	100	100
Lead screw	6	200	300
	4	200	200
	2	100	100

*< > Indicates Vertical Use

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Ambient operating temperature, humidity		0 to 40 °C, 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

Options

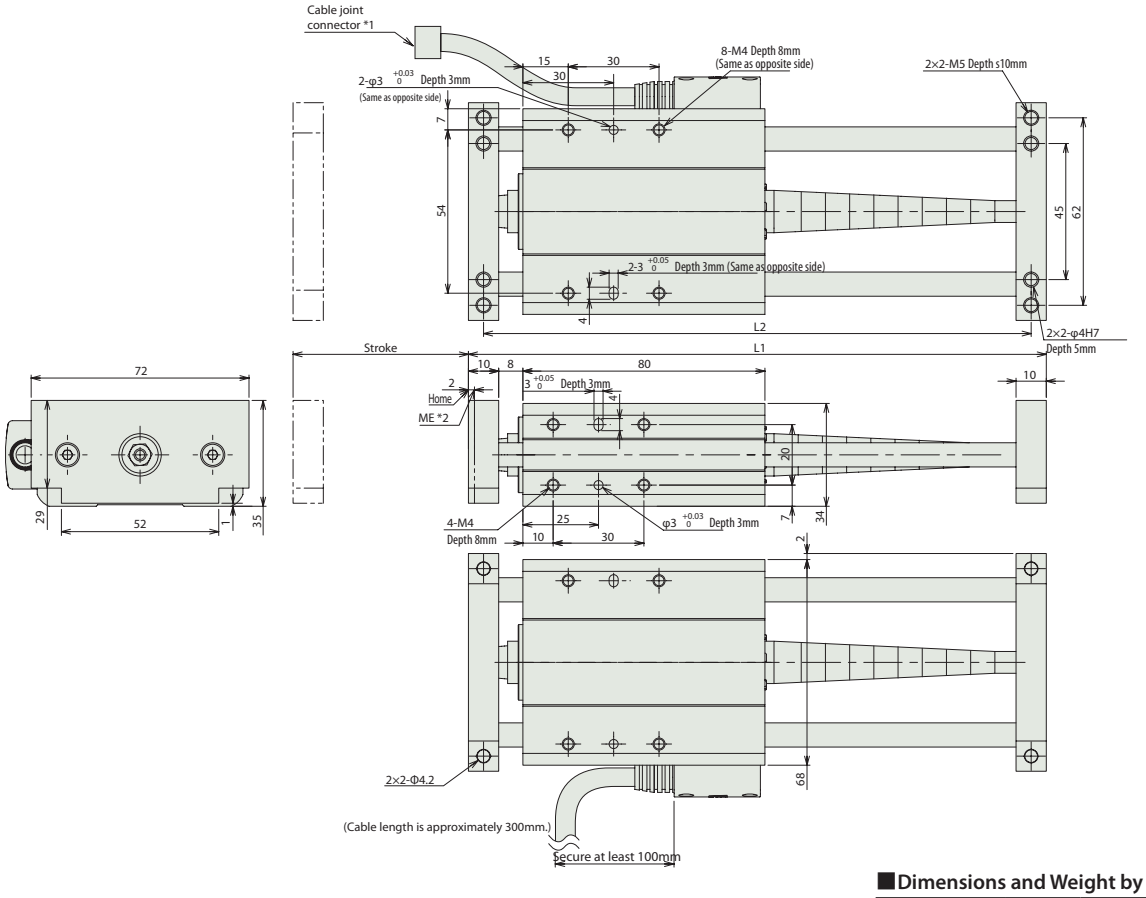
Title	Option code	See page	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Dimensions and Weight by Stroke

Stroke	25	50	75
L1	141	166	191
L2	131	156	181
Mass (kg)	0.73	0.75	0.77

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TC3N

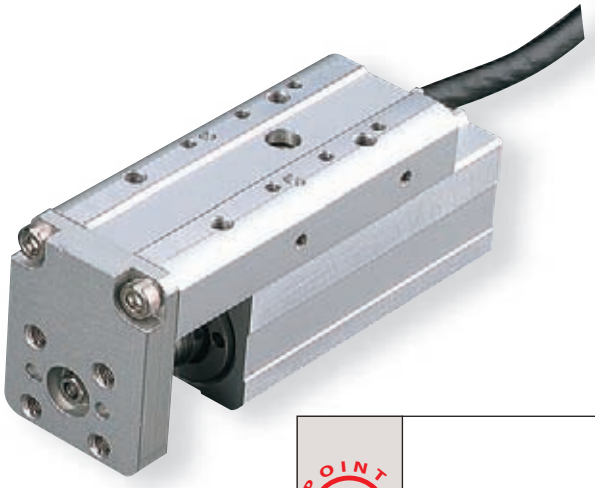
RoboCylinder Mini Table type Short Length Compact type Actuator Width 32mm 24V servo motor
Lead screw specification

■Model Description

RCA2 — TC3N — I — 10 — □ — 30 — □ — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TC3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-TC3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-TC3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma : 9.9 N・m Mb : 9.9 N・m Mc : 3.3 N・m
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.

Options

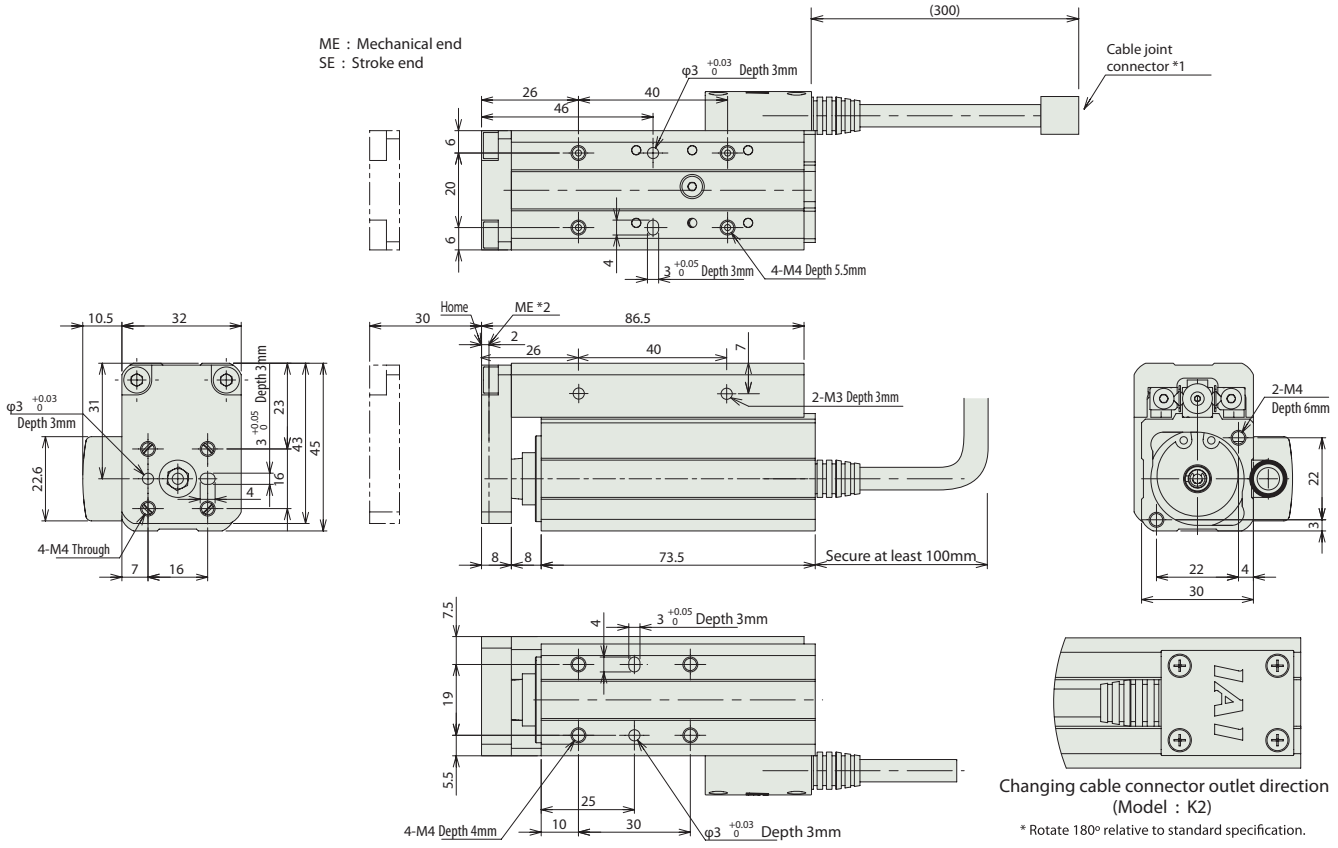
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P50	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.37

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TC4N

RoboCylinder Mini Table type Short Length Compact type Actuator Width 36mm
24V servo motor Ball screw specification/ Lead screw specification

■Model Description

RCA2 — TC4N — I — 20 — □ — 30 — □ — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use).
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TC4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-TC4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-TC4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-TC4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-TC4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-TC4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)		Ma : 9.9 N・m Mb : 9.9 N・m Mc : 3.3 N・m
Ambient operating temperature, humidity		0 to 40 °C, 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.

Options

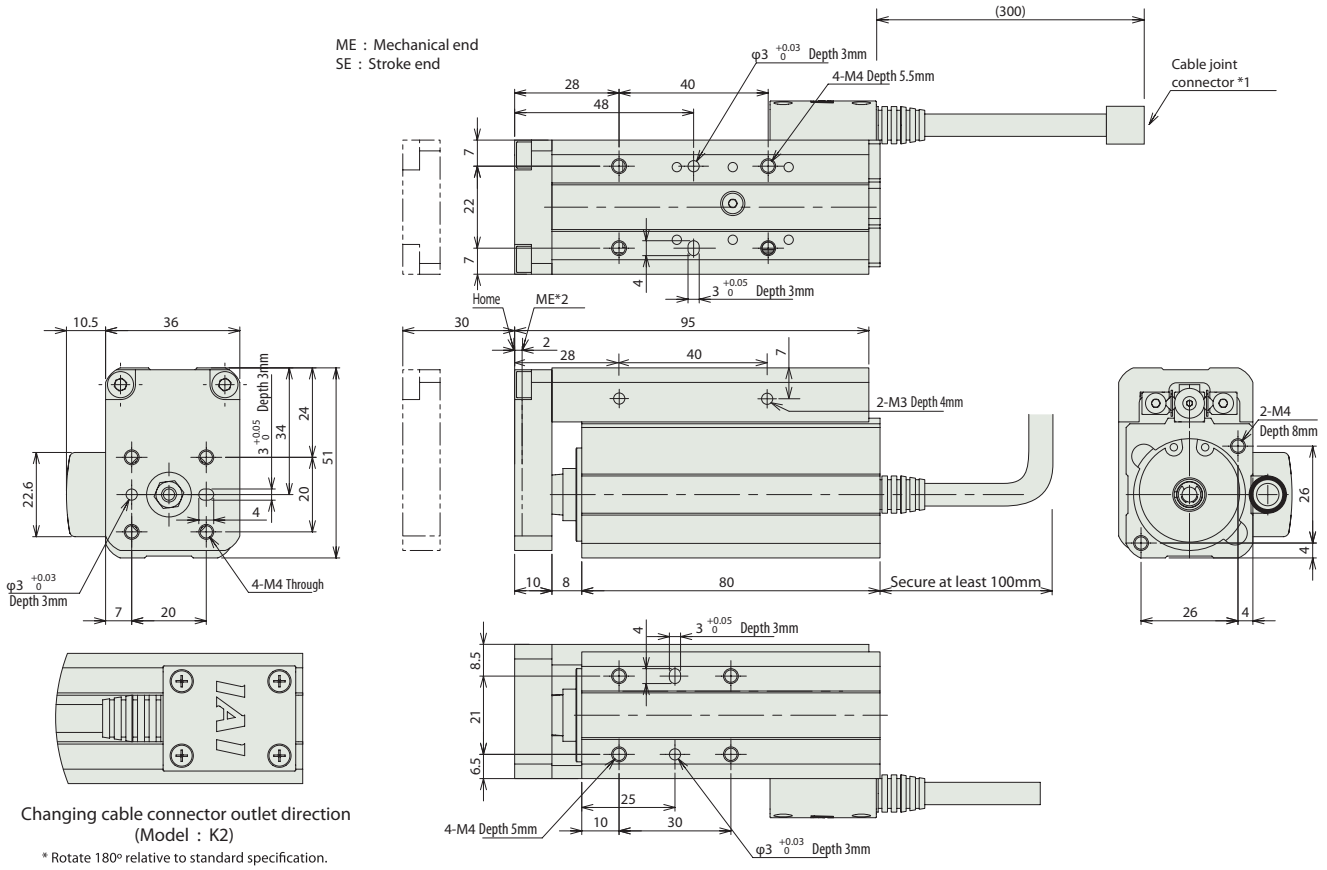
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P52	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction (Model : K2)

* Rotate 180º relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.48

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TW3N

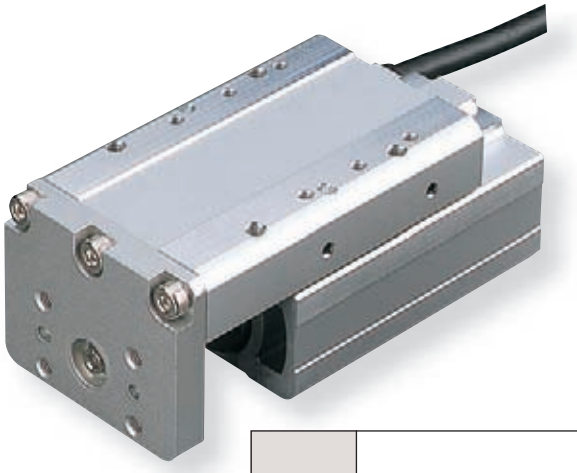
RoboCylinder Mini Table type Short Length Wide type Actuator Width 50mm
24V servo motor Lead screw specification

■Model Description

RCA2 – TW3N – I – 10 – □ – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TW3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-TW3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-TW3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma : 9.9 N m Mb : 9.9 N m Mc : 9.4 N m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.

Options

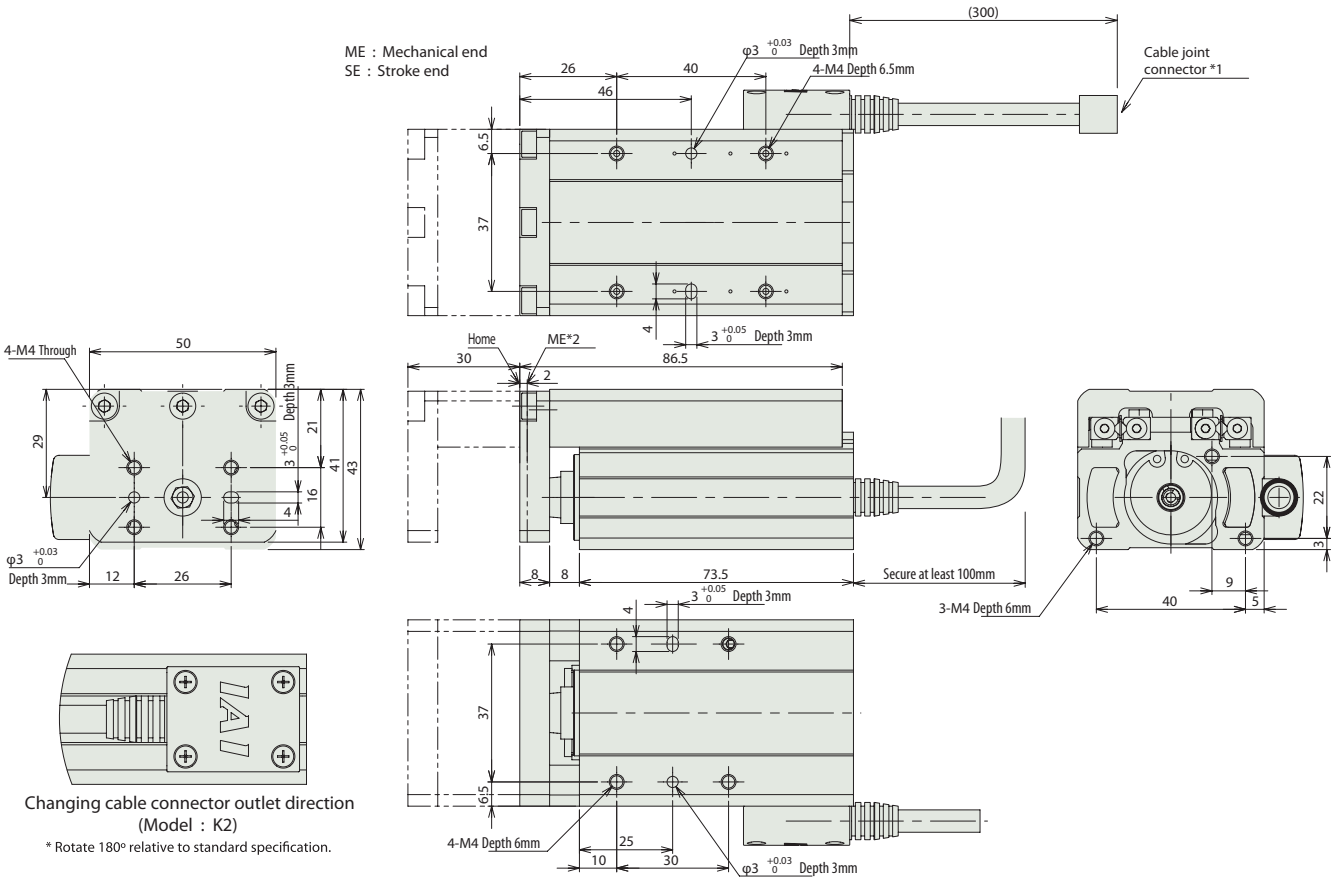
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P54	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.52

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TW4N

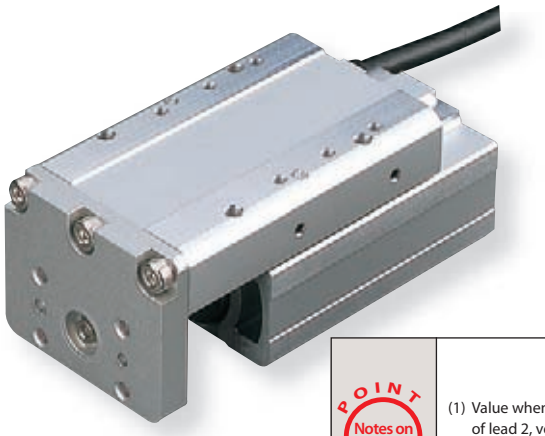
RoboCylinder Mini Table type Short Length Wide type Actuator Width 58mm
24V servo motor Ball screw specification/ Lead screw specification

■Model Description

RCA2 – TW4N – I – 20 – □ – 30 – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use).
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TW4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-TW4N-I-20-4-30-①-②-③			4	3	0.75	50.7		
RCA2-TW4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-TW4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-TW4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-TW4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead	Stroke 30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)		Ma : 9.9 N m Mb : 9.9 N m Mc : 12.2 N m
Ambient operating temperature, humidity		0 to 40 °C, 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.)

Options

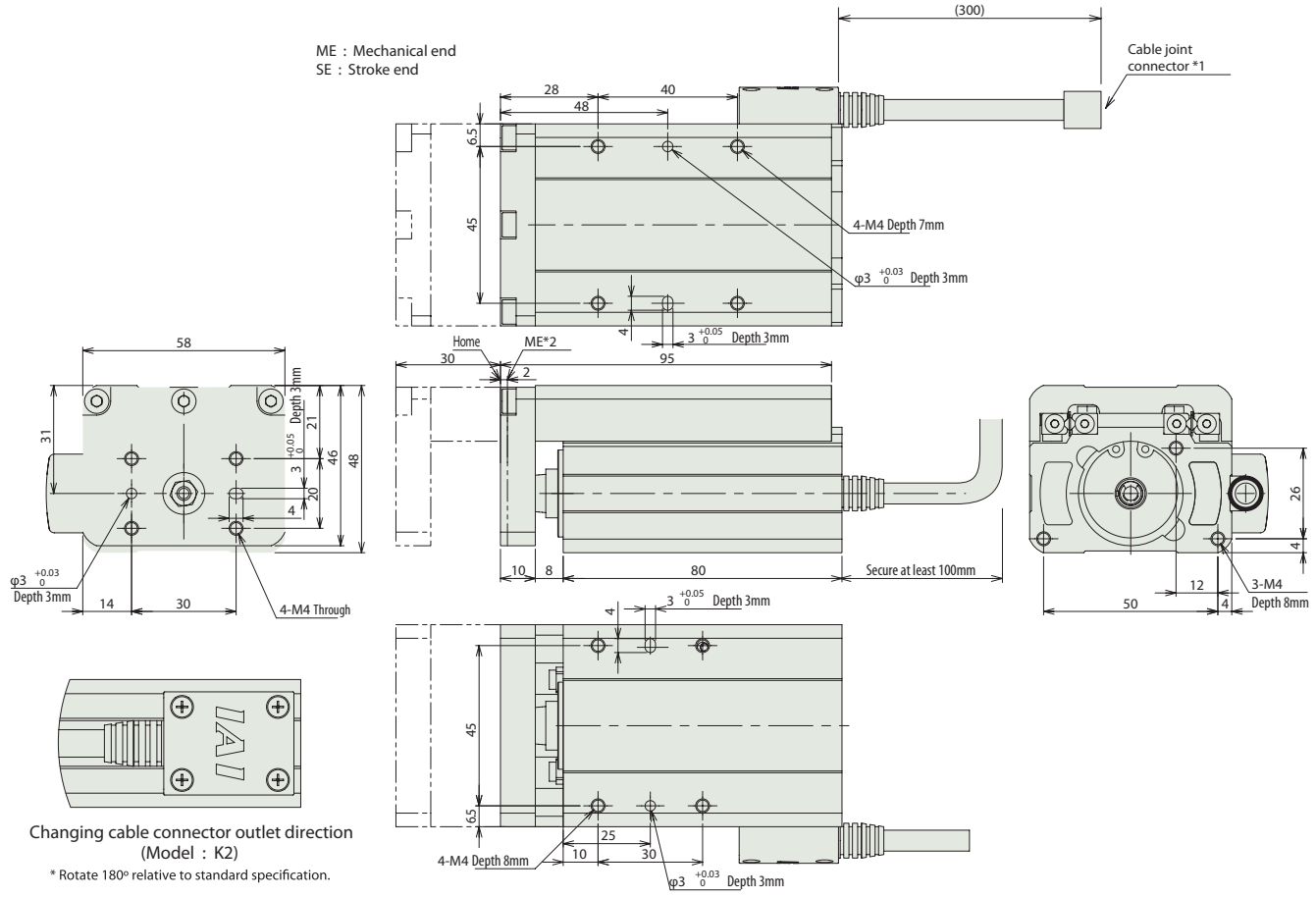
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P56	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.65

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TF3N

RoboCylinder Mini Table type Short Length Flat type Actuator Width 61mm
24V servo motor Lead screw specification

■Model Description

RCA2 — TF3N — I — 10 — □ — 30 — □ — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	4S: Lead screw 4mm 2S: Lead screw 2mm 1S: Lead screw 1mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) The payload is the value when operated at 0.2G acceleration.
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TF3N-I-10-4S-30-①-②-③	10	Lead screw	4	0.25	0.125	25.1	±0.05	30 (Fixed)
RCA2-TF3N-I-10-2S-30-①-②-③			2	0.5	0.25	50.3		
RCA2-TF3N-I-10-1S-30-①-②-③			1	1	0.5	100.5		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Lead screw 4	200
Lead screw 2	100
Lead screw 1	50

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Lead screw, φ4mm, rolled C10
Backlash	0.3mm or less (initial value)
Frame	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma : 9.9 N m Mb : 9.9 N m Mc : 3.3 N m
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (no condensation)
Service life	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.

Options

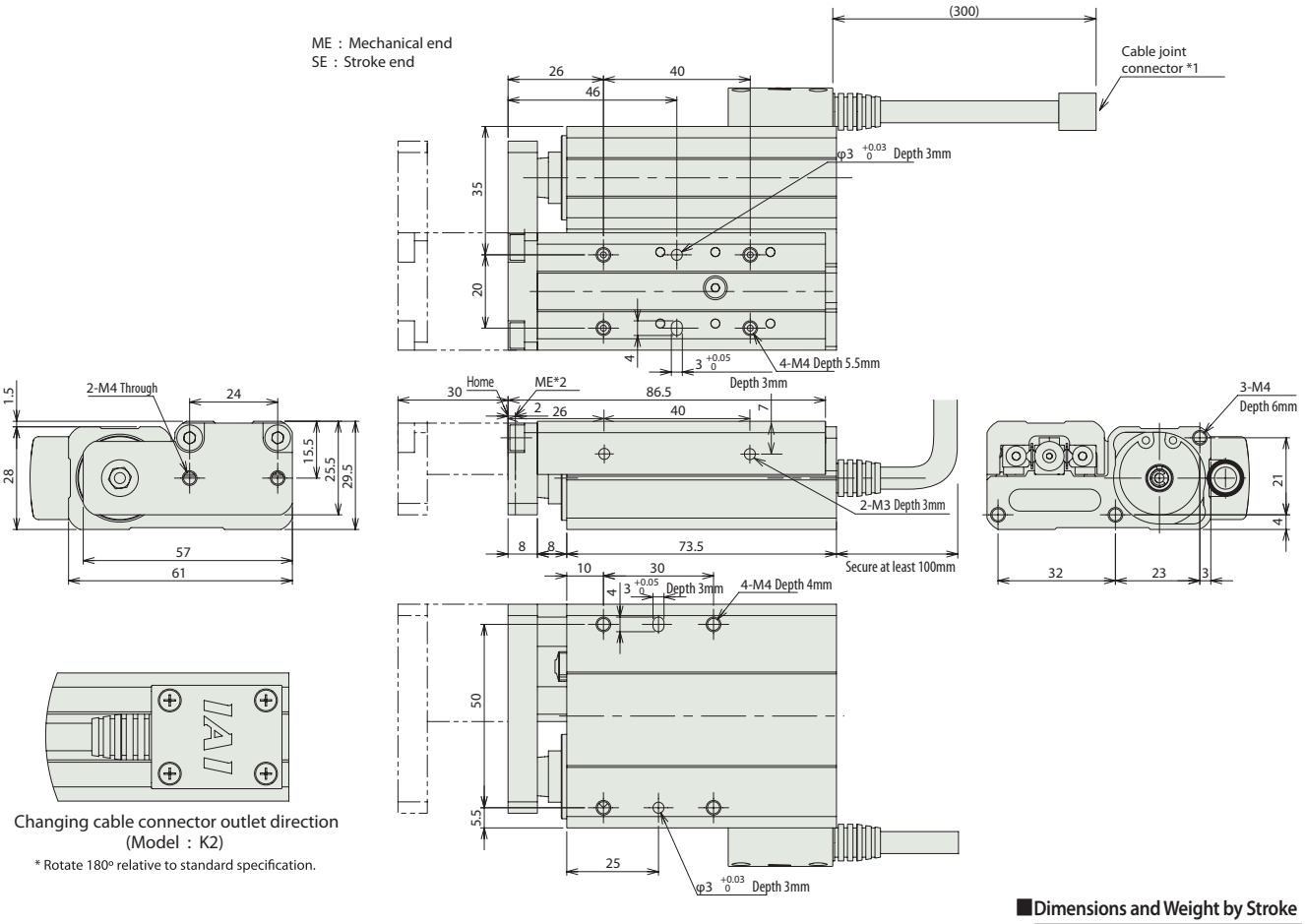
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P58	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction
(Model : K2)

* Rotate 180º relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.4

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCA2-TF4N

RoboCylinder Mini Table type Short Length Flat type Actuator Width 71mm
24V servo motor Lead screw specification

■Model Description

RCA2 — TF4N — I — 20 — □ — 30 — □ — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20: Servo Motor 20W	6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm	30: 30mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) Value when operated with payload acceleration of 0.3G (or 0.2G in the case of lead 2, vertical use).
Acceleration limit is value indicated above.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TF4N-I-20-6-30-①-②-③	20	Ball screw	6	2	0.5	33.8	±0.02	30 (Fixed)
RCA2-TF4N-I-20-4-30-①-②-③			4	3	0.75)	50.7		
RCA2-TF4N-I-20-2-30-①-②-③			2	6	1.5	101.5		
RCA2-TF4N-I-20-6S-30-①-②-③	20	Lead screw	6	0.25	0.125	19.9	±0.05	30 (Fixed)
RCA2-TF4N-I-20-4S-30-①-②-③			4	0.5	0.25	29.8		
RCA2-TF4N-I-20-2S-30-①-②-③			2	1	0.5	59.7		

Legend ① Compatible Controllers ② Cable length ③ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
Ball screw 6	270 <220>
Ball screw 4	200
Ball screw 2	100
Lead screw 6	220
Lead screw 4	200
Lead screw 2	100

*< > Indicates Vertical Use (Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item		Description
Drive System		Ball screw/ lead screw, φ6mm, rolled C10
Backlash		Ball screw: 0.1mm or less/ Lead screw: 0.3mm or less
Frame		Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)		Ma : 9.9 N m Mb : 9.9 N m Mc : 3.3 N m
Ambient operating temperature, humidity		0 to 40 °C, 85% RH or less (no condensation)
Service life	Ball screw	5,000km
	Lead screw	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles

(*1) For cases when the guide service life has been set to 5,000km.

Options

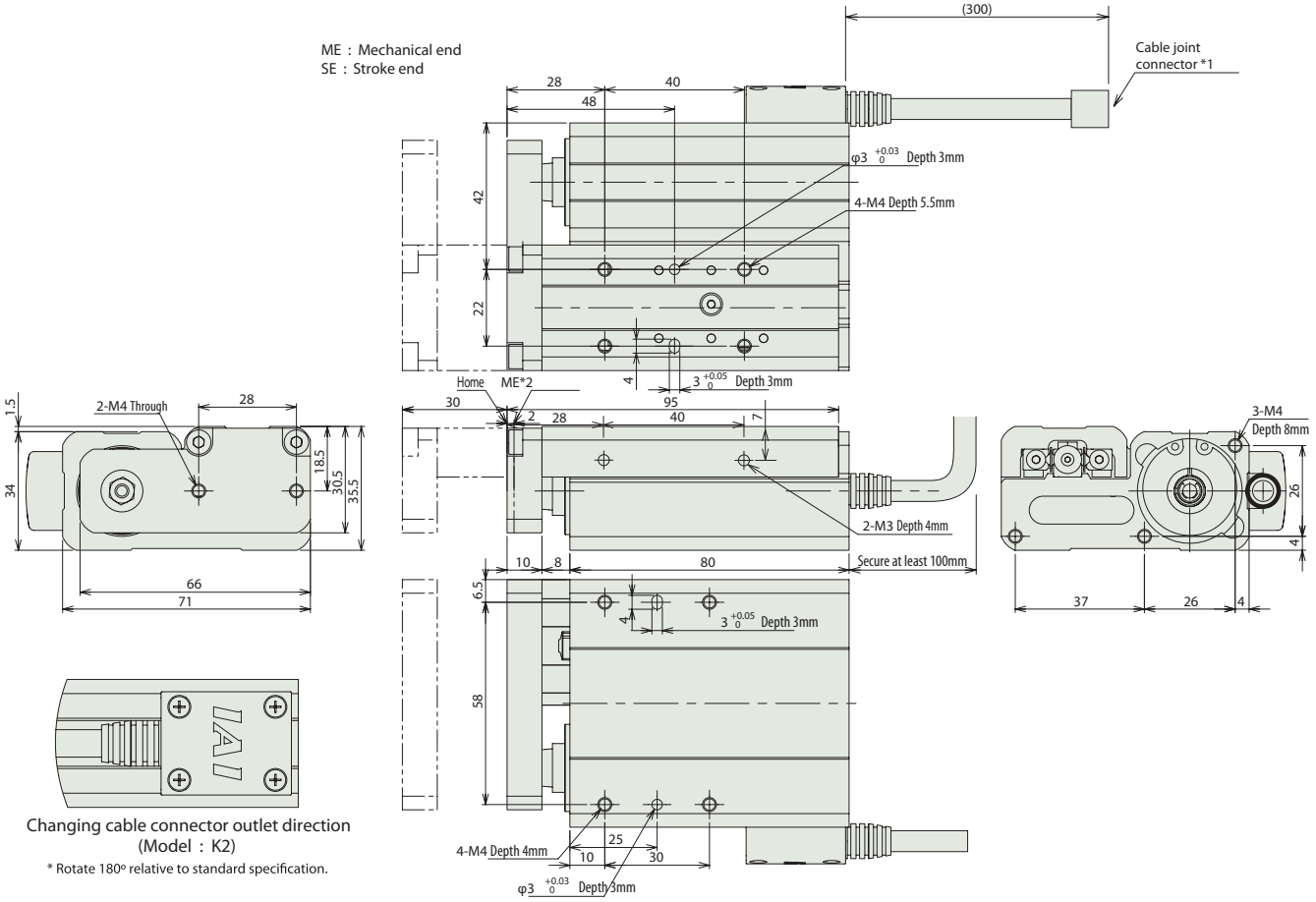
Title	Option code	See page	
Change the cable connector outlet direction	**K2**	→P60	
Power-saving feature	**LA**	→P109	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 Connect the motor and encoder cables. See page 113 for cable details.
*2 During home return, be careful to avoid interference from peripheral objects because the slider travels until the mechanical end.



Changing cable connector outlet direction
(Model : K2)
* Rotate 180° relative to standard specification.

Dimensions and Weight by Stroke

Stroke	30
Mass (kg)	0.6

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-20I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary.	3 points	DC24V	See P109.		→P101
		ASEP-CW-20I-NP-2-0						
Positioner type		ACON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple Absolute unit cannot be used.	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

Option

PSEP/ASEP dedicated teaching panel

Features This is a data input device with a touch panel that uses a dialogue menu screen that makes it easy to use even for first-time users. Enables operation adjustment for movements, etc. to front end, rear end, middle position, speed, push force, etc. settings and jog/inching/command position.

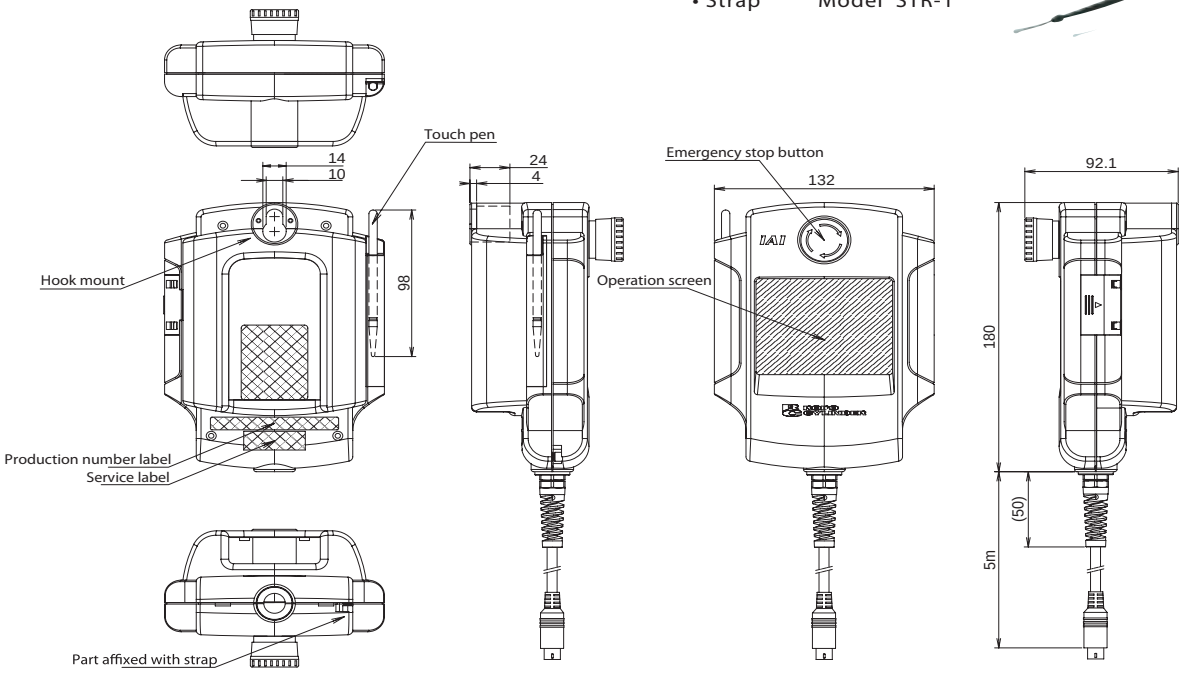
Model / Specifications

Item	Description			
Model (*1)	**CON-PT-M-ENG**	**CON-PD-M-ENG**	**CON-PG-M-S-ENG**	
Type	Standard type	Deadman switch type	Safety category type	
Applicable controllers	PSEP/PCON/RPCON ASEP/ACON/RACON SCON/ERC2 (*2)			
3-position deadman switch	-	o	o	
Functions	Position data input/Editing Movement function (set position movement, jog function, inching function) Output signal test Editing parameters Switch language (Japanese to English)			
Display	With 3-color LED backlight			
Ambient operating temperature, humidity	0 to 50°C, 20 to 85%RH (but no condensation)			
Environmental resistance	IP40			
Weight (5m cable included)	ca. 750g	ca. 780g	ca. 780g	
Standard accessories	• Touch pen	• Touch pen	• Teaching pendant adapter (model RCB-LB-TG) • Dummy plug (model DP-4) • Controller conversion cable (model CB-CON-LB005) • Touch pen	

(*1) Language can be changed from japanese to english by customer.
(*2) Integrated ERC2 controller which does not have „4904“ engraving on serial number sticker is not applicable.

NOTE
It is not possible to use CON type controller (PCON/RPCON/ACON/RACON/SCON/ERC2) and SEP type controller on the same link simultaneously.

Name of each part / Outer dimensions



Option

• Strap Model STR-1

RCP3-TA3C

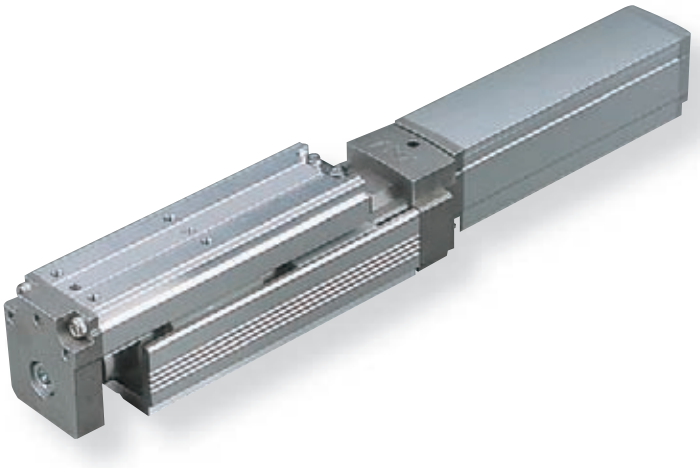
RoboCylinder Mini Table type Motor Unit Coupling type Actuator Width 36mm Pulse Motor Ball screw specification

■Model Description

RCP3 – TA3C – I – 20P – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20□Size	6: 6mm 4: 4mm 2: 2mm	20:20mm ~ 100:100mm (set in steps every 10mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

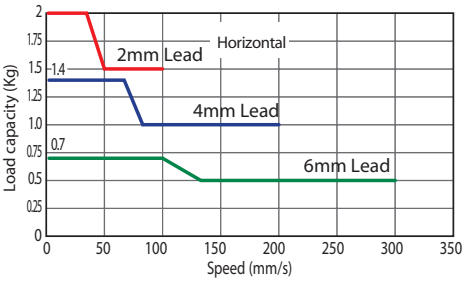


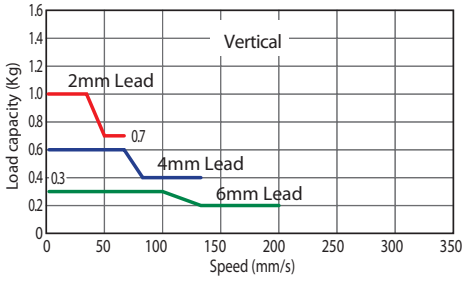
POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use). The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

■ Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

■Leads and Payloads

(*1) Please note that the maximum payload decreases as the speed increases.

Model	Feed screw	Lead (mm)	Maximum payload (*1) Horizontal (kg)	Maximum payload (*1) Vertical (kg)	Maximum pushing force (N) (*2)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-TA3C-I-20P-6-①-②-③-④	Ball screw	6	~0.7	~0.3	9	±0.02	20 to 100
RCP3-TA3C-I-20P-4-①-②-③-④		4	~1.4	~0.6	14		
RCP3-TA3C-I-20P-2-①-②-③-④		2	~2	~1	28		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

(*2) For a graph of the pushing force, see P97.

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (mm)
Ball screw 6	300 <200>
Ball screw 4	200 <133>
Ball screw 2	100 <67>

※< > Indicates Vertical Use

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*3)	Ma: 3.2 N·m Mb: 4.6 N·m Mc: 5.1 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*3) For case of 5,000km service life.

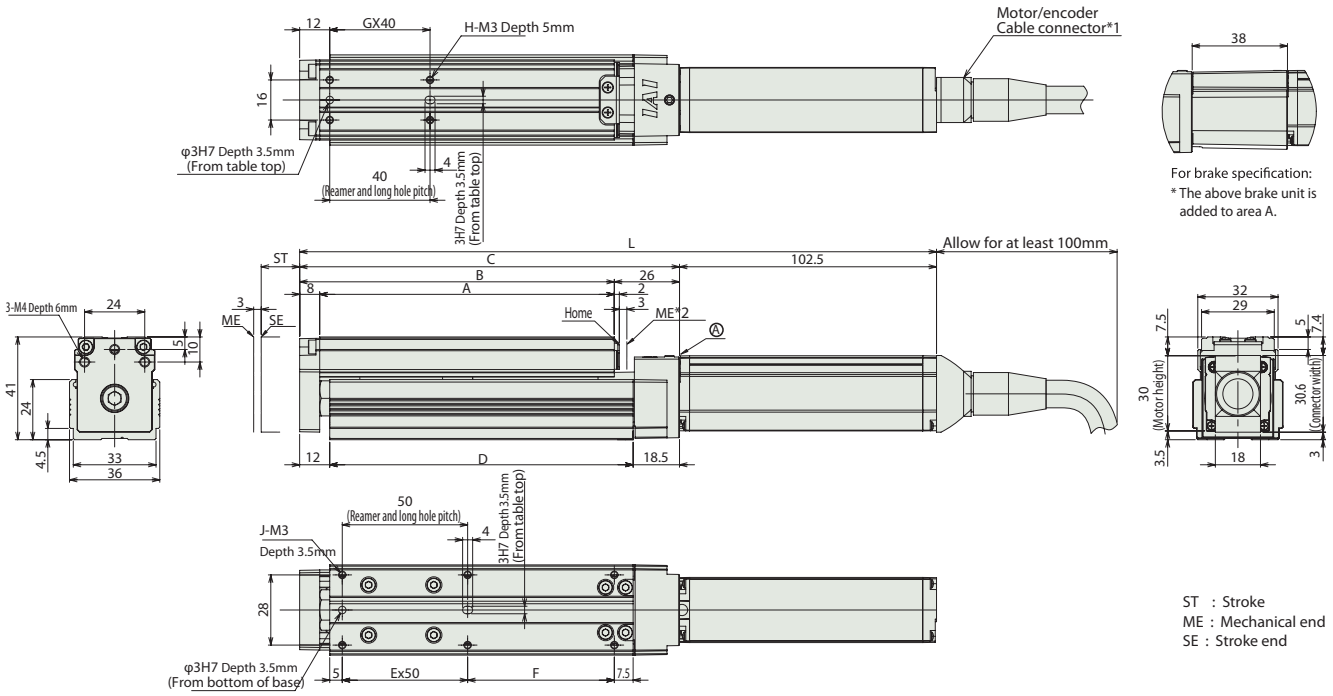
Options

Title	Option code	See page	
Brake	**B**	→P62	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



ST : Stroke
ME : Mechanical end
SE : Stroke end

*1 The motor-encoder cable is connected directly to the actuator motor cover. See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

■Dimensions and Weight by Stroke

* The attached brake adds 0.1kg of mass.

Stroke		20	30	40	50	60	70	80	90	100
L	No brake	224	234	244	254	264	274	284	294	304
	Brake-equipped	262	272	282	292	302	312	322	332	342
A		87.5	97.5	107.5	117.5	127.5	137.5	147.5	157.5	167.5
B		95.5	105.5	115.5	125.5	135.5	145.5	155.5	165.5	175.5
C		121.5	131.5	141.5	151.5	161.5	171.5	181.5	191.5	201.5
D		91	101	111	121	131	141	151	161	171
E		1	1	1	1	2	2	2	2	2
F		28.5	38.5	48.5	58.5	18.5	28.5	38.5	48.5	58.5
G		1	1	1	1	2	2	2	2	2
H		4	4	4	4	6	6	6	6	6
I		6	6	6	6	8	8	8	8	8
Mass (kg)		0.5	0.5	0.5	0.6	0.6	0.6	0.6	0.7	0.7

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports use of both the single solenoid and the double solenoid types Simple Absolute type makes return to home unnecessary	3 points	DC24V	See P109.		→P101
		PSEP-CW-20PI-NP-2-0						
Positioner type		PCON-□-20PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), return to home becomes the unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-TA4C

RoboCylinder Mini Table type Motor Unit Coupling type Actuator Width 40mm Pulse Motor Ball screw specification

■Model Description

RCP3 — TA4C — I — 28P — ☐ — ☐ — ☐ — ☐ — ☐ — ☐

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	28P: Pulse Motor 28☐Size	6 : 6mm 4 : 4mm 2 : 2mm	20:20mm ↓ 100:100mm (set in steps every 10mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

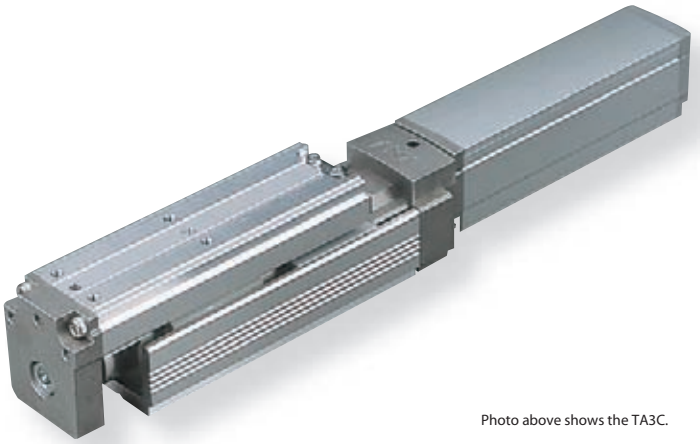


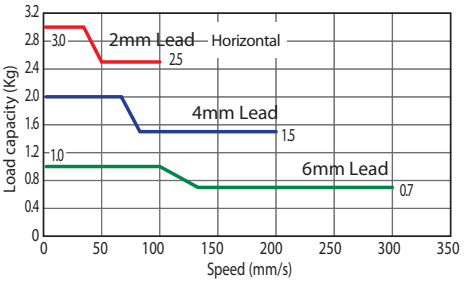
Photo above shows the TA3C.

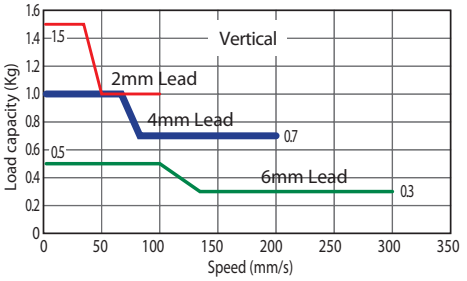
POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use). The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

■ Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

■Leads and Payloads

(*1) Please note that the maximum payload decreases as the speed increases.

Model	Feed screw	Lead (mm)	Maximum payload (*1) Horizontal (kg)	Maximum payload (*1) Vertical (kg)	Maximum pushing force (N) (*2)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-TA4C-I-28P-6- ①-②-③-④	Ball screw	6	~1	~0.5	15	±0.02	20 to 100 (every 10mm)
RCP3-TA4C-I-28P-4- ①-②-③-④		4	~2	~1	22		
RCP3-TA4C-I-28P-2- ①-②-③-④		2	~3	~1.5	44		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

(*2) For a graph of the pushing force, see P97.

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (mm)
Ball screw 6	300
Ball screw 4	200
Ball screw 2	100

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*3)	Ma: 4.2 N·m Mb: 6 N·m Mc: 8.2 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*3) For case of 5,000km service life.

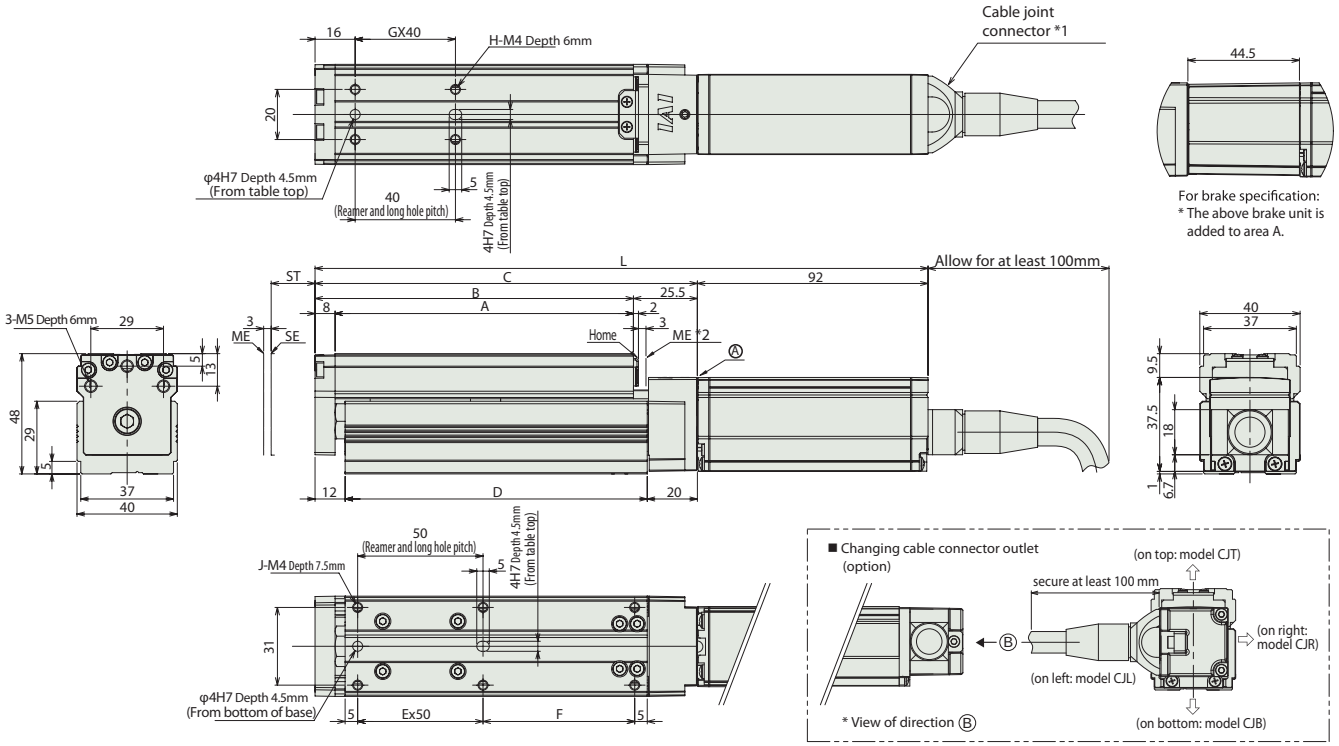
Options

Title	Option code	See page	
Brake	**B**	→P64	
Reversed-home specification	**NM**	–	
Cable connector outlet on top	**CJT**	→P64	
Cable connector outlet on right	**CJR**	→P64	
Cable connector outlet on left	**CJL**	→P64	
Cable connector outlet on bottom	**CJB**	→P64	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor-encoder cable is connected directly to the actuator motor cover. See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

* The attached brake adds 0.2kg of mass.

Stroke		20	30	40	50	60	70	80	90	100
L	No brake	214.5	224.5	234.5	244.5	254.5	264.5	274.5	284.5	294.5
	Brake-equipped	259	269	279	289	299	309	319	329	339
A		89	99	109	119	129	139	149	159	169
B		97	107	117	127	137	147	157	167	177
C		122.5	132.5	142.5	152.5	162.5	172.5	182.5	192.5	202.5
D		90.5	100.5	110.5	120.5	130.5	140.5	150.5	160.5	170.5
E		1	1	1	1	2	2	2	2	2
F		30.5	40.5	50.5	60.5	20.5	30.5	40.5	50.5	60.5
G		1	1	1	1	2	2	2	2	2
H		4	4	4	4	6	6	6	6	6
I		6	6	6	6	8	8	8	8	8
Mass (kg)		0.7	0.7	0.7	0.8	0.8	0.9	0.9	0.9	0.9

Compatible Controllers

RCP3 Compact ROBO Cylinder Table type. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-28PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports use of both the single solenoid and the double solenoid types Simple Absolute type makes return to home unnecessary	3 points	DC24V	See P109		→P101
		PSEP-CW-28PI-NP-2-0						
Positioner type		PCON-□-28PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), return to home becomes the unnecessary.	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-28PI-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCA2-TA4C

RoboCylinder Mini Table type Motor Unit Coupling type Actuator Width 40mm 24V servo motor Ball screw specification

■Model Description

RCA2 – TA4C – I – 10 – [ ] – [ ] – [ ] – [ ] – [ ]

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10w	6: 6mm 4: 4mm 2: 2mm	20:20mm ↕ 100:100mm (set steps every 10mm)	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Cable Length	Following options Refer to below table

*See page 11 for details on the model descriptions.

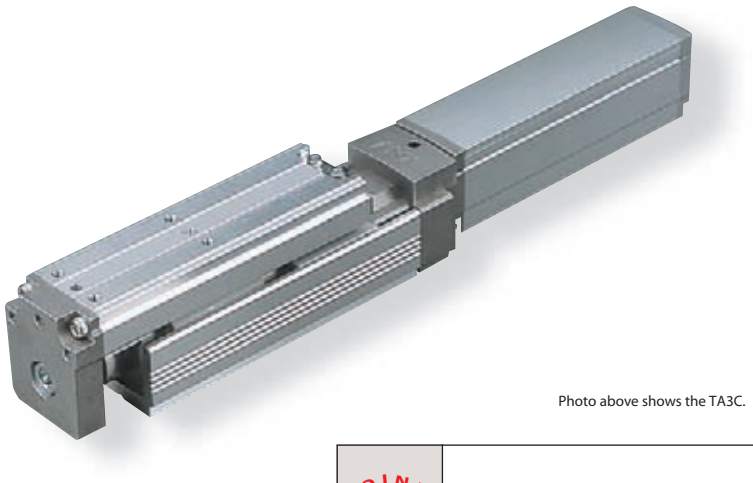


Photo above shows the TA3C.

POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use).
The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TA4C-I-10-6-①-②-③-④	10	Ball screw	6	1	0.5	28	±0.02	20 to 100 (every 10mm)
RCA2-TA4C-I-10-4-①-②-③-④			4	2	1	43		
RCA2-TA4C-I-10-2-①-②-③-④			2	3	1.5	85		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (every 10mm)
Ball screw 6	300
Ball screw 4	200
Ball screw 2	100

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 4.2 N·m Mb: 6 N·m Mc: 8.2 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

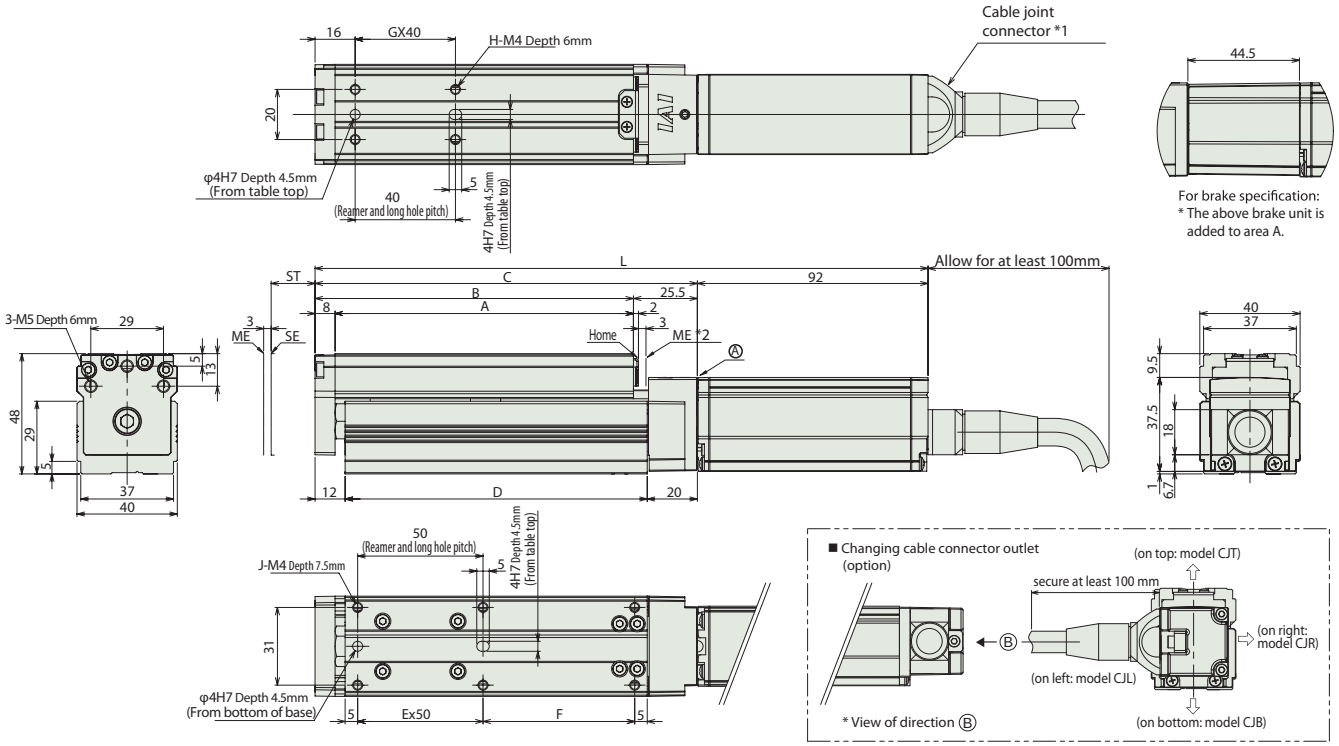
Options

Title	Option code	See page	
Brake	**B**	→P66	
Reversed-home specification	**NM**	–	
Cable connector outlet on top	**CJT**	→P66	
Cable connector outlet on right	**CJR**	→P66	
Cable connector outlet on left	**CJL**	→P66	
Cable connector outlet on bottom	**CJB**	→P66	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor-encoder cable is connected directly to the actuator motor cover. See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

ST : Stroke
ME : Mechanical end
SE : Stroke end

■Dimensions and Weight by Stroke

* The attached brake adds 0.2kg of mass.

Stroke		20	30	40	50	60	70	80	90	100
L	No brake	214.5	224.5	234.5	244.5	254.5	264.5	274.5	284.5	294.5
	Brake-equipped	259	269	279	289	299	309	319	329	339
A		89	99	109	119	129	139	149	159	169
B		97	107	117	127	137	147	157	167	177
C		122.5	132.5	142.5	152.5	162.5	172.5	182.5	192.5	202.5
D		90.5	100.5	110.5	120.5	130.5	140.5	150.5	160.5	170.5
E		1	1	1	1	2	2	2	2	2
F		30.5	40.5	50.5	60.5	20.5	30.5	40.5	50.5	60.5
G		1	1	1	1	2	2	2	2	2
H		4	4	4	4	6	6	6	6	6
I		6	6	6	6	8	8	8	8	8
Mass (kg)		0.8	0.8	0.8	0.9	0.9	0.9	1.0	1.0	1.0

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary	3 points	DC24V	See P109		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), return to home becomes the unnecessary	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes Simple absolute unit cannot be used	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCP3-TA3R

RoboCylinder Mini Table type Motor Unit Reversing type Actuator Width 72mm Pulse Motor Ball screw specification

■Model Description

RCP3 — TA3R — I — 20P — ☐ — ☐ — ☐ — ☐ — ☐

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
RCP3	TA3R	I: Incremental specification * Model number is "I" when used with simple absolute unit.	20P: Pulse Motor 20☐Size	6: 6mm 4: 4mm 2: 2mm	20: 20mm ↓ 100: 100mm (every 20mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

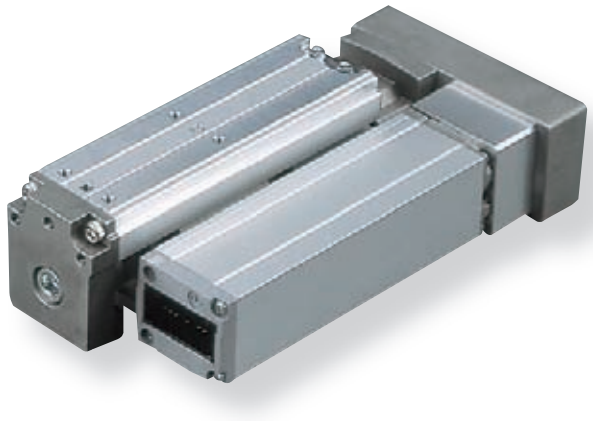


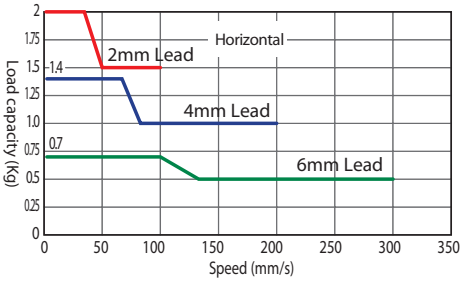
Photo above shows specification with motor reversing on left.

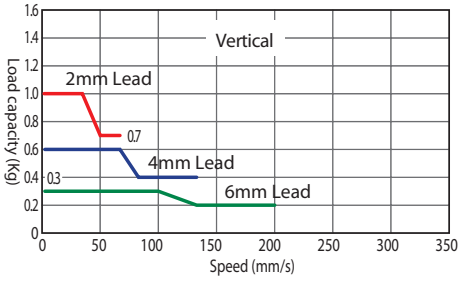
POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use).
The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases. Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

■Leads and Payloads

(*1) Please note that the maximum payload decreases as the speed increases.

Model	Feed screw	Lead (mm)	Maximum payload (*1) Horizontal (kg)	Maximum payload (*1) Vertical (kg)	Maximum pushing force N (*2)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-TA3R-I-20P-6-①-②-③-④	Ball screw	6	~0.7	~0.3	9	±0.02	20 to 100 (every 10mm)
RCP3-TA3R-I-20P-4-①-②-③-④		4	~1.4	~0.6	14		
RCP3-TA3R-I-20P-2-①-②-③-④		2	~2	~1	28		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

(*2) For a graph of the pushing force, see P97.

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (every10mm)
Ball screw 6	300 <200>
Ball screw 4	200 <133>
Ball screw 2	100 <167>

* < > Indicates Vertical Use

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*3)	Ma: 3.2 N·m Mb: 4.6 N·m Mc: 5.1 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*3) For case of 5,000km service life.

Options

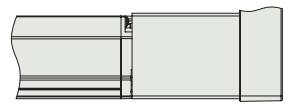
Title	Option code	See page	
Brake	**B**	→P68	
Specification with motor reversing on left	**ML**	–	
Specification with motor reversing on right	**MR**	–	
Reversed-home specification	**NM**	–	

Dimensional Drawings

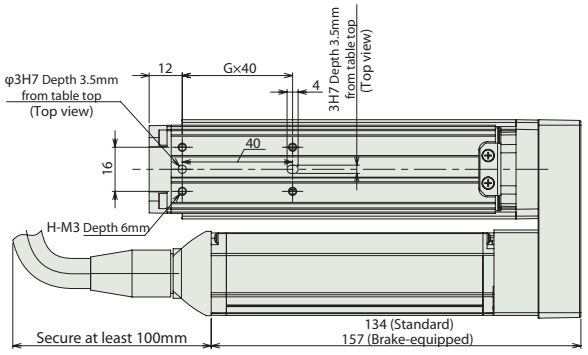
CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

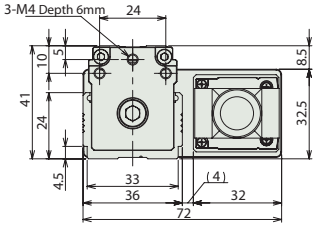
* The drawing below shows the specification with motor reversing on left.

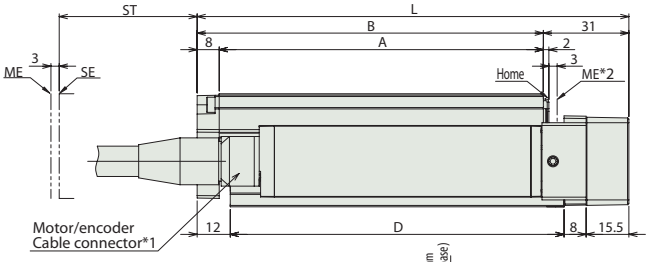


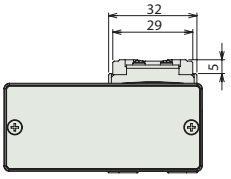
With brake:
(see drawing on the right for dimensions)

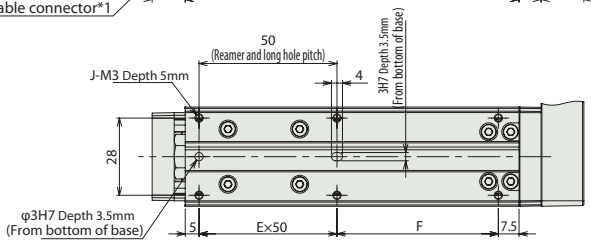


The offset standard position of Ma and Mb moment is the same as TA3C (P62).









ST : Stroke
ME : Mechanical end
SE : Stroke end

*1 The motor-encoder cable is connected directly to the actuator motor cover.
See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

■Dimensions and Weight by Stroke

* The attached brake adds 0.1kg of mass.

Stroke	20	30	40	50	60	70	80	90	
L	126.5	136.5	146.5	156.5	166.5	176.5	186.5	196.5	206.5
A	87.5	97.5	107.5	117.5	127.5	137.5	147.5	157.5	
B	95.5	105.5	115.5	125.5	135.5	145.5	155.5	165.5	175.5
D	91	101	111	121	131	141	151	161	
E	1	1	1	1	2	2	2	2	2
F	28.5	38.5	48.5	58.5	18.5	28.5	38.5	48.5	
G	1	1	1	1	2	2	2	2	2
H	4	4	4	4	6	6	6	6	6
J	6	6	6	6	8	8	8	8	8
Mass (kg)	0.5	0.6	0.6	0.6	0.6	0.7	0.7	0.7	0.7

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-20I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary	3 points	DC24V	See P109		→P101
		PSEP-CW-20I-NP-2-0						
Positioner type		PCON-□-20I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-20I-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCP3-TA4R

RoboCylinder Mini Table type Motor Unit Reversing type Actuator Width 81mm Pulse Motor Ball screw specification

■Model Description

RCP3 — TA4R — I — 28P — ☐ — ☐ — ☐ — ☐ — ☐ — ☐

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	28P: Pulse Motor 28☐Size	6: 6mm 4: 4mm 2: 2mm	20: 20mm ↕ 100: 100mm (every 20mm)	P1: PCON RPCON PSEL P3: PSEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

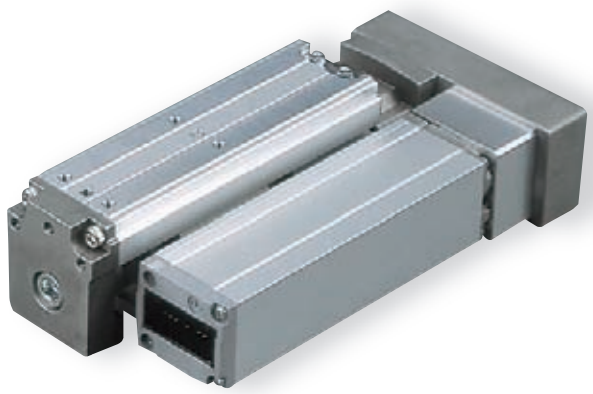


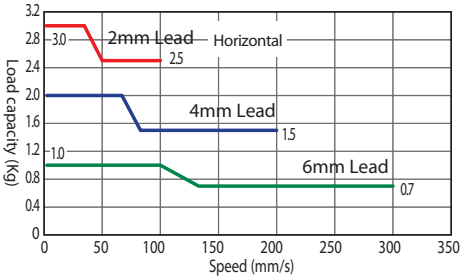
Photo above shows specification with TA3R motor reversing on left.

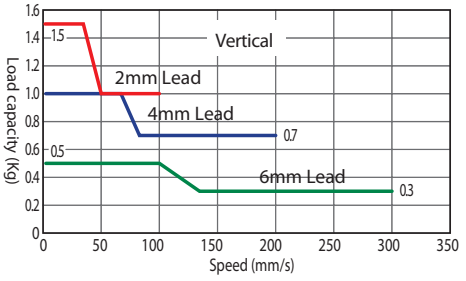
POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use).
The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

■Correlation Diagrams of Speed and Load Capacity

With the RCP3 series, due to the characteristics of the pulse motor, load capacity decreases as the speed increases.Use the chart below to confirm that the desired speed and load capacity requirements are met.





Actuator Specification Table

■Leads and Payloads

(*1) Please note that the maximum payload decreases as the speed increases.

Model	Feed screw	Lead (mm)	Maximum payload (*1) Horizontal (kg)	Maximum payload (*1) Vertical (kg)	Maximum pushing force N (*2)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-TA4R-I-28P-6-①-②-③-④	Ball screw	6	~1	~0.5	15	±0.02	20 to 100 (every 10mm)
RCP3-TA4R-I-28P-4-①-②-③-④		4	~2	~1	22		
RCP3-TA4R-I-28P-2-①-②-③-④		2	~3	~1.5	44		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

(*2) For a graph of the pushing force, see P97.

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (mm)
Ball screw 6	300
Ball screw 4	200
Ball screw 2	100

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCP3 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*3)	Ma: 4.2 N·m Mb: 6 N·m Mc: 8.2 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*3) For case of 5,000km service life.

Options

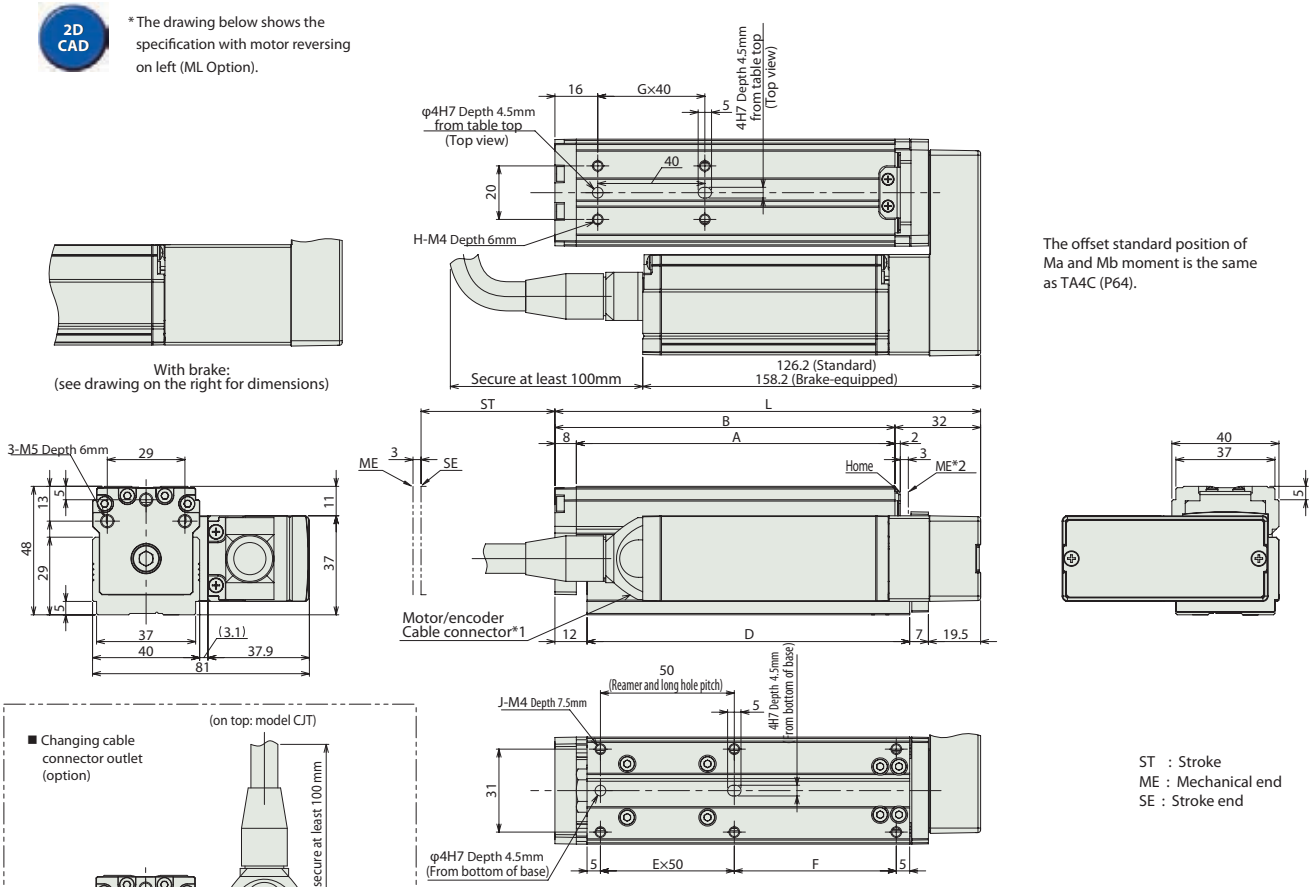
Title	Option code	See page	
Brake	**B**	→P70	
Specification with motor reversing on left	**ML**	–	
Specification with motor reversing on right	**MR**	–	
Reversed-home specification	**NM**	–	
Cable connector outlet on top	**CJT**	→P70	
Cable connector outlet on side	**CJO**	→P70	
Cable connector outlet on bottom	**CJB**	→P70	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*The drawing below shows the specification with motor reversing on left (ML Option).



The offset standard position of Ma and Mb moment is the same as TA4C (P64).

ST : Stroke
ME : Mechanical end
SE : Stroke end

*1 The motor-encoder cable is connected directly to the actuator motor cover. See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

■Dimensions and Weight by Stroke

*The attached brake adds 0.2kg of mass.

Stroke	20	30	40	50	60	70	80	90	100
L	129	139	149	159	169	179	189	199	209
A	89	99	109	119	129	139	149	159	169
B	97	107	117	127	137	147	157	167	177
D	90.5	100.5	110.5	120.5	130.5	140.5	150.5	160.5	170.5
E	1	1	1	1	2	2	2	2	2
F	30.5	40.5	50.5	60.5	20.5	30.5	40.5	50.5	60.5
G	1	1	1	1	2	2	2	2	2
H	4	4	4	4	6	6	6	6	6
J	6	6	6	6	8	8	8	8	8
Mass (kg)	0.7	0.8	0.8	0.8	0.9	0.9	0.9	1.0	1.0

Compatible Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		PSEP-C-28PI-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary	3 points	DC24V	See P109		→P101
		PSEP-CW-28PI-NP-2-0						
Positioner type		PCON-□-28PI-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	512 points				See the Robo-Cylinder general catalog.
Program type		PSEL-C-1-28P0I-NP-2-0	Programmable type Capable of operating up to 2 axes By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	1500 points				See the PSEL-C-ABU flyer.

(Note 1) PCON can be used with C/CG/CY/PL/PO/SE types. Also, ROBONET can be used.

RCA2-TA4R

RoboCylinder Mini Table type Motor Unit Reversing type Actuator Width 81mm 24V servo motor Ball screw specification

■Model Description

RCA2 – TA4R – I – 10 – □ – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification * Model number is "I" when used with simple absolute unit.	10: Servo Motor 10W	6: 6mm 4: 4mm 2: 2mm	20: 20mm ↓ 100: 100mm (every 20mm)	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

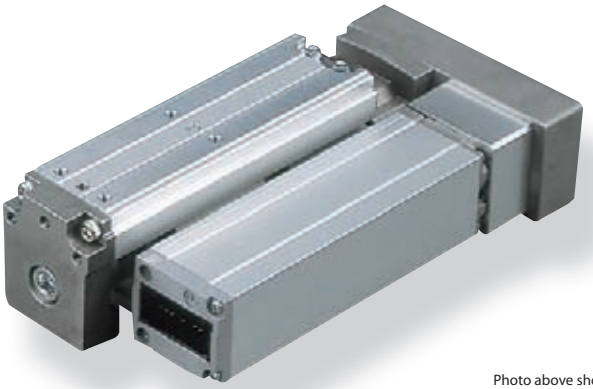


Photo above shows specification with TA3R motor reversing on left.

POINT Notes on selection

(1) The payload is the value when operated with acceleration of 0.3G (or 0.2G in the case of Lead 2 and vertical use).
The upper limit for acceleration is 0.3G (or 0.2G in the case of Lead 2 and vertical use).

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Positioning Repeatability (mm)	Stroke (mm)
RCA2-TA4R-I-10-6-①-②-③-④	10	Ball screw	6	1	0.5	28	±0.02	20 to 100 (set in 10mm increments)
RCA2-TA4R-I-10-4-①-②-③-④			4	2	1	43		
RCA2-TA4R-I-10-2-①-②-③-④			2	3	1.5	85		

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	20 to 100 (every 10mm)
Ball screw 6	300
Ball screw 4	200
Ball screw 2	100

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* Robot type cable comes as standard with the RCA2 actuator.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Ball screw φ6mm rolled C10
Backlash	0.1mm or less
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 4.2 N·m Mb: 6 N·m Mc: 8.2 N·m
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

Options

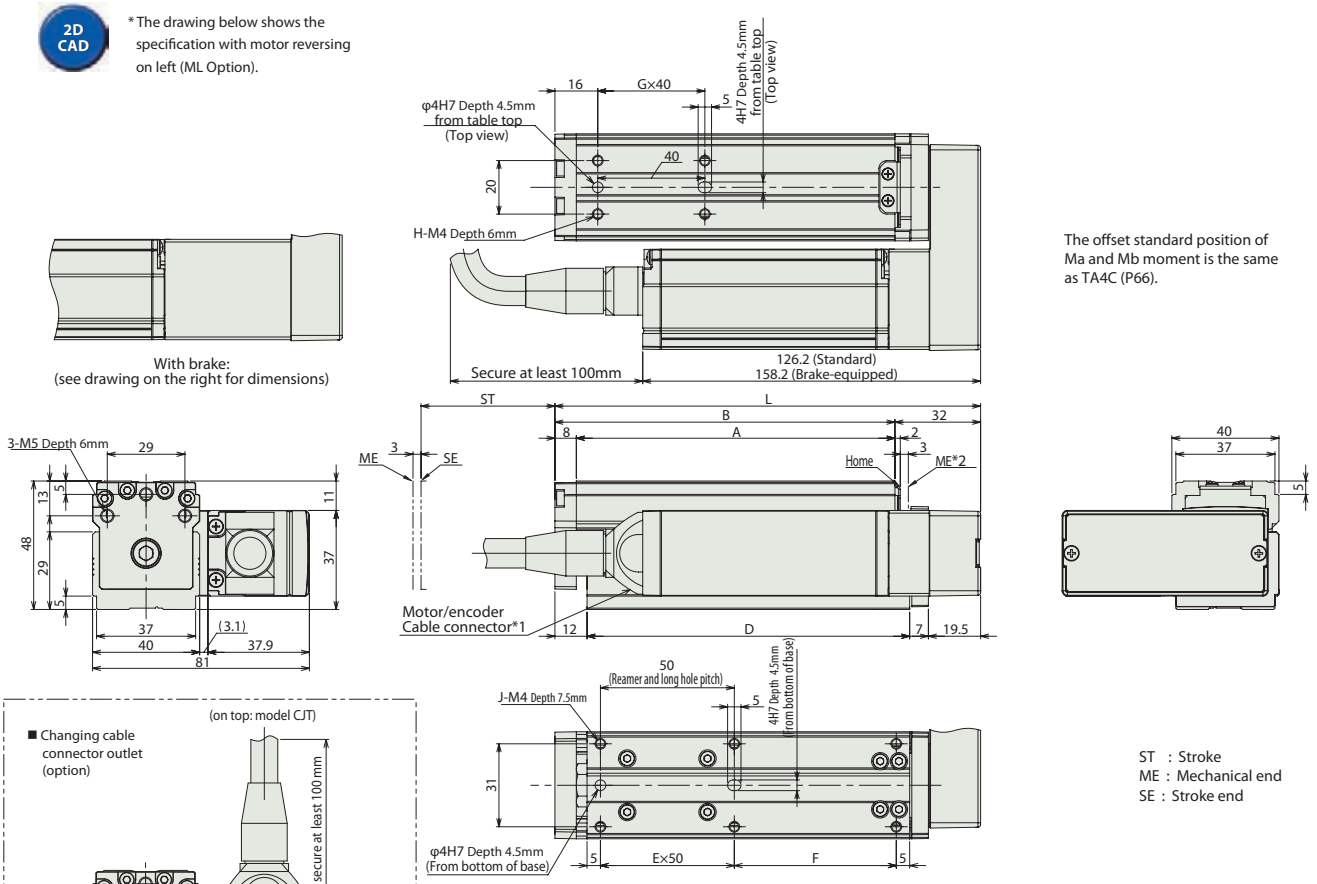
Title	Option code	See page	
Brake	**B**	→P72	
Specification with motor reversing on left	**ML**	–	
Specification with motor reversing on right	**MR**	–	
Reversed-home specification	**NM**	–	
Power-saving feature	**LA**	→P109	
Cable connector outlet on top	**CJT**	→P72	
Cable connector outlet on side	**CJO**	→P72	
Cable connector outlet on bottom	**CJB**	→P72	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*The drawing below shows the specification with motor reversing on left (ML Option).



The offset standard position of Ma and Mb moment is the same as TA4C (P66).

ST : Stroke
ME : Mechanical end
SE : Stroke end

*1 The motor-encoder cable is connected directly to the actuator motor cover. See page 113 for cable details.

*2 The slider moves to the mechanical end during home return. Pay attention to prevent contact between the slider and surrounding parts.

■Dimensions and Weight by Stroke

*The attached brake adds 0.2kg of mass.

Stroke	20	30	40	50	60	70	80	90	100
L	129	139	149	159	169	179	189	199	209
A	89	99	109	119	129	139	149	159	169
B	97	107	117	127	137	147	157	167	177
D	90.5	100.5	110.5	120.5	130.5	140.5	150.5	160.5	170.5
E	1	1	1	1	2	2	2	2	2
F	30.5	40.5	50.5	60.5	20.5	30.5	40.5	50.5	60.5
G	1	1	1	1	2	2	2	2	2
H	4	4	4	4	6	6	6	6	6
J	6	6	6	6	8	8	8	8	8
Mass (kg)	0.8	0.9	0.9	0.9	1.0	1.0	1.0	1.1	1.1

Compatible Controllers

RCA2 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types Simple Absolute type makes the return to home unnecessary	3 points	DC24V	See P109		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible By attaching a simple absolute unit (sold separately), the return to home becomes unnecessary	512 points				See the Robo-Cylinder general catalog
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

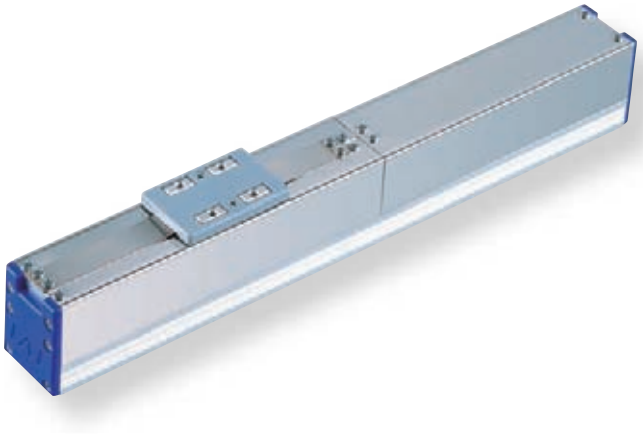
RCL-SA1L

RoboCylinder Mini Linear Motor type Micro Slider Slim type Actuator Width 20mm Linear motor

■Model Description

RCL	SA1L	I	2	N	40	☐	☐
Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
		I: Incremental specification	2: Linear motor 2W	N: No screw	40: 40mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■ Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)	
	Continuous operation (Duty is 100%)	Duty is 70% or less
0.1	0.5	0.5
0.3		
0.5	0.42	
1	0.25	0.32
1.5	0.18	0.24
2	0.15	0.2

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA1L-I-2-N-40-①-②	2	See chart above	–	2	10	2	±0.1	40 (Fixed)

Legend ① Compatible Controllers ② Cable length

■Stroke and Maximum Speed

Lead \ Stroke	40 (mm)
(no screw)	420

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.13 N·m Mb: 0.12 N·m Mc: 0.21 N·m
Overhung load length	50mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

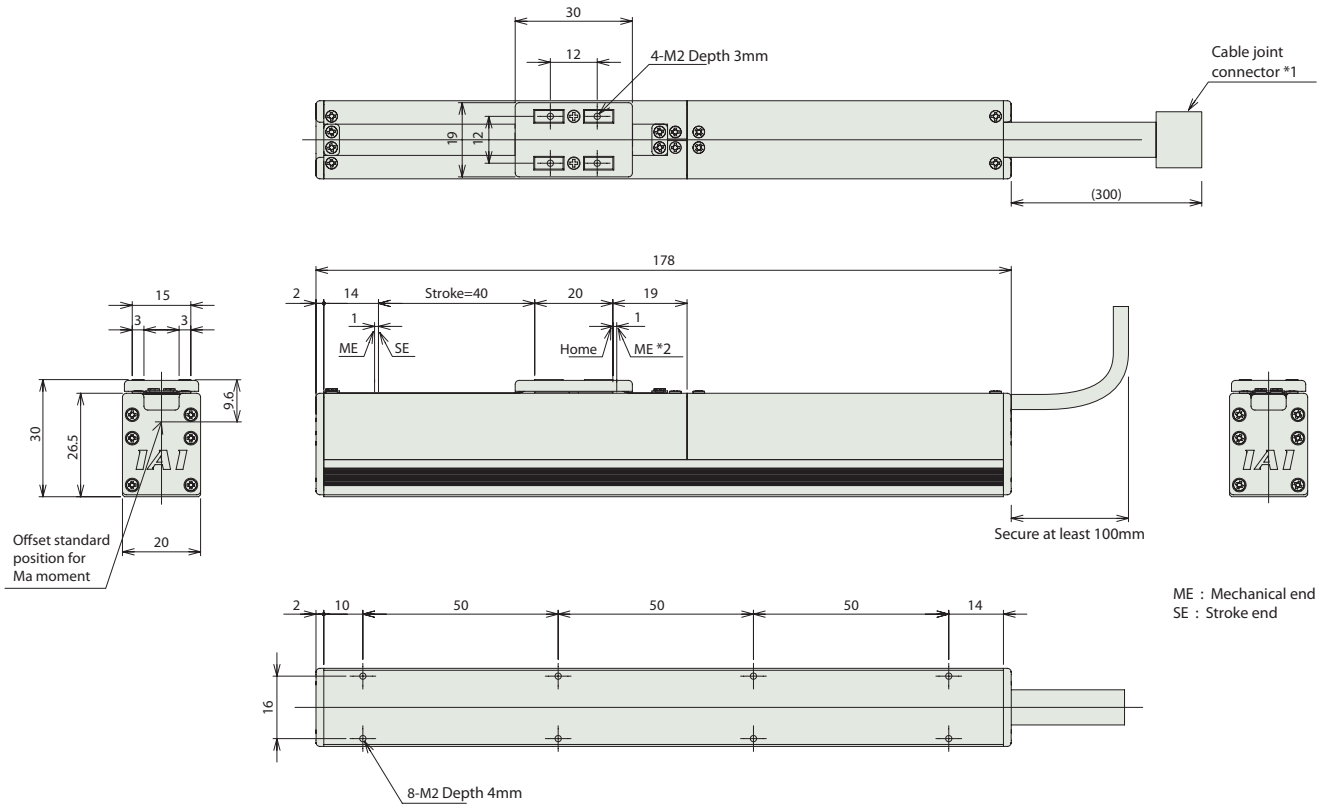
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 The motor and encoder cable are attached. Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.



■Dimensions and Weight by Stroke

Stroke	40
Mass (kg)	0.28

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-2I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW-2I-NP-2-0						
Positioner type		ACON-□-2I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-2I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SA2L

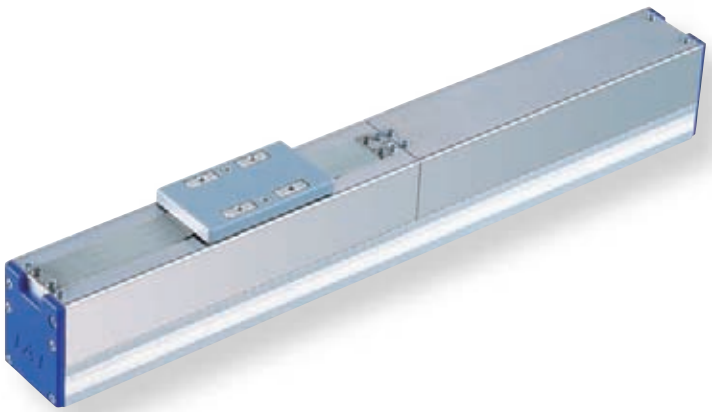
RoboCylinder Mini Linear Motor type Micro Slider Slim type Actuator Width 24mm Linear motor

■Model Description

RCL – SA2L – I – 5 – N – 48 – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
RCL	SA2L	I: Incremental specification	5: Linear motor 5W	N: No screw	48: 48mm	A1: ACON, RACON, ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation

*See page 11 for details on the model descriptions.



■ Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)	
	Continuous operation (Duty is 100%)	Duty is 70% or less
0.1	1	1
0.3		
0.5	0.85	
1	0.5	0.6
1.5	0.36	0.45
2	0.3	0.36

POINT Notes on selection

(1) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA2L-I-5-N-48-①-②	5	See chart above	–	4	18	2	±0.1	48 (Fixed)

Legend ① Compatible Controllers ② Cable length

■Stroke and Maximum Speed

Lead \ Stroke	48 (mm)
(no screw)	460

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.2 N·m Mb: 0.17 N·m Mc: 0.25 N·m
Overhung load length	60mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

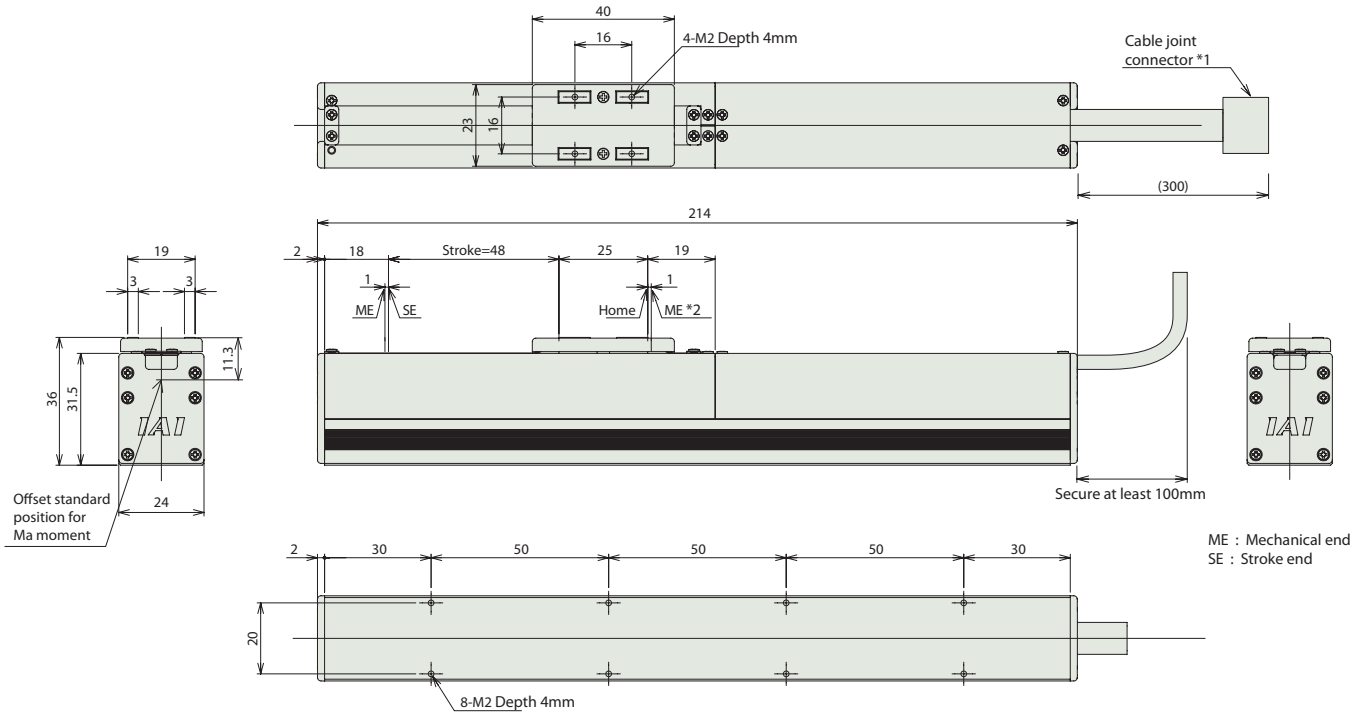
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.



■Dimensions and Weight by Stroke

Stroke	48
Mass (kg)	0.45

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-5I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW-5I-NP-2-0						
Positioner type		ACON-□-5I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-5I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SA3L

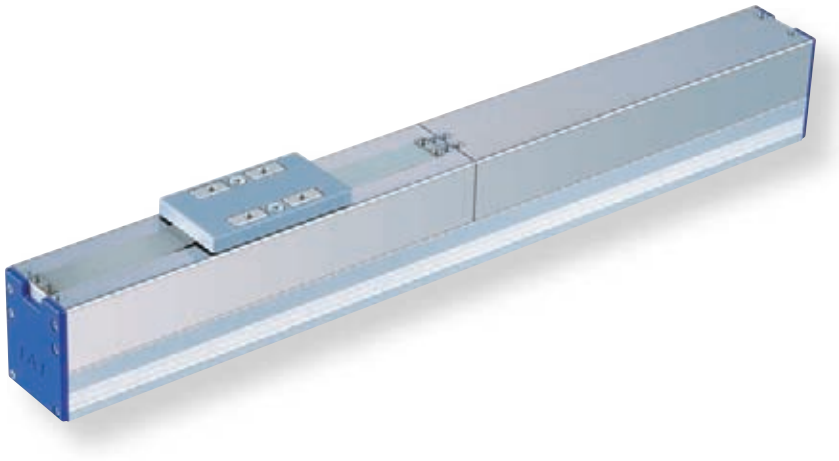
RoboCylinder Mini Linear Motor type Micro Slider Slim type Actuator Width 28mm Linear motor

■Model Description

RCL — SA3L — I — 10 — N — 64 — □ — □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
		I: Incremental specification	10: Linear motor 10 W	N: No screw	64: 64mm	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation

*See page 11 for details on the model descriptions.



■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)	
	Continuous operation (Duty is 100%)	Duty is 70% or less
0.1	2	2
0.3		
0.5	1.8	
1	1	1.2
1.5	0.65	0.8
2	0.5	0.6

POINT Notes on selection

(1) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.

The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA3L-I-10-N-64- ① - ②	10	See chart above	–	84	30	2	±0.1	64 (Fixed)

Legend ① Compatible Controllers ② Cable length

■Stroke and Maximum Speed

Lead \ Stroke	64 (mm)
(no screw)	600

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 1.22 N·m Mb: 1.08 N·m Mc: 0.34 N·m
Overhung load length	Ma direction: 120mm or less, Mb and Mc directions: 80mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

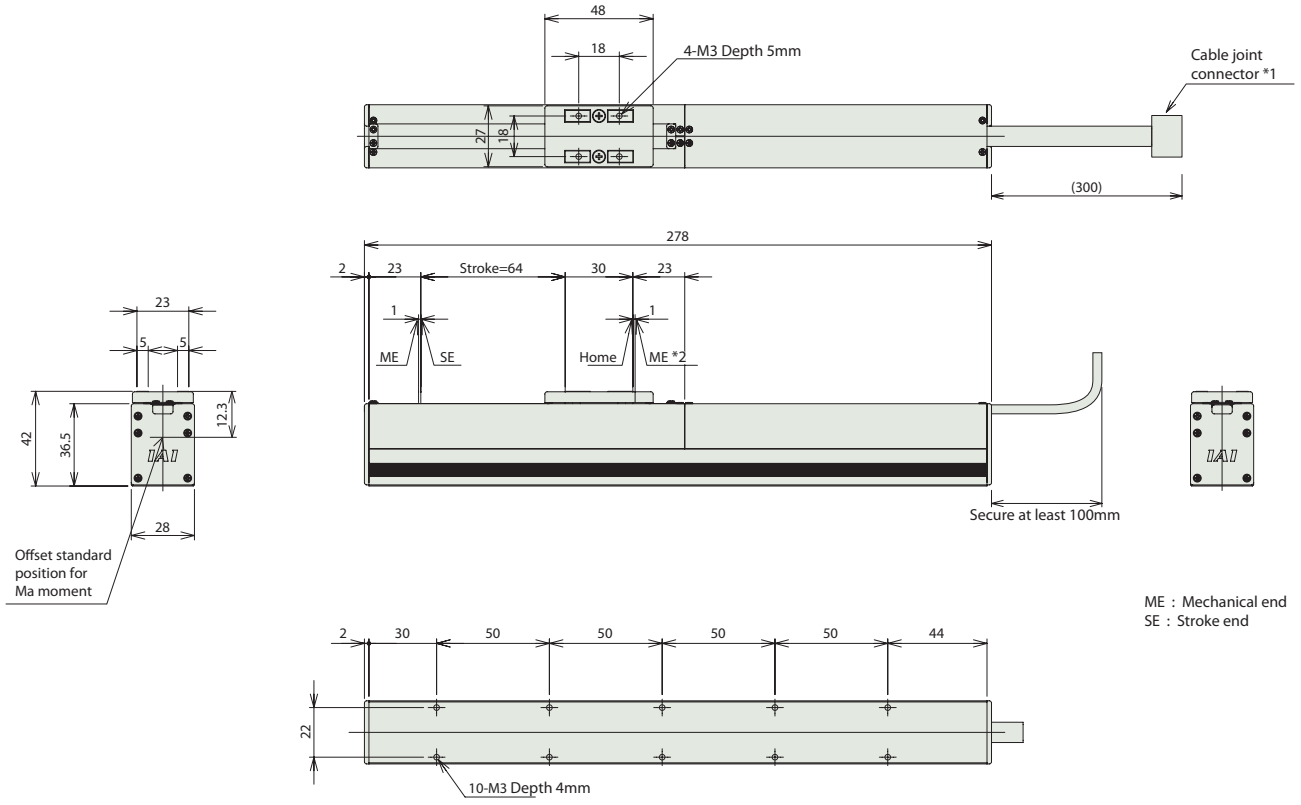
Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.



■Dimensions and Weight by Stroke

Stroke	64
Mass (kg)	0.82

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SA4L

RoboCylinder Mini Linear Motor type Single Slider Long Stroke type Actuator Width 40mm Linear motor

■Model Description

RCL – SA4L – I – 2 – N – [ ] – [ ] – [ ] – [ ] _ [ ]

- Series: RCL
- Type: SA4L
- Encoder type: I — I: Incremental specification
- Motor type: 2 — 2: Linear motor 2 W
- Lead: N — N: No screw
- Stroke: 30: 30 mm ~ 180: 180mm (30mm Setting for each pitch)
- Compatible Controllers: A1: ACON RACON ASEL A3: ASEP
- Cable length: N: None P: 1m S: 3m M: 5m X□□: Length Designation
- Option: NM: Reversed-home specification

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)
	Continuous operation (Duty is 100%)
0.1	0.8
0.3	
0.5	0.5
1	0.25
1.5	0.18
2	0.14

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA4L-I-2-N-①-②-③-④	2	See chart above	–	2.5	10	2	±0.1	30 to 180 (set in 30mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	30 to 180 (set in 30mm increments)
(no screw)	1200

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.2 N·m Mb: 0.17 N·m Mc: 0.25 N·m
Overhung load length	Ma direction: 60mm or less, Mb and Mc directions: 80mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

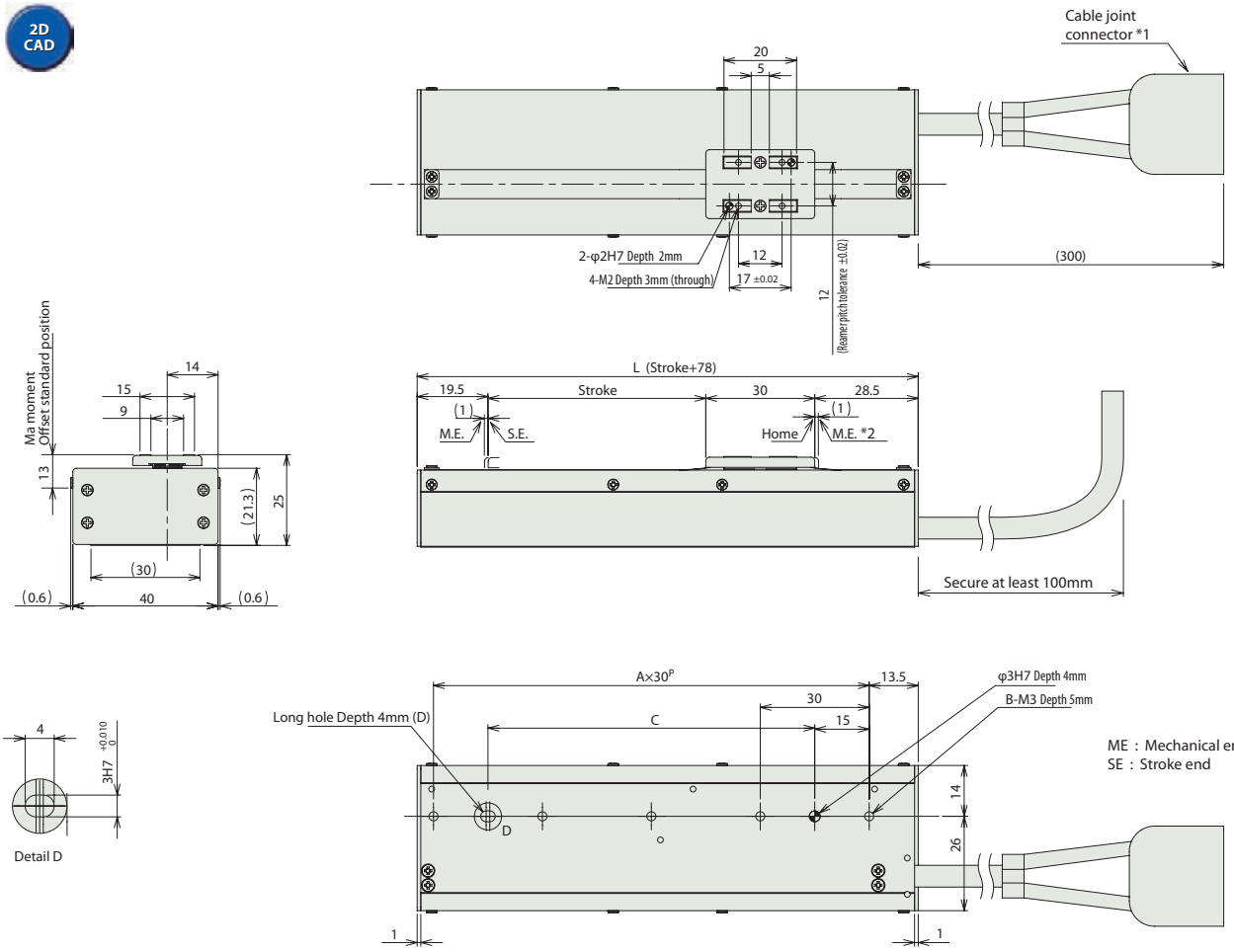
Options

Title	Option code	See page	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	30	60	90	120	150	180
L	108	138	168	198	228	258
A	3	4	5	6	7	8
B	4	5	6	7	8	9
C	60	90	120	150	180	210
Mass (kg)	0.21	0.25	0.29	0.32	0.36	0.4

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-2I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW-2I-NP-2-0						
Positioner type		ACON-□-2I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-2I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SM4L

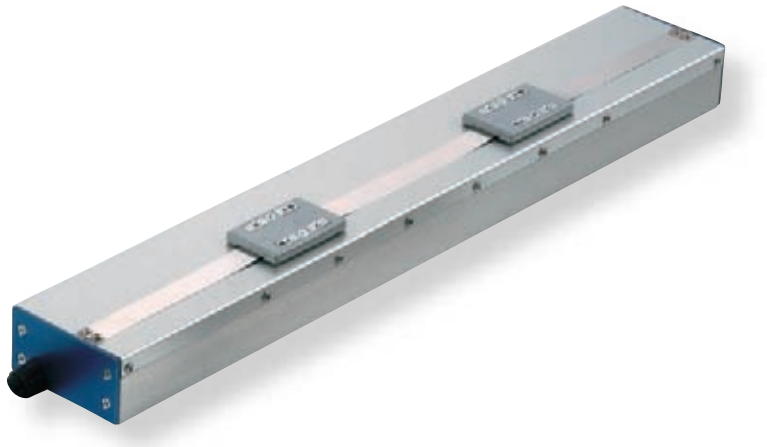
RoboCylinder Mini Linear Motor type Multi Slider Long Stroke type Actuator Width 40mm Linear motor

■Model Description

RCL – SM4L – I – 2 – N – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
—	—	I: Incremental specification	2: Linear motor 2W	N: No screw	30: 30 mm ~ 120: 120mm (30mm Setting for each pitch)	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)
	Continuous operation (Duty is 100%)
0.1	0.8
0.3	
0.5	0.5
1	0.25
1.5	0.18
2	0.14

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SM4L-I-2-N-①-②-③	2	See chart above	–	2.5	10	2	±0.1	30 to 120 (set in 30mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length

■Stroke and Maximum Speed

Lead \ Stroke	30 to 120 (set in 30mm increments)
(no screw)	1200

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

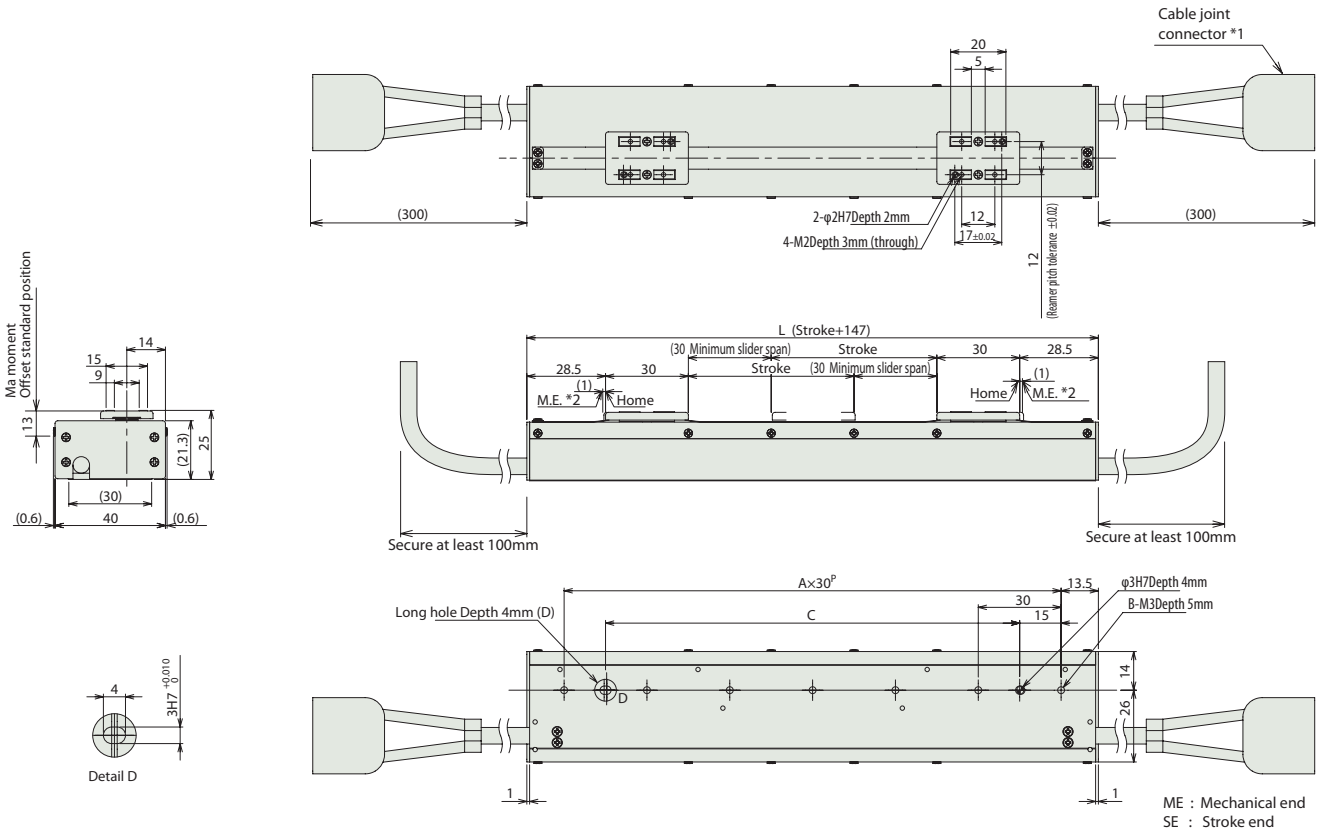
Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.2 N·m Mb: 0.17 N·m Mc: 0.25 N·m
Overhung load length	Ma direction: 60mm or less, Mb and Mc directions: 80mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	30	60	90	120
L	177	207	237	267
A	5	6	7	8
B	6	7	8	9
C	120	150	180	210
Mass (kg)	0.37	0.4	0.44	0.48

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-2I-NP-2-0 (Note 1)	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW -2I-NP-2-0 (Note 1)						
Positioner type		ACON-□-2I-NP-2-0 (Note 1) (Note 2)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-2-2I-NP-2-0 (Note 3)	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) Two controllers are needed when operating multi slider.
(Note 2) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.
(Note 3) If 2-axis controller is used, operation is possible with one controller even if multi slider is operated.

RCL-SA5L

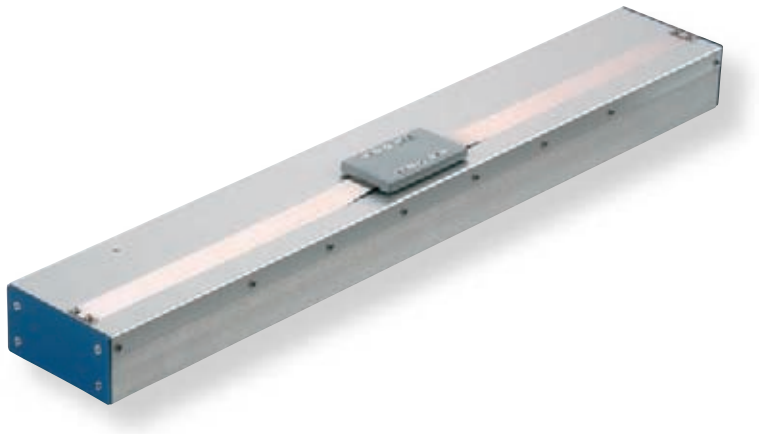
RoboCylinder Mini Linear Motor type Single Slider Long Stroke type Actuator Width 48mm Linear motor

■Model Description

RCL – SA5L – I – 5 – N – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Options
RCL	SA5L	I: Incremental specification	5: Linear motor 5W	N: No screw	36: 36 mm ~ 216: 216mm (36mm Setting for each pitch)	A1: ACON RACON ASEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	NM: Reversed-home specification

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)
	Continuous operation (Duty is 100%)
0.1	1.6
0.3	
0.5	1.0
1	0.5
1.5	0.35
2	0.25

Actuator Specification Table

■Leads and Payloads

Model	Motor output (W)	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instantaneous maximum thrust (G)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA5L-I-5-N-①-②-③-④	5	See chart above	–	5	18	2	±0.1	36 to 216 (set in 36mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	36 to 216 (set in 36mm increments)
(no screw)	1400

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.49 N·m Mb: 0.41 N·m Mc: 0.72 N·m
Overhung load length	Ma direction: 80mm or less, Mb and Mc directions: 100mm or less
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (no condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

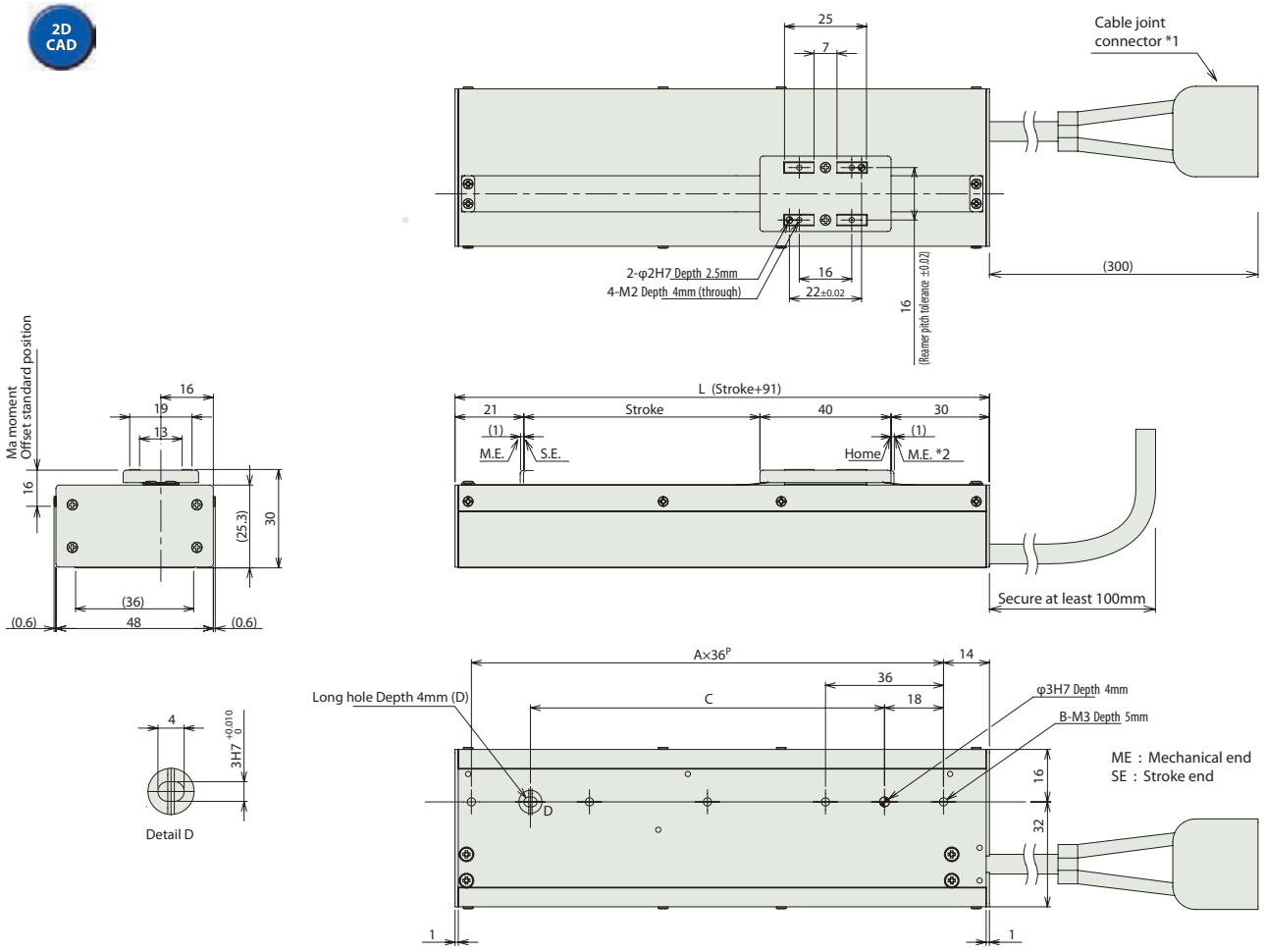
Options

Title	Option code	See page	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	36	72	108	144	180	216
L	127	163	199	235	271	307
A	3	4	5	6	7	8
B	4	5	6	7	8	9
C	72	108	144	180	216	252
Mass (kg)	0.35	0.42	0.48	0.55	0.62	0.68

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-5I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109		→P101
		ASEP-CW -5I-NP-2-0						
Positioner type		ACON-□-5I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-5I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SM5L

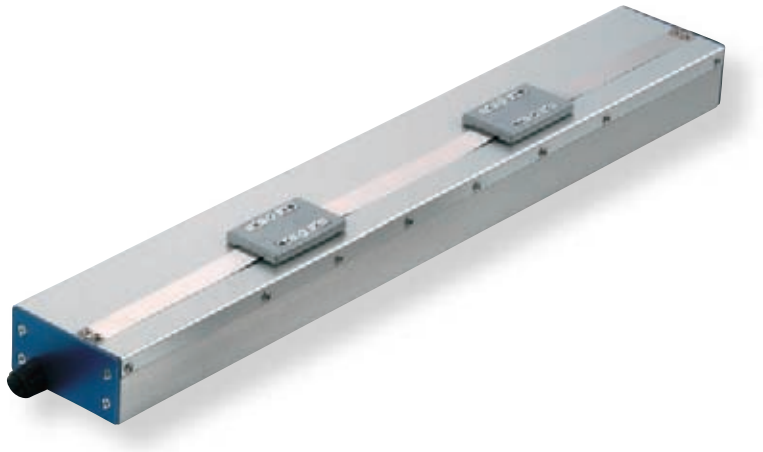
RoboCylinder Mini Linear Motor type Multi Slider Long Stroke type Actuator Width 48mm Linear motor

■Model Description

RCL – SM5L – I – 5 – N – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
RCL	SM5L	I: Incremental specification	5: Linear motor 5W	N: No screw	36: 36 mm ~ 144:144 mm (36mm Setting for each pitch)	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)
	Continuous operation (Duty is 100%)
0.1	1.6
0.3	
0.5	1.0
1	0.5
1.5	0.35
2	0.25

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload		Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)					
RCL-SM5L-I-5-N-①-②-③	5	See chart above	–	5	18	2	±0.1	36 to 144 (set in 36mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length

■Stroke and Maximum Speed

Lead \ Stroke	36 to 144 (set in 36mm increments)
(no screw)	1400

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

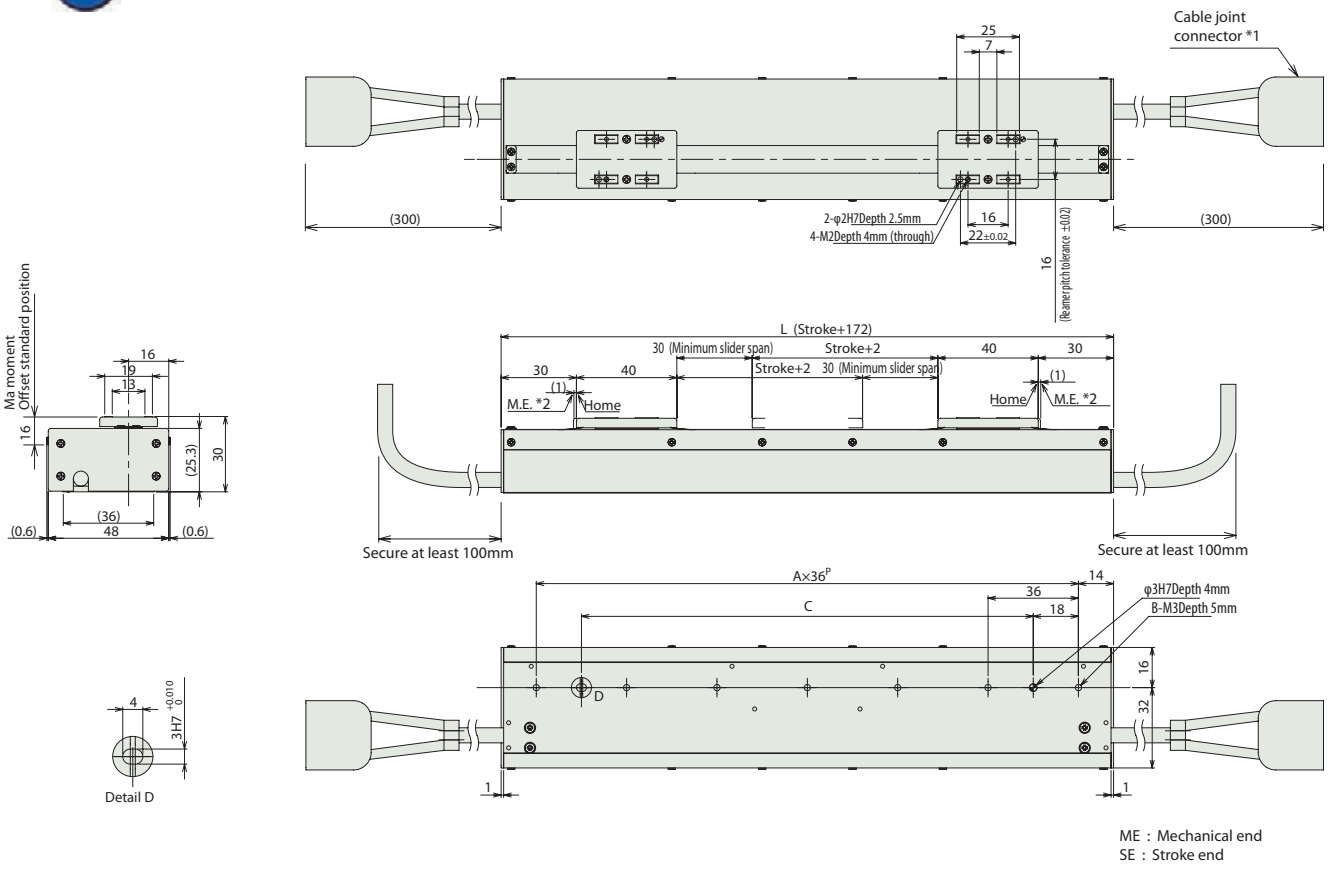
Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.49 N•m Mb: 0.41 N•m Mc: 0.72 N•m
Overhung load length	Ma direction: 80mm or less, Mb and Mc directions: 10 million times (number of round trips)
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



ME : Mechanical end
SE : Stroke end

*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	36	72	108	144
L	208	244	280	316
A	5	6	7	8
B	6	7	8	9
C	144	180	216	252
Mass (kg)	0.62	0.69	0.75	0.82

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference Page
Solenoid valve type		ASEP-C-5I-NP-2-0 (Note 1)	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.	–	→P101
		ASEP-CW-5I-NP-2-0 (Note 1)					–	
Positioner type		ACON-□-5I-NP-2-0 (Note 1) (Note 2)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points			–	See the ROBO Cylinder general catalog.
Program type		ASEL-C-2-5I-NP-2-0 (Note 3)	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points			–	

(Note 1) Two controllers are needed when operating multi slider.
(Note 2) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.
(Note 3) If 2-axis controller is used, operation is possible with one controller even if multi slider is operated.

RCL-SA6L

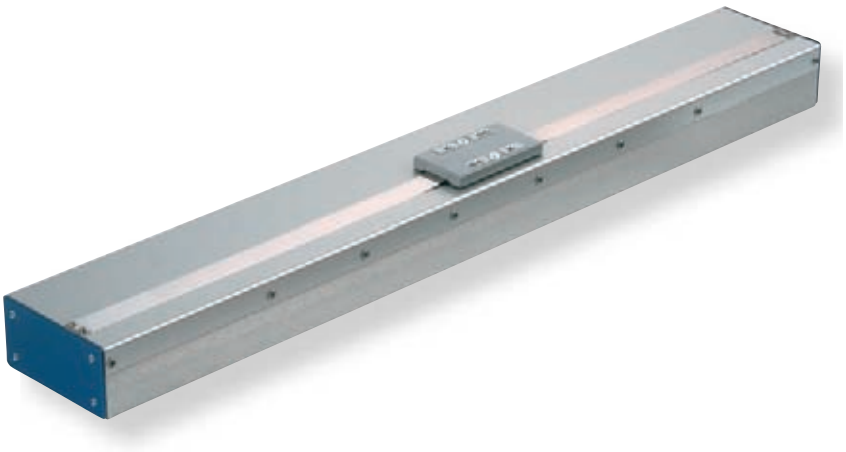
RoboCylinder Mini Linear Motor type Single Slider Long Stroke type Actuator Width 58mm Linear motor

■Model Description

RCL – SA6L – I – 10 – N – □ – □ – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification	10: Linear motor 10 W	N: No screw	48: 48 mm ~ 288: 288 mm (48mm Setting for each pitch)	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	NM: Reserved-home Specification

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

■Relation between payload (horizontal) and acceleration)

Maximum Acceleration (G)	Load Capacity (kg) Continuous operation (Duty is 100%)
0.1	3.2
0.3	
0.5	2
1	1
1.5	0.65
2	0.5

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload Horizontal (kg)	Maximum payload Vertical (kg)	Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
RCL-SA6L-I-10-N-①-②-③-④	10	See chart above	–	10	30	2	±0.1	40 to 288 (set in 48mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

■Stroke and Maximum Speed

Lead \ Stroke	48 to 288 (set in 48mm increments)
(no screw)	1600

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.87 N•m Mb: 0.75 N•m Mc: 1.22N•m
Overhung load length	Ma direction: 80mm or less, Mb and Mc directions:
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

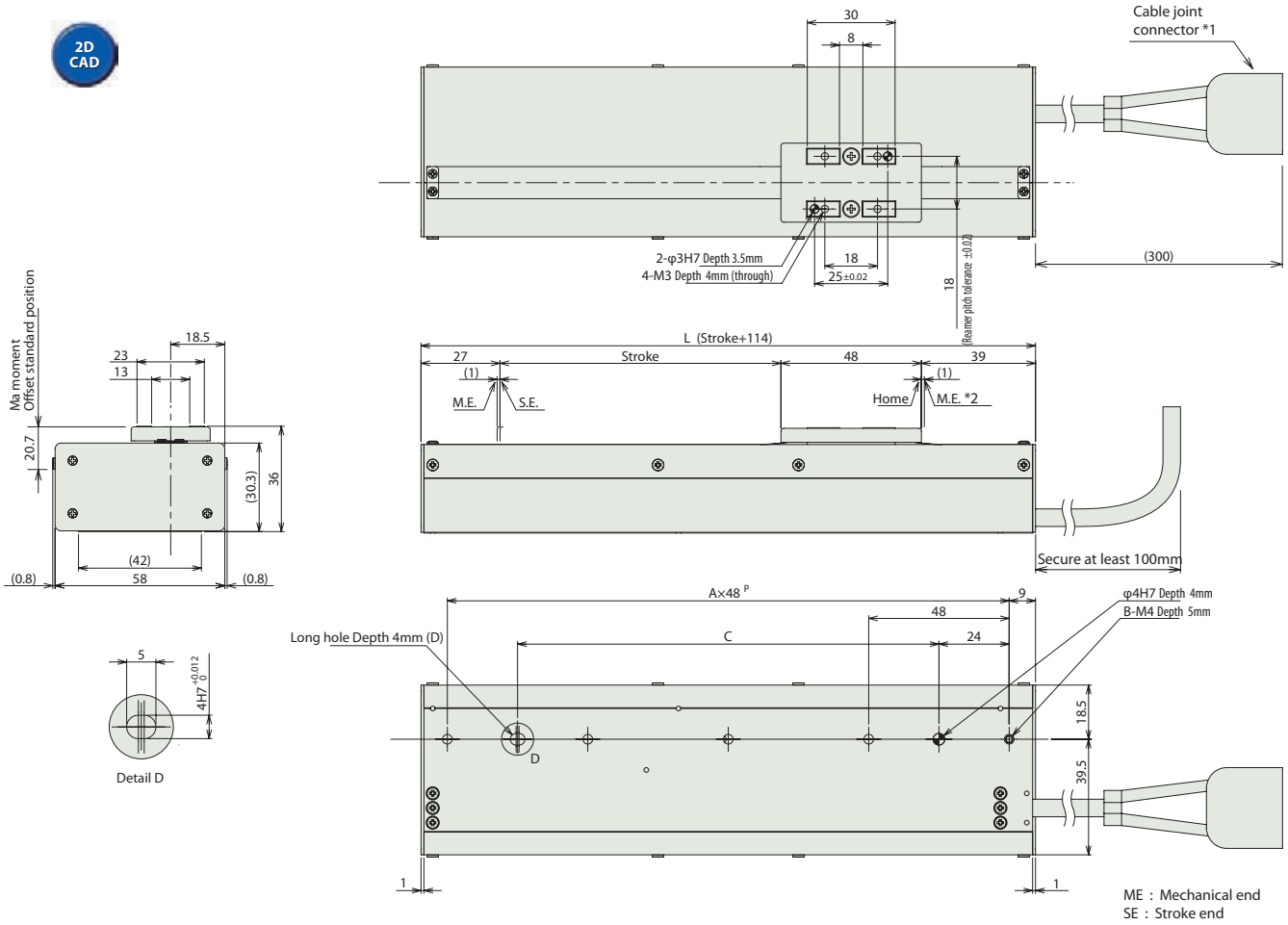
Options

Title	Option code	See page	
Reversed-home specification	**NM**	–	

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	48	96	144	192	240	288
L	162	210	258	306	354	402
A	3	4	5	6	7	8
B	4	5	6	7	8	9
C	96	144	192	240	288	336
Mass (kg)	0.67	0.8	0.93	1.07	1.2	1.34

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-SM6L

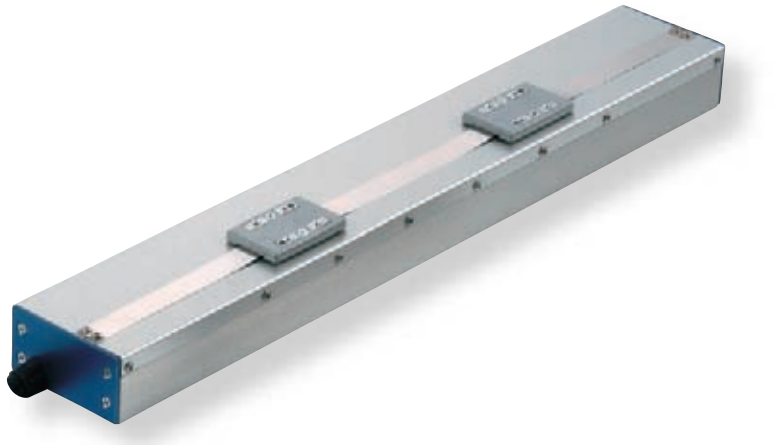
RoboCylinder Mini Linear Motor type Multi Slider Long Stroke type Actuator Width 58mm Linear motor

■Model Description

RCL – SM6L – I – 10 – N – □ – □ – □

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length
—	—	I: Incremental specification	10: Linear motor 10W	N: No screw	48: 48mm ~ 192: 192mm (48mm Setting for each pitch)	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation

*See page 11 for details on the model descriptions.



■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)
	Continuous operation (Duty is 100%)
0.1	3.2
0.3	
0.5	2
1	1
1.5	0.65
2	0.5

POINT Notes on selection

(1) Please take care because this type has magnetic flux leakage.
(If magnetism is a problem, use SA1L/SA2L/SA3L)

(2) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.

The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(3) The mounting position is horizontal-only. Please take care because the slider will drop down with power OFF when operating vertically.

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload		Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)					
RCL-SM6L-I-10-N-①-②-③	10	See chart above	–	10	30	2	±0.1	48 to 192 (set in 48mm increments)

Legend ① Stroke ② Compatible Controllers ③ Cable length

■Stroke and Maximum Speed

Lead \ Stroke	48 to 192 (set in 48mm increments)
(no screw)	1600

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

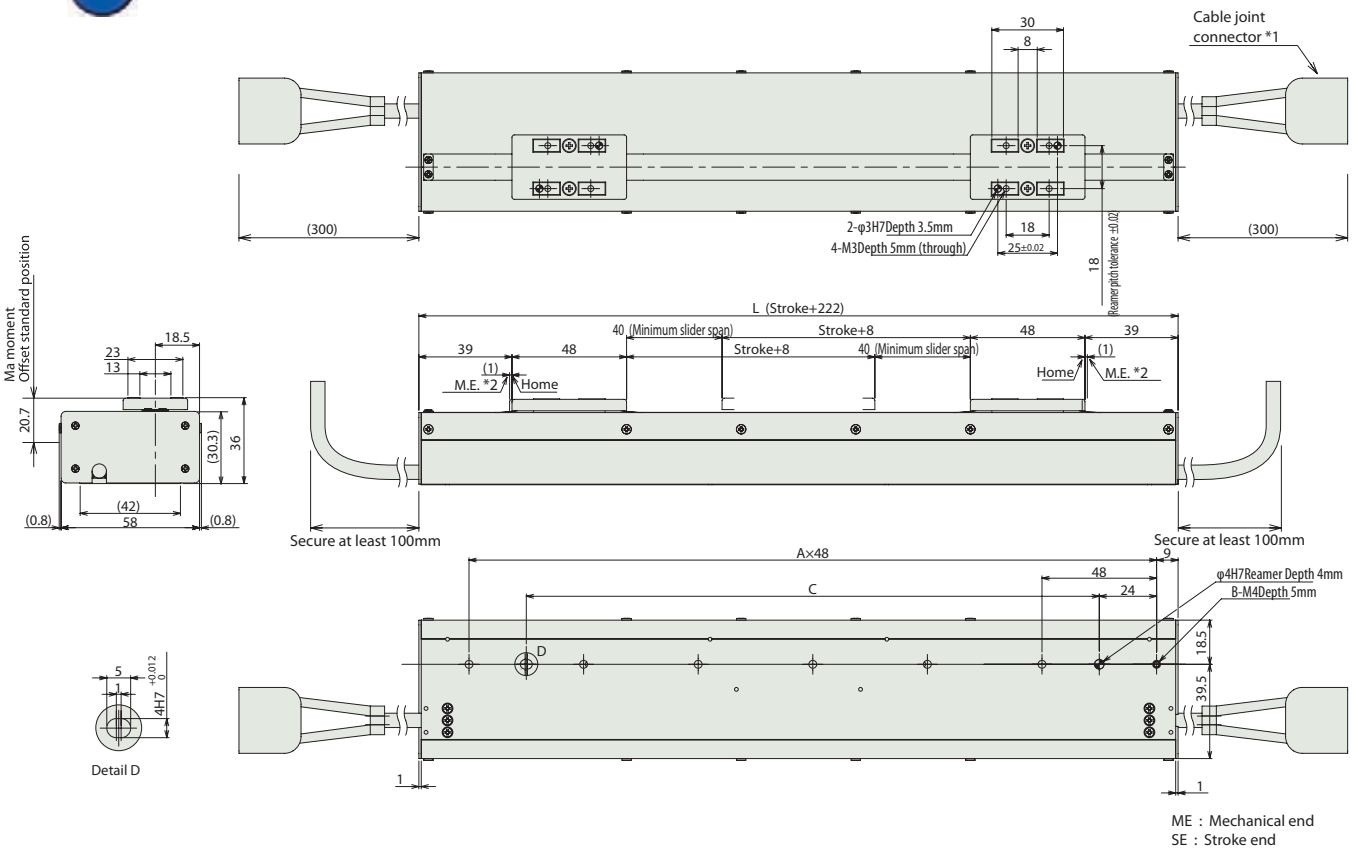
Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Base	Material: Aluminum, white alumite treated
Dynamic allowable moment (*1)	Ma: 0.87 N•m Mb: 0.75 N•m Mc: 1.22N•m
Overhung load length	Ma direction: 80mm or less, Mb and Mc directions:
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	5,000km

(*1) For case of 5,000km service life.

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD



*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

■Dimensions and Weight by Stroke

Stroke	48	96	144	192
L	270	318	366	414
A	5	6	7	8
B	6	7	8	9
C	192	240	288	336
Mass (kg)	1.17	1.31	1.44	1.58

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0 (Note 1)	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0 (Note 1)						
Positioner type		ACON-□-10I-NP-2-0 (Note 1) (Note 2)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-2-10I-NP-2-0 (Note 3)	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) Two controllers are needed when operating multi slider.
(Note 2) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.
(Note 3) If 2-axis controller is used, operation is possible with one controller even if multi slider is operated.

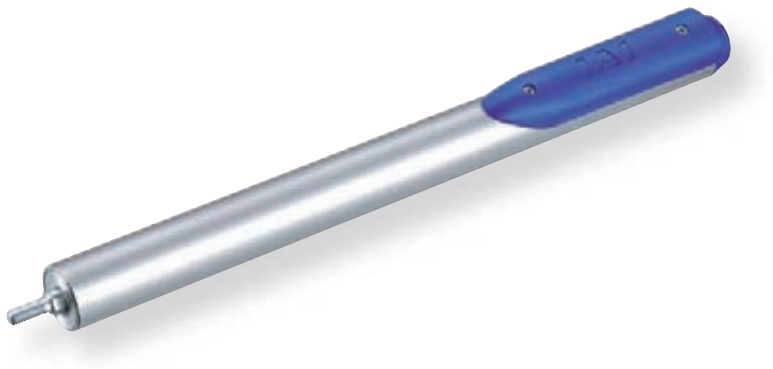
RCL-RA1L

ROBO Cylinder Mini Linear Motor type Micro Cylinder Slim type Main unit diameter: 16mm Linear motor

■Model Description

RCL	RA1L	I	2	N	25	□	□	□
Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification	2: Linear motor 2W	N: No screw	25: 25mm	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X□□: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The payload is determined by the acceleration and duty. Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) If operating vertically, the rod will drop down when the power is OFF, so please be careful.

(3) Please receive with external guide, etc. so that side and rotating load are not added to the rod.

(4) The pushing force fluctuation increases when the current limit is low.

■Relation between payload (horizontal) and acceleration)

Maximum Acceleration (G)	Load Capacity (kg)			
	Continuous operation (Duty is 100%)		Duty is 70% or less	
	Horizontal	Vertical	Horizontal	Vertical
0.1	0.5	0.1	0.5	0.1
0.3				
0.5	0.42			
1	0.2		0.25	
1.5	0.11	–	0.15	–
2	0.07	–	0.1	–

■Pushing force guidelines

Pushing operation is possible within the range of numeric values listed below.

Electric current limit	30%	40%	50%	60%	70%	80%
Pushing force (N)	0.75	1	1.25	1.5	1.75	2

(Note) The pushing forces listed above are for horizontal usage. If facing vertically upward, subtract 0.5N from the numeric values listed above, but if facing vertically downward, add 0.5N.

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload		Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)					
RCL-RA1L-I-2-N-25-①-②	2	See chart above	See chart above	2.5	10	Horizontal 2G Vertical 1G	±0.1	25 (Fixed)

Legend ① Stroke ② Compatible Controllers

■Stroke and Maximum Speed

Lead \ Stroke	25 (mm)
(no screw)	300

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Pipe	Material: Nickel-plated carbon steel tube
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

Title	Option code	See page	
Brake	**B**	→P92	
Brake without brake box	**BN**	→P92	

* A brake box and a brake cable are necessary for brake. To arrange actuators with the brake specification for spare and maintenance, please select option code BN.

Dimensional Drawings

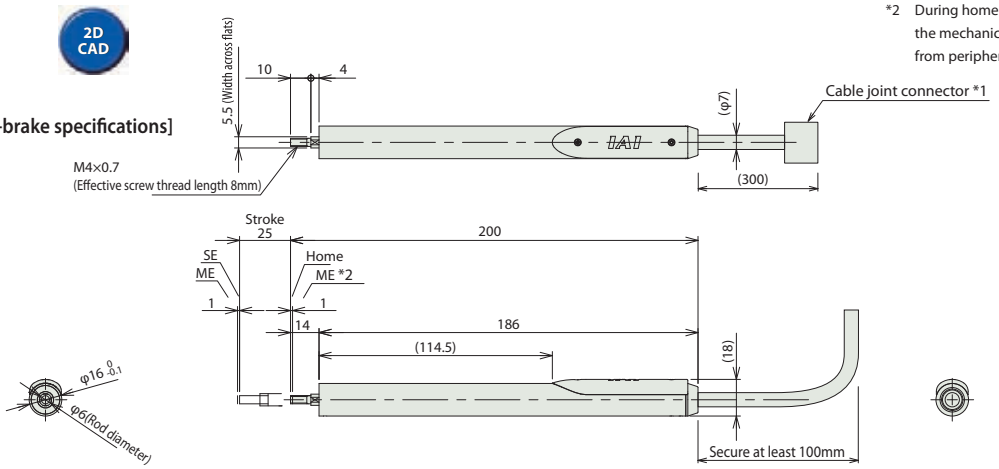
CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

*1 The motor and encoder cable are attached.
Please refer to page 113 for more information.

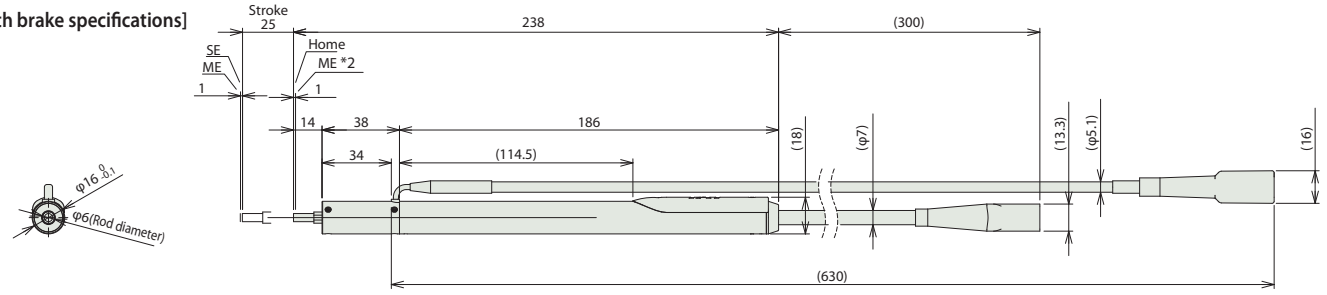
*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

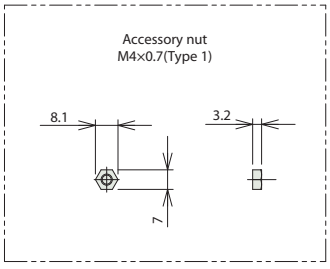
[No-brake specifications]

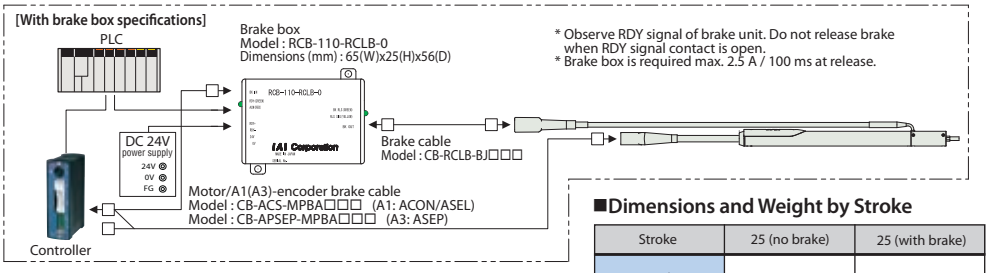


ME : Mechanical end
SE : Stroke end

[With brake specifications]







■Dimensions and Weight by Stroke

Stroke	25 (no brake)	25 (with brake)
Mass (kg)	0.2	0.25

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-2I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.		→P101
		ASEP-CW-2I-NP-2-0						
Positioner type		ACON-□-2I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-2I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-RA2L

RoboCylinder Mini Linear Motor type Micro Cylinder Slim type Main unit diameter: 20mm Linear motor

■Model Description

RCL — RA2L — I — 5 — N — 30 — ☐ — ☐ — ☐

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
RCL	RA2L	I: Incremental specification	5: Linear motor 5W	N: No screw	30: 30mm	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.

POINT Notes on selection

(1) The payload is determined by the acceleration and duty. Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) If operating vertically, the rod will drop down when the power is OFF, so please be careful.

(3) Please receive with external guide, etc. so that side and rotating load are not added to the rod.

(4) The pushing force fluctuation increases when the current limit is low.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)			
	Continuous operation (Duty is 100%)		Duty is 70% or less	
	Horizontal	Vertical	Horizontal	Vertical
0.1	1	0.2	1	0.2
0.3				
0.5	0.85			
1	0.4		0.5	
1.5	0.24	–	0.3	–
2	0.15	–	0.2	–

■Pushing force guidelines

Pushing operation is possible within the range of numeric values listed below.

Electric current limit	30%	40%	50%	60%	70%	80%
Pushing force (N)	1.5	2	2.5	3	3.5	4

(Note) The pushing forces listed above are for horizontal usage. If facing vertically upward, subtract 1N from the numeric values listed above. If facing vertically downward, add 1N.

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload		Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)					
RCL-RA2L-I-5-N-30-①-②	5	See chart above	See chart above	5	18	Horizontal 2G Vertical 1G	±0.1	30 (Fixed)

Legend ① Stroke ② Compatible Controllers

■Stroke and Maximum Speed

Lead \ Stroke	30 (mm)
(no screw)	340

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Pipe	Material: Nickel-plated carbon steel tube
Ambient operating temperature, humidity	0 to 40 °C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

Title	Option code	See page	
Brake	**B**	→ P94	
Brake without brake box	**BN**	→ P94	

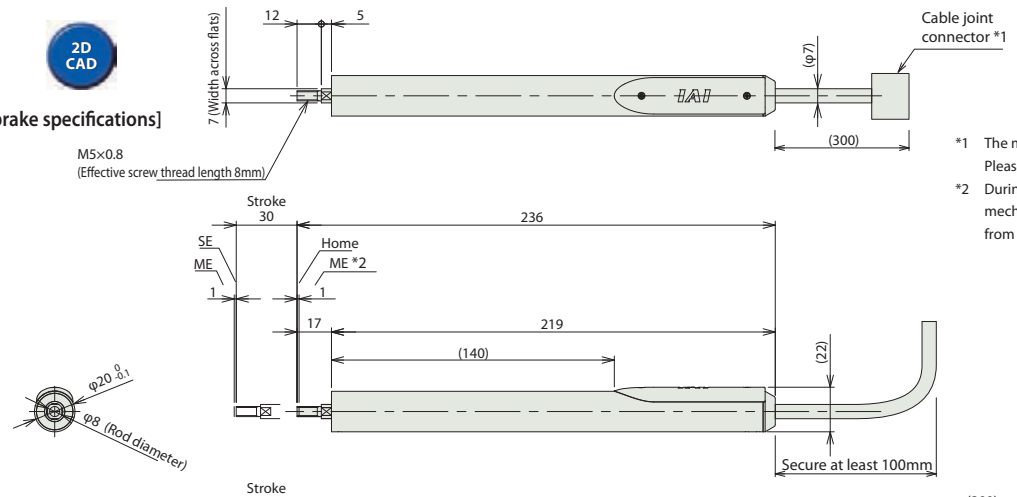
* A brake box and a brake cable are necessary for brake. To arrange actuators with the brake specification for spare and maintenance, please select option code BN.

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

[No-brake specifications]

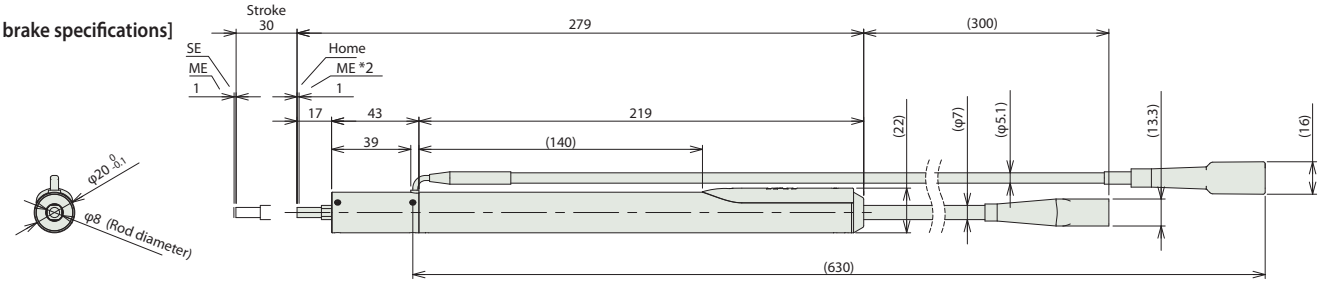


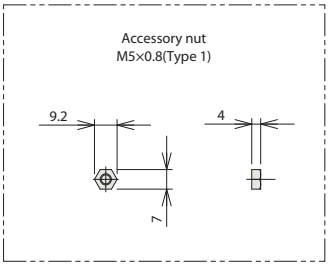
*1 The motor and encoder cable are attached. Please refer to page 113 for more information.

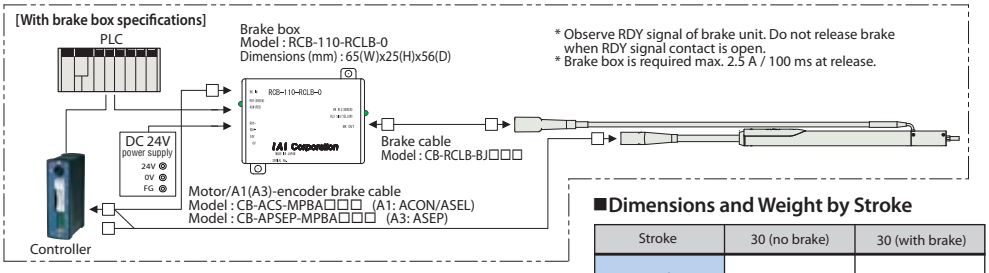
*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

ME : Mechanical end
SE : Stroke end

[With brake specifications]







■Dimensions and Weight by Stroke

Stroke	30 (no brake)	30 (with brake)
Mass (kg)	0.33	0.4

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-5I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.		→P101
		ASEP-CW-5I-NP-2-0						
Positioner type		ACON-□-5I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		AASEL-C-1-5I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

RCL-RA3L

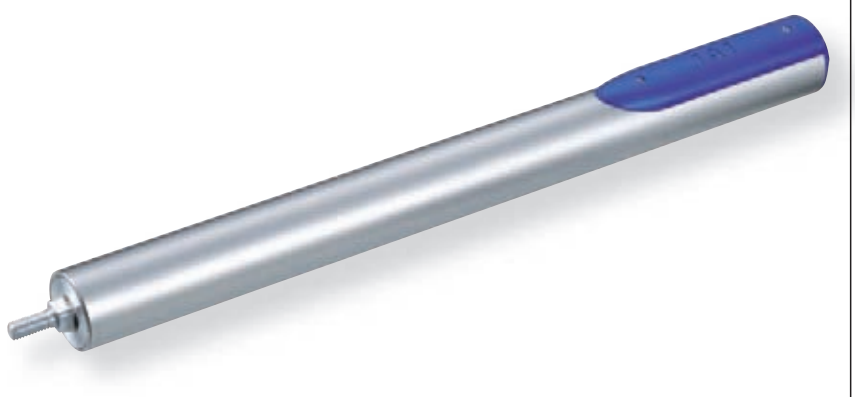
RoboCylinder Mini Linear Motor type Micro Cylinder Slim type Main unit diameter: 25mm Linear motor

■Model Description

RCL – RA3L – I – 10 – N – 40 – ☐ – ☐ – ☐

Series	Type	Encoder type	Motor type	Lead	Stroke	Compatible Controllers	Cable length	Option
		I: Incremental specification	10: Linear motor 10W	N: No screw	40: 40mm	A1: ACON RACON PSEL A3: ASEP	N: None P: 1m S: 3m M: 5m X☐☐: Length Designation	Following options Refer to below table

*See page 11 for details on the model descriptions.



POINT Notes on selection

(1) The payload is determined by the acceleration and duty.
Verify the payload in the payload (horizontal) and acceleration chart at right.
The duty is $\frac{\text{Operating time}}{\text{Operating time + stop time}}$ ×100 per cycle.

(2) If operating vertically, the rod will drop down when the power is OFF, so please be careful.

(3) Please receive with external guide, etc. so that side and rotating load are not added to the rod.

(4) The pushing force fluctuation increases when the current limit is low.

■Relation between payload (horizontal) and acceleration

Maximum Acceleration (G)	Load Capacity (kg)			
	Continuous operation (Duty is 100%)		Duty is 70% or less	
	Horizontal	Vertical	Horizontal	Vertical
0.1	2	0.4	2	0.4
0.3				
0.5	1.6			
1	0.78		1	
1.5	0.46	–	0.6	–
2	0.3	–	0.4	–

■Pushing force guidelines

Pushing operation is possible within the range of numeric values listed below.

Electric current limit	30%	40%	50%	60%	70%	80%
Pushing force (N)	3	4	5	6	7	8

(Note) The pushing forces listed above are for horizontal usage. If facing vertically upward, subtract 1.8N from the numeric values listed above, but if facing vertically downward, add 1.8N.

Actuator Specification Table

■Leads and Payloads

Model	Motor Output	Maximum payload		Rated thrust (N)	Instaneuous maximum thrust (N)	Maximum acceleration (G)	Positioning Repeatability (mm)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)					
RCL-RA3L-I-10-N-40-①-②	10	See chart above	See chart above	10	30	Horizontal 2G Vertical 1G	±0.1	40 (Fixed)

Legend ① Stroke ② Compatible Controllers

■Stroke and Maximum Speed

Lead \ Stroke	40 (mm)
(no screw)	450

(Unit = mm/s)

Cable length

Type	Cable symbol	
Standard type (Robot cable)	**P** (1m)	
	S (3m)	
	M (5m)	
Special length	**X06** (6m) to **X10** (10m)	
	X11 (11m) to **X15** (15m)	
	X16 (16m) to **X20** (20m)	

* The standard cable for the RCL is the robot cable.
* See page 113 for maintenance cables.

Actuator Specification

Item	Description
Drive System	Linear motor
Encoder resolution	0.042mm
Pipe	Material: Nickel-plated carbon steel tube
Ambient operating temperature, humidity	0 to 40 ˚C, 85% RH or less (No condensation)
Service life	10 million cycles

Options

Title	Option code	See page	
Brake	**B**	→ P96	
Brake without brake box	**BN**	→ P96	

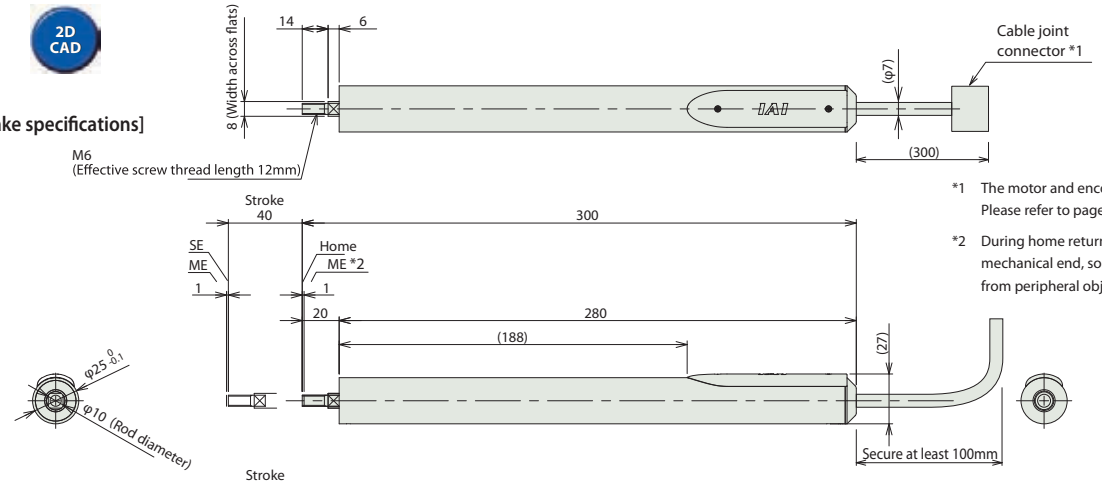
* A brake box and a brake cable are necessary for brake. To arrange actuators with the brake specification for spare and maintenance, please select option code BN.

Dimensional Drawings

CAD drawings can be downloaded from the website. www.robocylinder.de

2D CAD

[No-brake specifications]

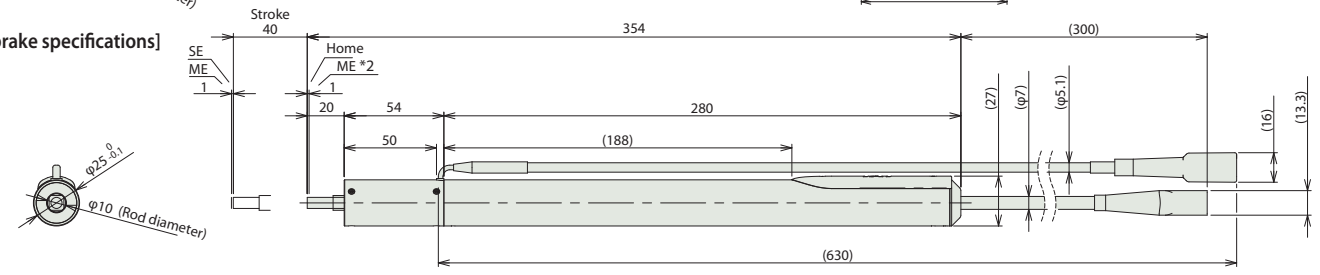


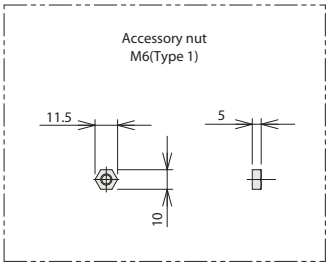
*1 The motor and encoder cable are attached. Please refer to page 113 for more information.

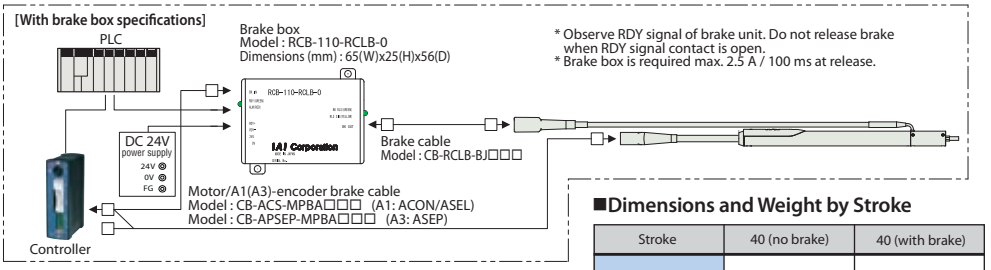
*2 During home return, the slider travels until the mechanical end, so be careful to avoid interference from peripheral objects.

ME : Mechanical end
SE : Stroke end

[With brake specifications]







■Dimensions and Weight by Stroke

Stroke	40 (no brake)	40 (with brake)
Mass (kg)	0.6	0.77

Compatible Controllers

RCL series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Title	External View	Model	Features	Maximum number of positioning points	Input power	Power-supply capacity		Reference Page
Solenoid valve type		ASEP-C-10I-NP-2-0	Simple controller capable of operating with the same signal as the solenoid valve Supports the use of both the single solenoid and the double solenoid types *Simple absolute unit cannot be used with RCL series	3 points	DC24V	See P109.		→P101
		ASEP-CW-10I-NP-2-0						
Positioner type		ACON-□-10I-NP-2-0 (Note 1)	Up to 512-points positioning possible *Simple Absolute type cannot be used with RCL series	512 points				See the Robo-Cylinder general catalog.
Program type		ASEL-C-1-10I-NP-2-0	Programmable type Capable of operating up to 2 axes *Simple absolute unit cannot be used with RCL series	1500 points				

(Note 1) ACON can be used with C/CG/CY/PL/PO/SE type. Also, ROBONET can be used.

Selection Guide (Push force and current limiting value correlation graph)

Use the following models for push-motion operation.
The push force applied in push-motion operation can be freely set by changing the current-limiting value in the controller.
The push force setting ranges differ according to type. Use the following chart to verify.

RCL Series Micro Cylinder

● Setting the current limiting value in push-motion operation

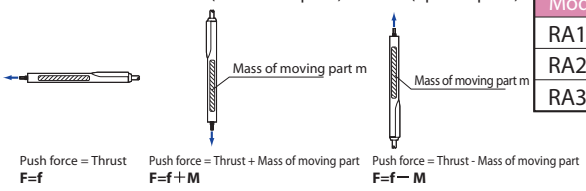
For push-motion operation, set the current limiting values that determine push force. The push force is an approximate standard, so it will vary somewhat.
The push time is not limited. Continuous pushing is possible.

Standard for push force [N]

Current limiting value	30 %	40 %	50 %	60 %	70 %	80 %
RA1L	0.75	1	1.25	1.5	1.75	2
RA2L	1.5	2	2.5	3	3.5	4
RA3L	3	4	5	6	7	8

Caution
- Depending on teaching pendant version or PC software, the current limiting value can be set within 71% to 80%. Be sure to read the "Caution" section shown at the beginning of the manual.
- Movement speed during push operation is fixed at 20mm/s.

Effect by push direction



Mass of moving part

Model	Mass of moving part [N]
RA1L	0.5
RA2L	1
RA3L	1.8

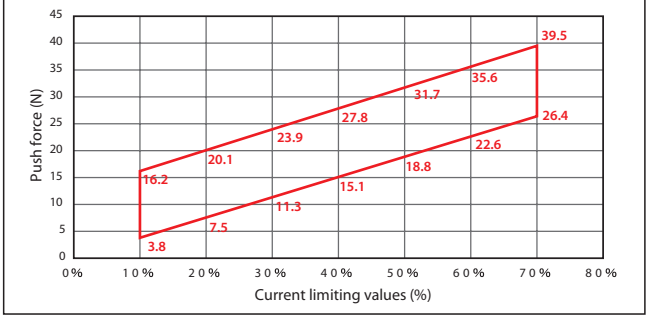
RCP3 Series Mini Rod type

* The red line ranges are specification values.

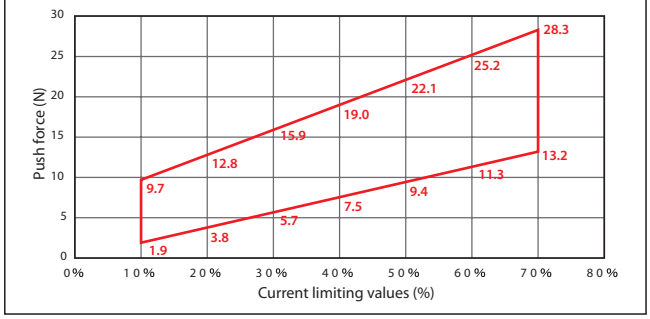
For push-motion operation, select the model with the desired push force that falls within the range of the red line in the graph below.
(The graph is extended to accommodate performance decrease in the slide screws due to wear.)

Caution
- Movement speed during push operation is fixed at 5mm/s.

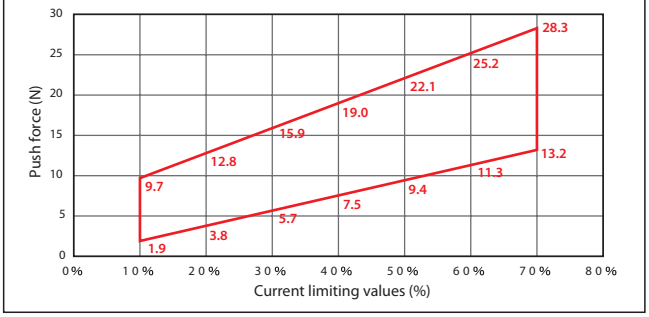
RA2AC／RA2AR 1mm Lead



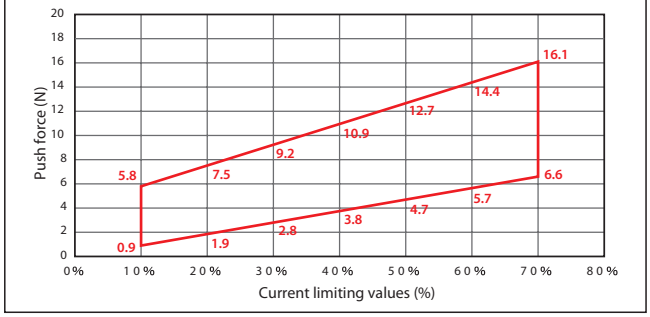
RA2BC／RA2BR 2mm Lead



RA2AC／RA2AR 2mm Lead



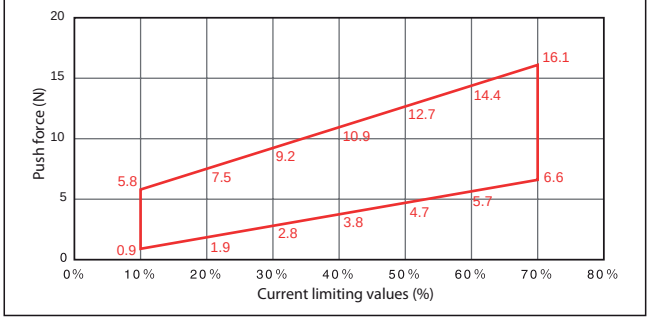
RA2BC／RA2BR 4mm Lead



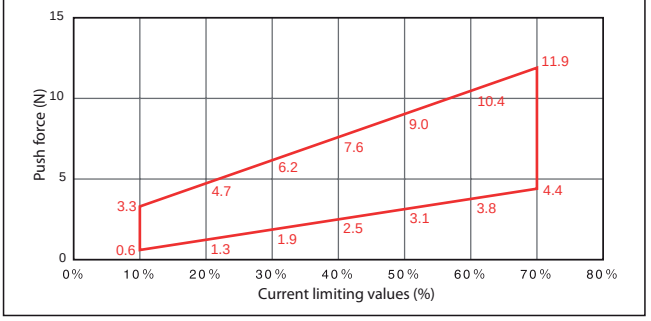
RCP3 Series Mini Rod type

* The red line ranges are specification values.

RA2AC/RA2AR 4mm Lead



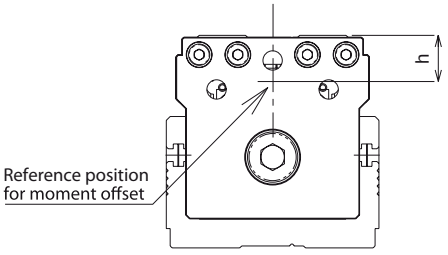
RA2BC/RA2BR 6mm Lead



RCP3 Series Mini Table type

When using the table type for a push operation, limit the pushing current to ensure that the reaction moment generated by the push force does not exceed the catalog specification rated moment (Ma, Mb) of 80%.

Refer to the figure below for the operation position for moment calculations.



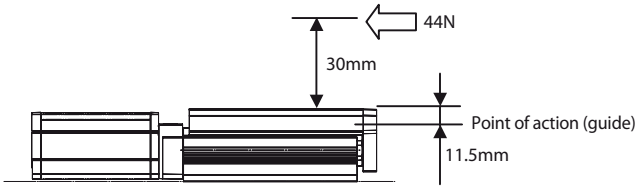
TA3C/TA3R : h = 10.5mm
TA4C/TA4R : h = 11.5mm

Caution
- Movement speed during push operation is fixed at 20mm/s.
- The push force is an approximate standard, so it will vary somewhat.

When using a slider type for a push operation, limit the pushing current to ensure that the reaction moment generated by the push force does not exceed the catalog specification **rated moment of 80%.**

Example of calculation:
When pushing at 44N at the position in the chart on the right using RCP3-TA4C (Lead 2) type:

The guide moment is Ma = (11.5+30) x 44
= 1826 (N·mm)
= 1.826 (N·m).

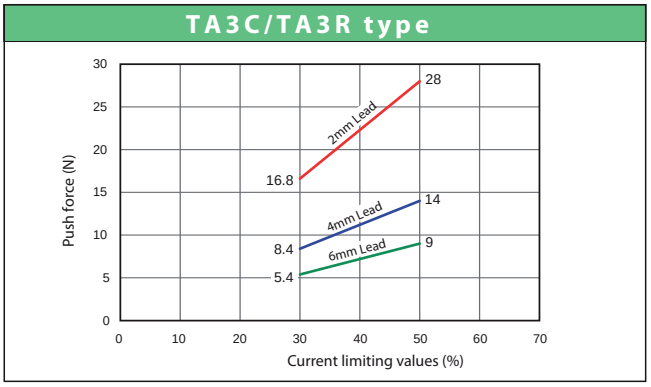


The TA4C allowable dynamic moment (Ma) is 4.2 (N·m), which means 80% is 3.36.
Therefore, a moment load greater than that actually received by the guide (1.826) can be used.

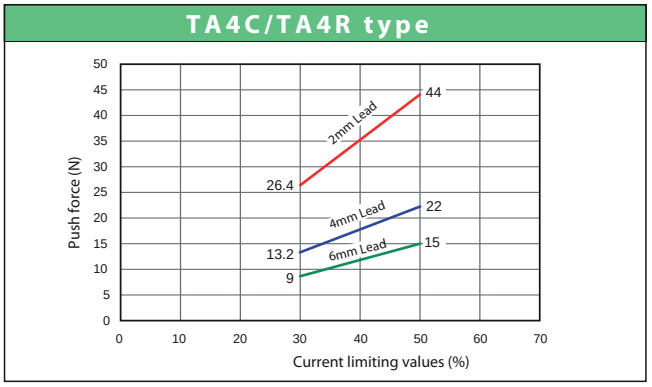
Push force and current limiting value correlation graph

Standard figures are shown in the table below. Actual figures will differ slightly.

TA3C/TA3R type



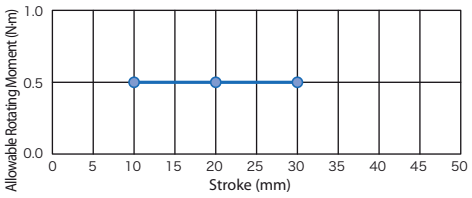
TA4C/TA4R type



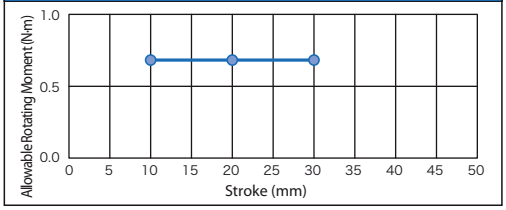
Allowable Rotating Torque

The allowable torque for each model is specified below.
When rotational torque is exerted, use within the range of values specified below. Please note that single-guide types cannot be subjected to rotational torque.

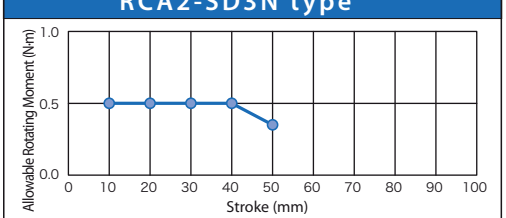
RCA2-GD3N type



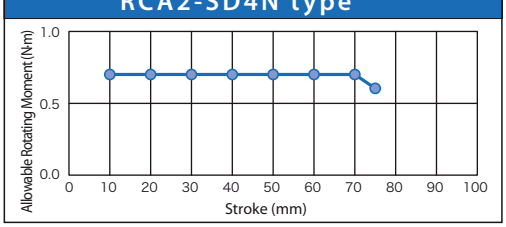
RCA2-GD4N type



RCA2-SD3N type



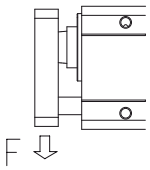
RCA2-SD4N type



Relationship Between Allowable Load at Tip & Running Service Life

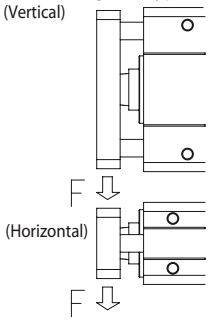
The greater the load at the guide tip, the shorter the running service life.
Select the appropriate model while considering the balance between load and service life.

■Single-guide type

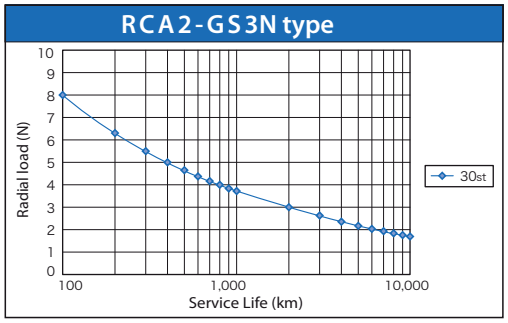


* Single-guide specifications can only be used with vertical loads.

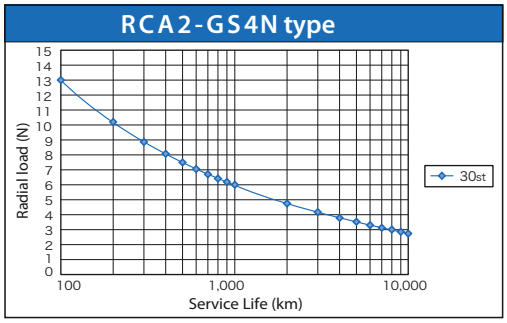
■Double-guide type



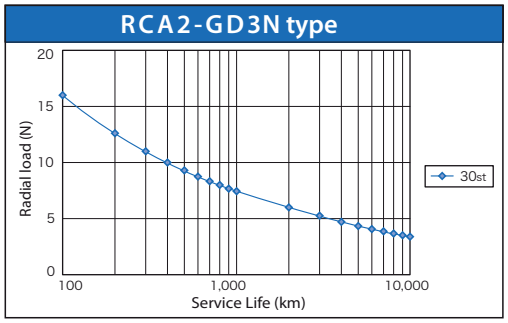
RCA2-GS3N type



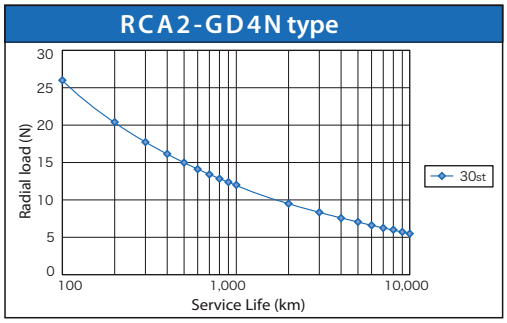
RCA2-GS4N type



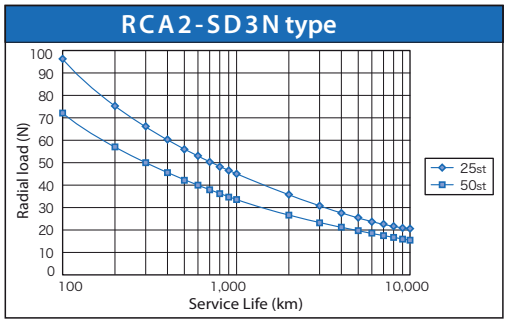
RCA2-GD3N type



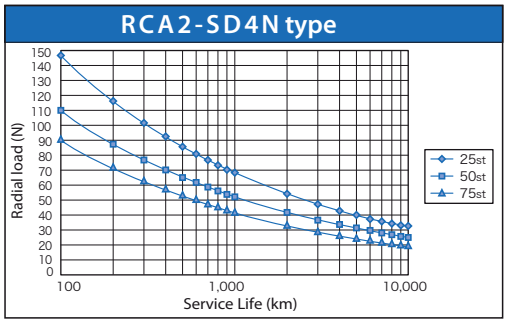
RCA2-GD4N type



RCA2-SD3N type



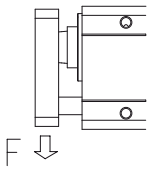
RCA2-SD4N type



Radial Load & Tip Deflection

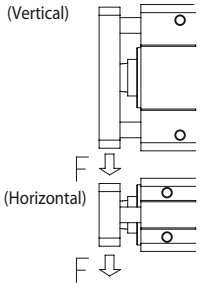
The graph below shows the correlation between the load exerted at the guide tip and the amount of deflection generated.

■Single-guide type

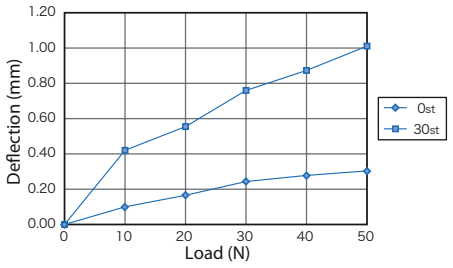


*Single-guide specifications can only be used with vertical loads.

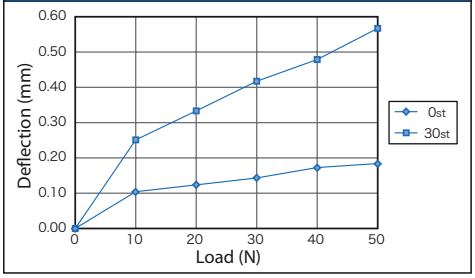
■Double-guide type



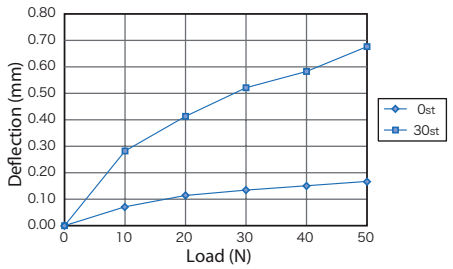
RCA2-GS3N type



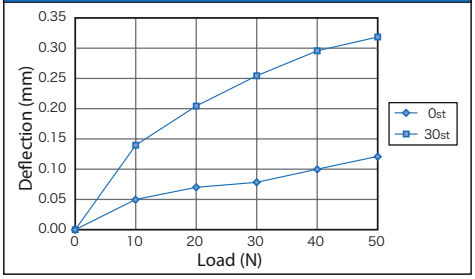
RCA2-GS4N type



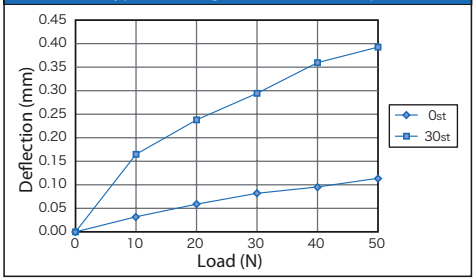
RCA2-GD3N type (Double guide <vertical> specifications)



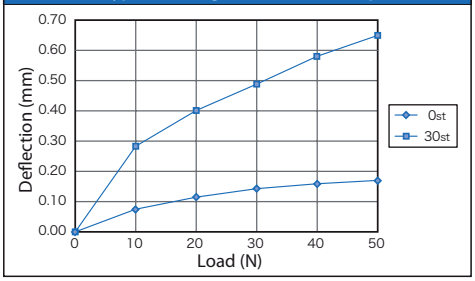
RCA2-GD4N type (Double guide <vertical> specifications)



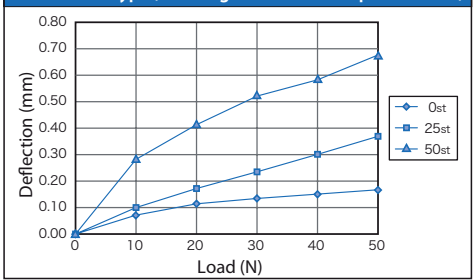
RCA2-GD3N type(Double guide<horizontal> specifications



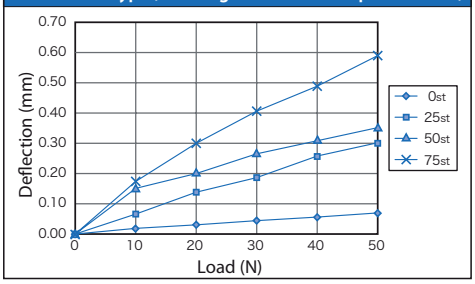
RCA2-GD4N type (Double guide <horizontal> specifications)



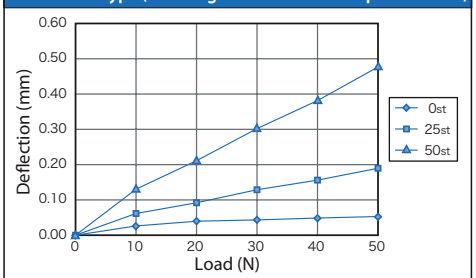
RCA2-SD3N type (Double guide <vertical> specifications)



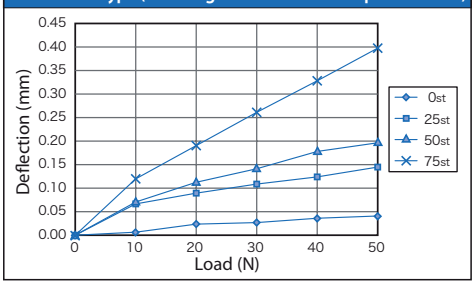
RCA2-SD4N type (Double guide <vertical> specifications)



RCA2-SD3N type (Double guide <horizontal> specifications)



RCA2-SD4N type (Double guide <horizontal> specifications)



PSEP

Model C/CW
3-position controller for RCP2/RCP3
Position Controller

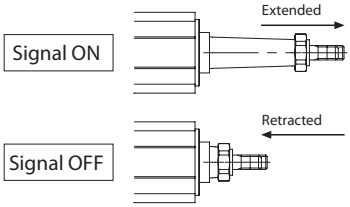
ASEP

Model C/CW
3-position controller for RCA/RCA2/RCL
Position Controller

Feature

1 Can operate with same signal as solenoid valve.

The signal that operates the actuator is the same as the signal that operates the air cylinder. Therefore, the PLC program currently in use can be used without modification even if the air cylinder is replaced by an electric-powered cylinder.
Either a single solenoid or a double solenoid may be used.



2 Establishes a dustproof type that supports IP53.

(*1) Protective structure has been configured for dust proofing. A controller can be configured external to the control panel.

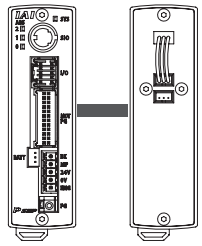
(*1) Does not include bottom surface portion.

3 Establishes Simple Absolute type capable of moving immediately after power has been turned on without returning to home.

When power is turned on or after an emergency stop is released, the simple absolute type determines its present position from the absolute battery unit and is ready to begin the next movement from that position.

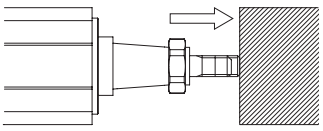
(Note 1) Incremental specifications are used for an actuator connecting a simple absolute unit ABU.
(Note 2) Cannot be used with the linear motor type.

If the absolute battery unit is to be installed, mount it below the SEP controller.



4 Push-motion and midway stop operations are possible.

Similar to an air cylinder, push-motion operation is possible with the motion of a rod pushing against the work piece halted. The force exerted during a push-motion operation is adjustable within a range of 20 to 70% of the maximum pushing force, and a signal is output when a preset pushing force value is achieved. Therefore the push-motion operation is suitable for use when performing such tasks as clamping the workpiece or assessing its size.



Push force can be adjusted from
20 to 70% of the maximum push force.

5 Easy data input with dedicated touch panel teaching unit.

The travel position, pushing force, etc. can be easily input using the optional touch panel teaching unit (model SEP-PT).
Using the interactive menu and direct onscreen operation, the touch panel teaching unit can be operated intuitively even without reading the user's manual.

Model list/Standard price

Series Name	PSEP				ASEP			
Type	C		CW		C		CW	
Title	Standard type		Dustproof type		Standard type		Dustproof type	
Positioning method	Incremental type	Simple Absolute type	Incremental type	Simple Absolute type	Incremental type	Simple Absolute type	Incremental type	Simple Absolute type
External View								
Description	Position controller that has been streamlined and specialized for 2-point/3-point positioning, for use with pulse motors.		PSEP-C dustproof type equipped with IP53-equivalent protective structure		Position controller that has been streamlined and specialized for 2-point/3-point positioning, for use with servo motors.		ASEP-C dustproof type equipped with IP53-equivalent protective structure	
Positioner Number of points	2-point/ 3-point							

* The absolute battery unit is attached to the simple absolute type (see P112).

Model

PSEP — Series — Type — Motor / Encoder type — **I** — I/O Type — I/O Cable length — **0** — Power Supply Voltage — For simple absolute type

Type	
C	Standard type
CW	Dustproof type

Motor / Encoder type	
I	Incremental type

I/O Type	
NP	NPN type
PN	PNP type

I/O Cable length	
0	No cable
2	2m
3	3m
5	5m

Power Supply Voltage	
0	DC24V

For simple absolute type	
ABU	Simple Absolute type
(not entered)	Incremental type

Motor / Encoder type	
20P	20☐ pulse motor compatible
28P	28☐ pulse motor compatible
28SP	28☐ pulse motor (RA3C dedicated) compatible
35P	35☐ pulse motor compatible
42P	42☐ pulse motor compatible
56P	56☐ pulse motor compatible

ASEP — Series — Type — Motor / Encoder type — **I** — I/O type — I/O Cable Length — **0** — Power Supply Voltage — For simple absolute type

Type	
C	Standard type
CW	Dustproof type

Motor / Encoder type	
LA	Power-save function
I	Incremental type

I/O type	
NP	NPN type
PN	PNP type

I/O Cable Length	
0	No cable
2	2m
3	3m
5	5m

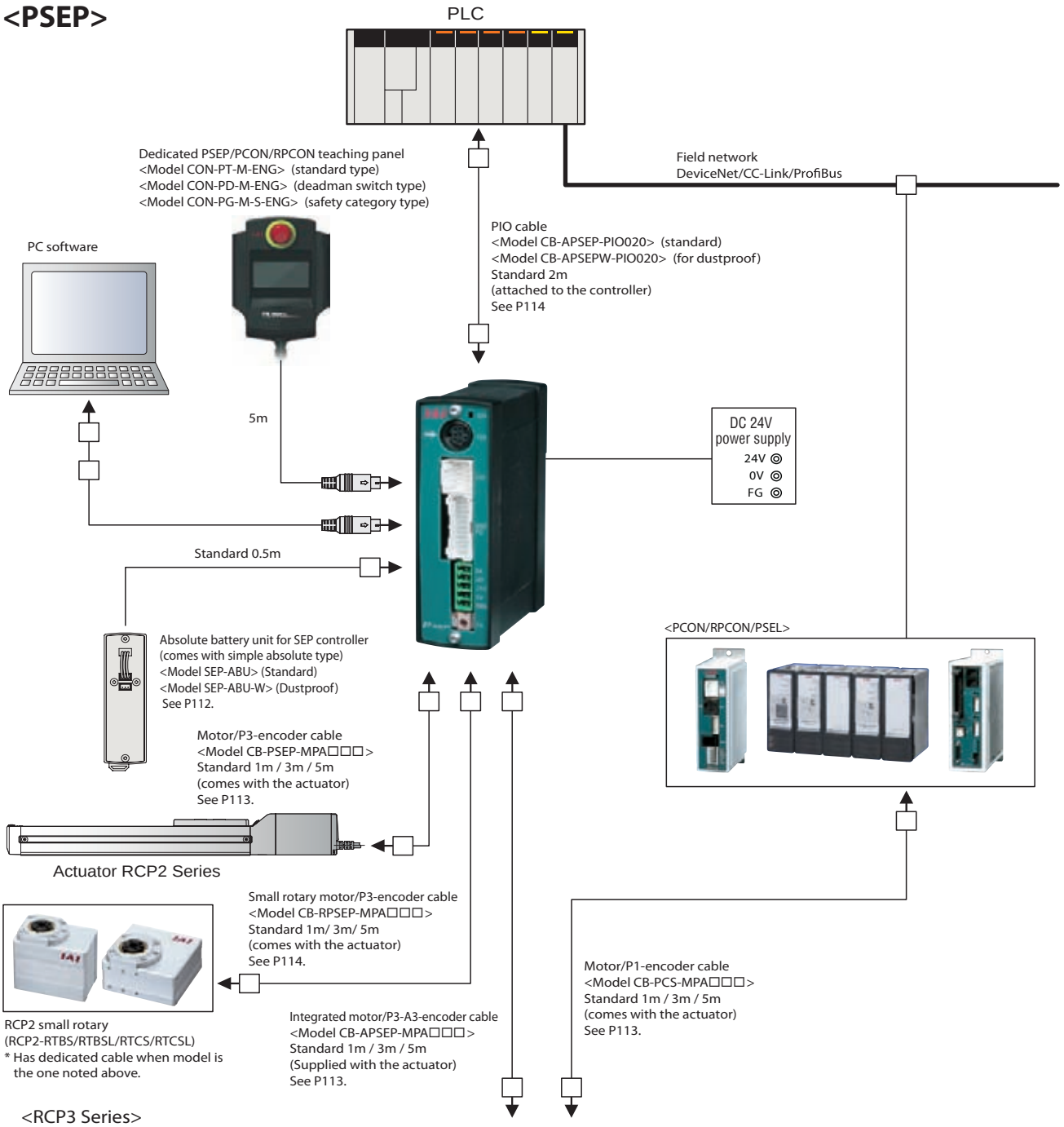
Power Supply Voltage	
0	DC24V

For simple absolute type	
ABU	Simple Absolute type
(not entered)	Incremental type

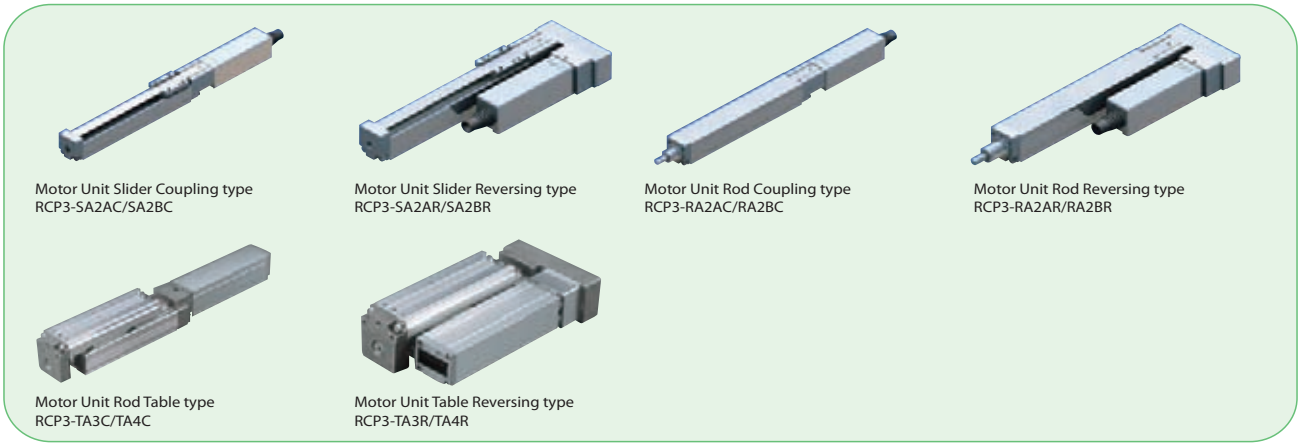
Motor / Encoder type	
2	For 2W motor
5	For 5W motor
10	For 10W motor
20	For 20W motor
20S	For 20W motor (RCA2-SA4C/ RCA-RA3☐ dedicated)
30	For 30W motor

System configuration

<PSEP>

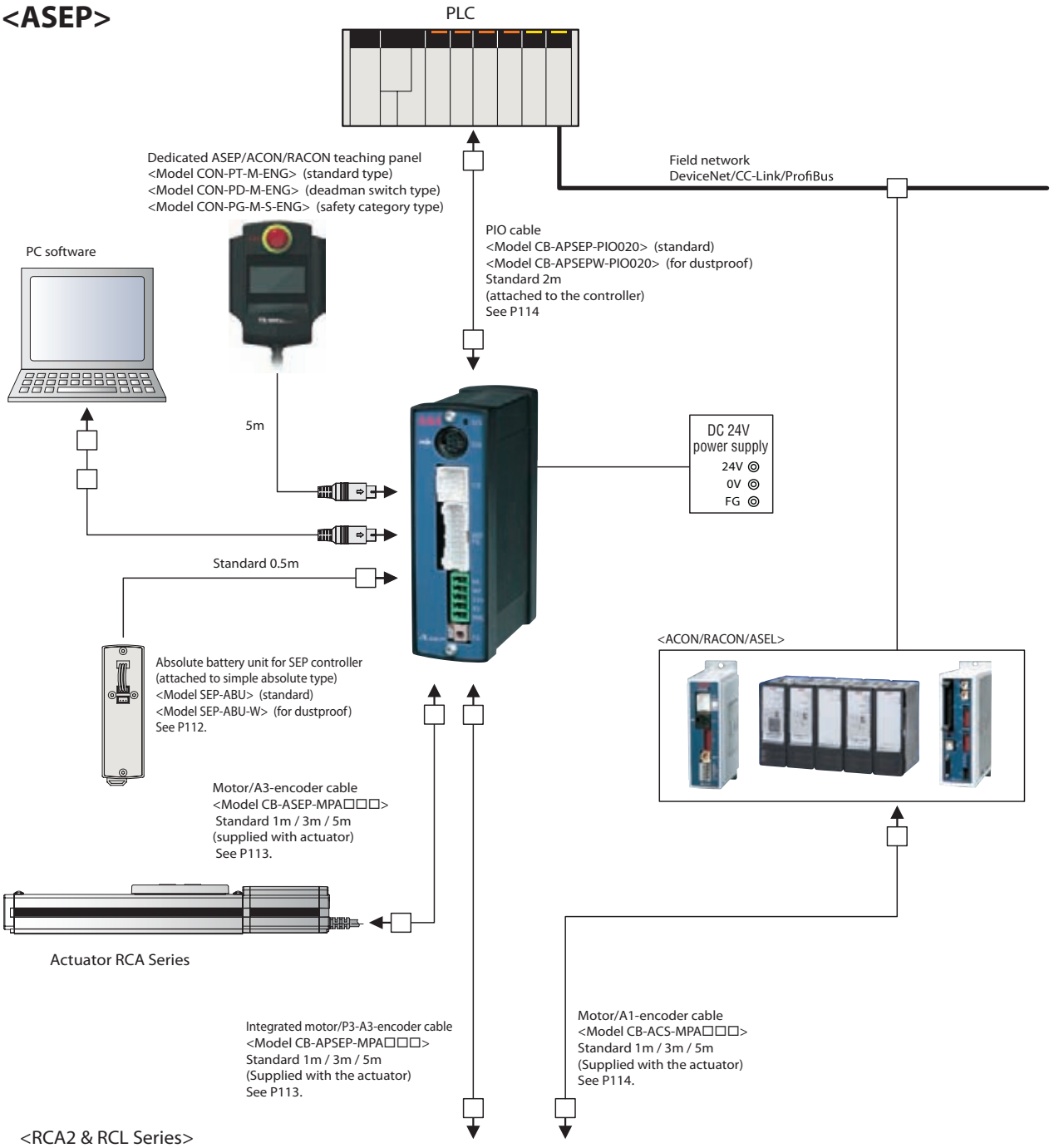


<RCP3 Series>

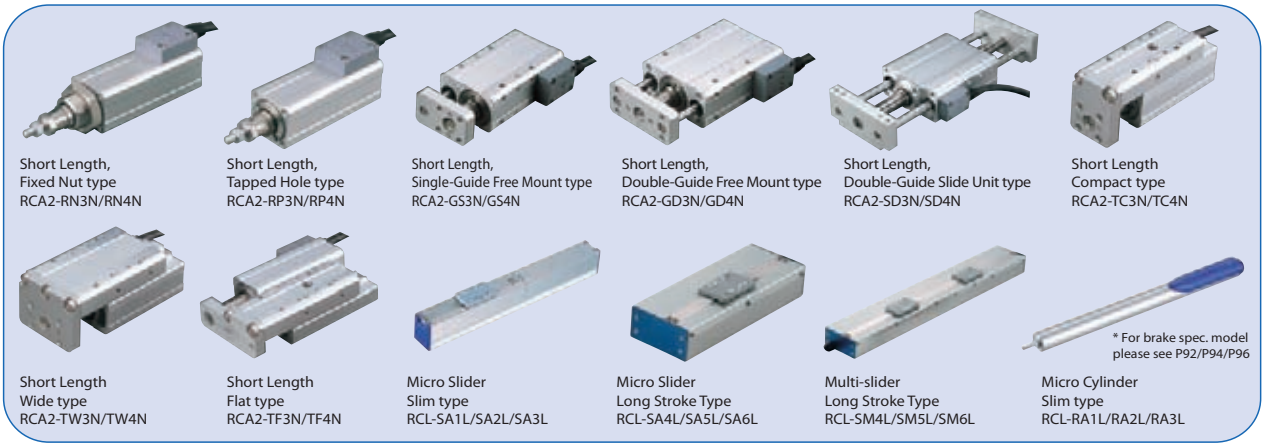


System configuration

<ASEP>



<RCA2 & RCL Series>



Explanation of movement patterns

The SEP controller is able to select and perform the following 6 movement patterns.

Also, movement patterns 0 to 2 are compatible with both the single solenoid and double solenoid signal formats.

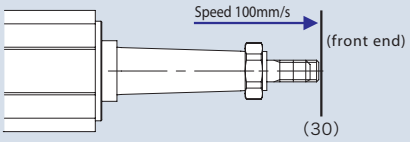
PIO pattern		0		1		2		3	4	5
PIO pattern name		Standard 2-point travel		Travel speed change		Position data Change		2-input 3-point travel	3-input 3-point travel	Continuous cycle operation
Functions		2-point travel		2-point travel		2-point travel		3-point travel	3-point travel	Continuous movement between 2 points
		Pushing operation		Pushing operation		Pushing operation		Pushing operation	Pushing operation	Pushing operation
		–		Speed change during travel		Positioning point data change		–	–	–
Supported solenoid configurations		single	double	single	double	single	double	–	–	–
Input	0	Movement signal	Movement signal 1	Movement signal	Movement signal 1	Movement signal	Movement signal 1	Movement signal 1	Retracting proximity movement signal	Continuous operation signal
	1	Pause signal	Movement signal 2	Pause signal	Movement signal 2	Pause signal	Movement signal 2	Movement signal 2	Extending proximity movement signal	Pause signal
	2	– (Reset signal)		Travel speed change signal (Reset signal)		Target position change signal (Reset signal)		– (Reset signal)	Midway travel command signal (Reset signal)	– (Reset signal)
	3	– /Servo ON signal		– /Servo ON signal		– /Servo ON signal		– /Servo ON signal	– /Servo ON signal	– /Servo ON signal
Output	0	Retracting proximity position output signal		Retracting proximity position output signal		Retracting proximity position output signal		Retracting proximity position output signal	Retracting proximity position output signal	Retracting proximity position output signal
	1	Extending proximity position output signal		Extending proximity position output signal		Extending proximity position output signal		Extending proximity position output signal	Extending proximity position output signal	Extending proximity position output signal
	2	Home return completion signal /Servo ON output signal		Home return completion signal /Servo ON output signal		Home return completion signal /Servo ON output signal		Midway position output signal	Midway position output signal	Home return completion signal /Servo ON output signal
	3	Alarm output signal /Servo ON output signal		Alarm output signal /Servo ON output signal		Alarm output signal /Servo ON output signal		Alarm output signal /Servo ON output signal	Alarm output signal /Servo ON output signal	Alarm output signal /Servo ON output signal

*For details of the signals listed above, see the Controller User's Manual. (Can be downloaded from our corporate website.)

PIO pattern 0 (Standard 2-point travel)

This is the movement pattern for movement between the 2 positions, the front and rear ends.
Front and rear end position values can be freely set. (Input in controller using optional touch panel teaching)
Two operations are possible: To move to position indicated for rod and slider, "Positioning operation"; and "Push-motion operation" to push rod to work part, etc.

Positioning operation (single solenoid)

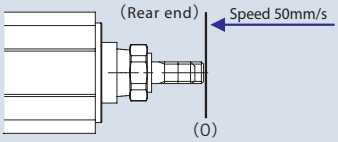


Front end position data	
Position	30
Speed	100
Push force	–
Width	–

Input signal

Input 0	ON
Input 1	–
Input 2	–
Input 3	–

Move with Input ON to extend
(position value 30mm) at speed of 100mm/s.



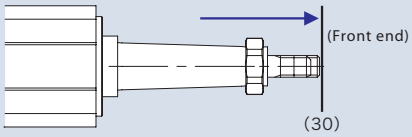
Rear end position data	
Position	0
Speed	50
Push force	–
Width	–

Input signal

Input 0	OFF
Input 1	–
Input 2	–
Input 3	–

Return with Input 0 OFF to retract
(position value 0mm) at speed of 50mm/s.

Positioning operation (double solenoid)

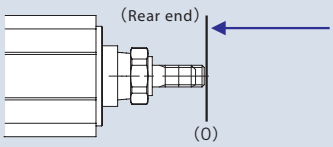


Front end position data	
Position	30
Speed	100
Push force	–
Width	–

Input signal

Input 0	OFF
Input 1	ON
Input 2	–
Input 3	–

With Input 1 ON/Input 0 OFF extend (position 30mm) at speed of 100mm/s.



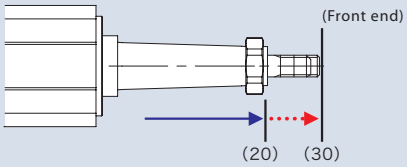
Rear end position data	
Position	0
Speed	50
Push force	–
Width	–

Input signal

Input 0	ON
Input 1	OFF
Input 2	–
Input 3	–

With Input 0 ON/ Input 1 OFF, retract at speed of 50mm/s.

Push operation (single solenoid)



Front end position data	
Position	30
Speed	100
Push force	50
Width	10

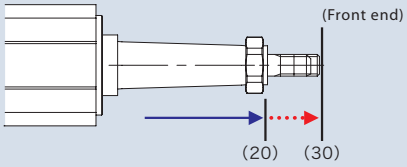
Input signal

Input 0	ON
Input 1	–
Input 2	–
Input 3	–

Start push operation with Input 0 ON and up to 20mm position at speed of 100mm/s; from 20mm position to 30mm position at low speed (5mm/s).

* Perform push operation when controller position data value is entered in push force. (Becomes positioning operation when value is not entered in push force.)

For push operation (double solenoid)



Front end position data	
Position	30
Speed	100
Push force	50
Width	10

Input signal

Input 0	OFF
Input 1	ON
Input 2	–
Input 3	–

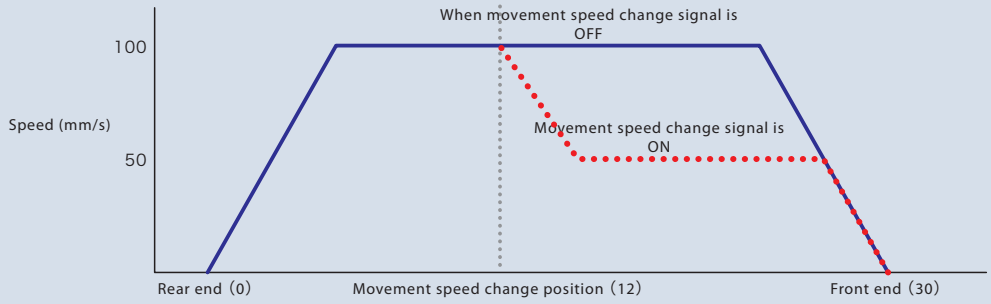
Start push operation with Input 1 ON/Input 0 OFF, and up to 20mm position at speed of 100mm/s; from 20mm position to 30mm position at low speed (5mm/s).

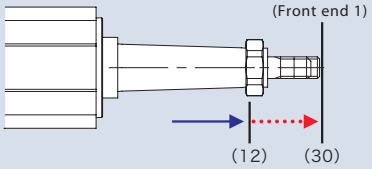
* Perform push operation when controller position data value is entered in push force. (Becomes positioning operation when value is not entered in push force.)

PIO pattern 1 (Travel speed change)

This is the PIO pattern for movement between the 2 positions, the front and rear ends.
It is possible to change movement speed in two stages. (Speed up/Speed down is possible)
To switch, designate the speed change position with the position value. The speed will change after movement past that position.

(Single solenoid)





Input signal

Input 0	ON
Input 1	–
Input 2	ON
Input 3	–

With Input 2 ON and Input 0 ON, it goes partially at set movement speed, then the speed changes after it passes through speed change position. Speed change cannot be performed when Input No. 2 is not ON.

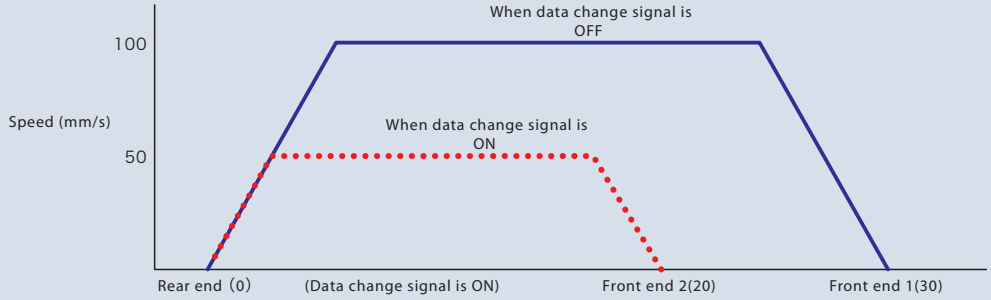
Rear end position data	
Position	0
Speed	50
Speed change position	12
Changed speed	100
Push force	–
Position band	–

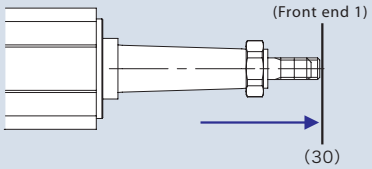
Front end position data	
Position	30
Speed	100
Speed change position	12
Changed speed	50
Push force	–
Position band	–

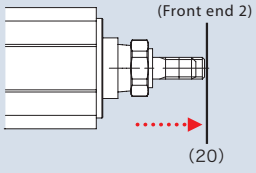
PIO pattern 2 (position data change)

This is the PIO pattern for movement between the 2 positions, the front and rear points.
Front end and rear end positions, speed, push force, and 2 types of push force positioning bands can be set.
Switch between 2 types of data with Input 2 target position change signal ON or OFF.

(Single solenoid)







Input signal

Input 0	ON
Input 1	–
Input 2	ON
Input 3	–

Perform movement with Input 2 (data change signal) OFF, Input 0 is ON, set position (30) at forward end position data 1, speed (100).
If Input 2 is ON and Input 0 is ON, movement performed with forward end position data 2 and position set at (20), and speed changed to (50).
Movement started with Input 2 OFF, and when Input 2 is ON during movement, from that time on it becomes movement position, speed change.

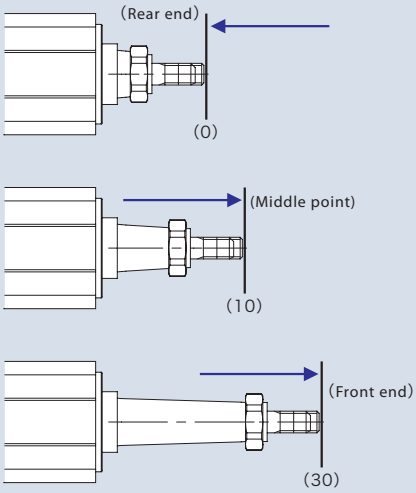
Front end position data 1	
Position	30
Speed	100
Push force	–
Positioning bands	–

Front end position data 2	
Position	20
Speed	50
Push force	–
Positioning bands	–

PIO pattern 3 (2-input 3-point travel)

This is the PIO pattern to perform movement for front end, rear end, and middle position between the three positions.
The change of movement positions are decided by a combination of two signals, Input 0 and Input 1.

Positioning operation



Input signal

Input 0	ON
Input 1	OFF
Input 2	–
Input 3	–

When only Input 0 is ON, move with the set speed to the rear end.

Input signal

Input 0	ON
Input 1	ON
Input 2	–
Input 3	–

When both Input 0 and 1 are ON, move with the set speed to the middle position.

Input signal

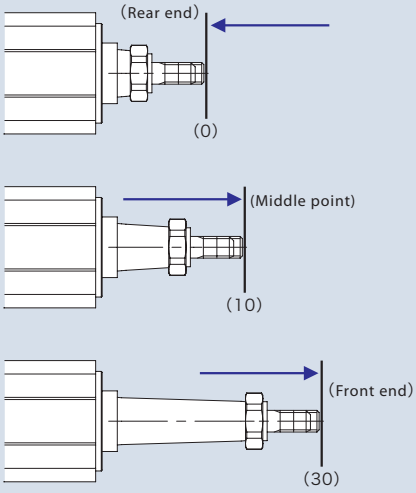
Input 0	OFF
Input 1	ON
Input 2	–
Input 3	–

When only Input 1 is ON, move with the set speed to the front end.

PIO pattern 4 (3-input 3-point travel)

This is the PIO pattern to perform movement for front end, rear end, and middle position between the three positions.
Changes in movement positions are decided by the combination of 3 signals: Input 0 (rear end movement command), Input 1 (front end movement command) and Input 2 (middle point movement command).

Positioning operation



Input signal

Input 0	ON
Input 1	OFF
Input 2	OFF
Input 3	–

Perform movement when Input 0 is ON, and speed is set to the rear end.

Input signal

Input 0	OFF
Input 1	OFF
Input 2	ON
Input 3	–

Perform movement when Input 2 is ON, and speed is set to the middle position.

Input signal

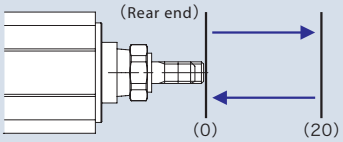
Input 0	OFF
Input 1	ON
Input 2	OFF
Input 3	–

Perform movement when Input 1 is ON, and speed is set to the front end.

PIO pattern 5 (continuous cycle operation)

This is the PIO pattern for continuous cycle operation between 2 positions.
If Input 0 (continuous operation signal) is ON, perform continuous movement between 2 set positions.
When Input 0 is OFF during operation, it stops after movement to the destination position is reached.

Positioning operation



Input signal

Input 0	ON
Input 1	–
Input 2	–
Input 3	–

Perform continuous movement if Input 0 is ON and with speed set to the front end and to the rear end.

I/O signal table

Pin No.	Cable color	PIO pattern number		0		1		2		3	4	5
		PIO pattern name		Standard 2-point travel		Travel speed change		Position data change		2-input 3-point travel	3-input 3-point travel	Continuous cycle operation
		Solenoid type		single	double	single	double	single	double	–	–	–
1	Brown	COM		24V		24V		24V		24V	24V	24V
2	Red	COM		0V		0V		0V		0V	0V	0V
3	Orange	Input	0	ST0	ST0	ST0	ST0	ST0	ST0	ST0	ST0	ASTR
4	Yellow		1	*STP	ST 1(–)	*STP	ST 1(–)	*STP	ST 1(–)	ST1	ST 1(–)	–/*STP
5	Green		2	– (RES)		SPDC (RES)		CN 1(RES)		– (RES)	– (RES)	– (RES)
6	Blue		3	–/SON		–/SON		–/SON		–/SON	–/SON	–/SON
7	Purple	Output	0	LS0/PE0		LS0/PE0		LS0/PE0		LS0/PE0	LS0/PE0	LS0/PE0
8	Gray		1	LS1/PE1		LS1/PE1		LS1/PE1		LS1/PE1	LS1/PE1	LS1/PE1
9	White		2	HEND/SV		HEND/SV		HEND/SV		HEND/SV	HEND/SV	HEND/SV
10	Black		3	*ALM/SV		*ALM/SV		*ALM/SV		*ALM/SV	*ALM/SV	*ALM/SV

*For details of the signals listed above, see the Controller User's Manual. (Can be downloaded from our corporate website.)

Specification Table

Item		Specifications			
Controller Type		PSEP		ASEP	
		C	CW	C	CW
Connected Actuator		RCP2/RCP3 series actuators		RCA/RCA2/RCL series actuators	
Number of control axes		1 Axis			
Operating method		Positioner type			
Number of positions		2-point/ 3-point (4-point) (*2)			
Backup memory		EEPROM			
I/O connector		10-pin connector			
Number of I/O		4 input points/4 output points			
I/O power		External supply DC24V±10%			
Serial communications		RS485 1ch			
Peripheral device communication cable		CB-APSEP-PIO□□□	CB-APSEPW-PIO□□□	CB-APSEP-PIO□□□	CB-APSEPW-PIO□□□
Position detection method		Incremental encoder (Attaching an absolute battery unit makes the simple absolute specification possible.) (*3)			
Motor-encoder cable	RCP2 connection-use	CB-PSEP-MPA□□□		(Connection not possible)	
	RCA connection-use	(Connection not possible)		CB–ASEP–MPA□□□	
	RCP3/RCA2 connection-use	CB-APSEP-MPA□□□			
	RCP2 small rotary connection-use	CB–RPSEP–MPA□□□		(Connection not possible)	
Input power		DC24V±10%			
Control power supply capacity		0.5A (In the case of simple absolute specifications, 0.8A)			

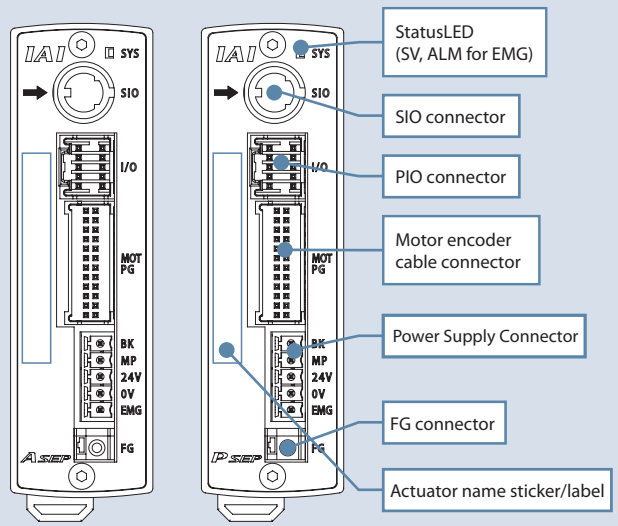
Motor power supply capacity						
Motor size	Rated	Max. (*4)	Motor W number	Rated	Max.	
					Power-saving specification (*5)	Standard high acceleration specification (*6)
20P	0.4A	2.0A	2W	0.8A	-	4.6A
28P	0.4A	2.0A	5W	1.0A	-	6.4A
35P	1.2A	2.0A	10W (RCL-use)	1.3A	-	6.4A
42P	1.2A	2.0A	10W (RCA/RCA2-use)	1.3A	2.5A	4.4A
56P	1.2A	2.0A	20W	1.3A	2.5A	4.4A
–	–	–	20W (20S motor-use)	1.7A	3.4A	5.1A
–	–	–	30W	1.3A	2.2A	4.4A

Inrush current (*1)	Max10A			
Amount of heat generated	8.4W		9.6W	
Dielectric strength voltage	DC500V 1MΩ			
Vibration resistance	XYZ in each direction	10 to 57Hz/one-side width 0.035m (continuous), 0.075m (intermittent) 58 to 150Hz/4.9m/s², 9.8m/s²		
Ambient temperature	0 to 40°C			
Ambient humidity	85% RH or less (No condensation)			
Ambient atmosphere	Free from corrosive gases.			
Protection Class	IP20	IP53 (*7)	IP20	IP53 (*7)
Weigh	Approx. 130g	Approx. 160g	Approx. 130g	Approx. 160g

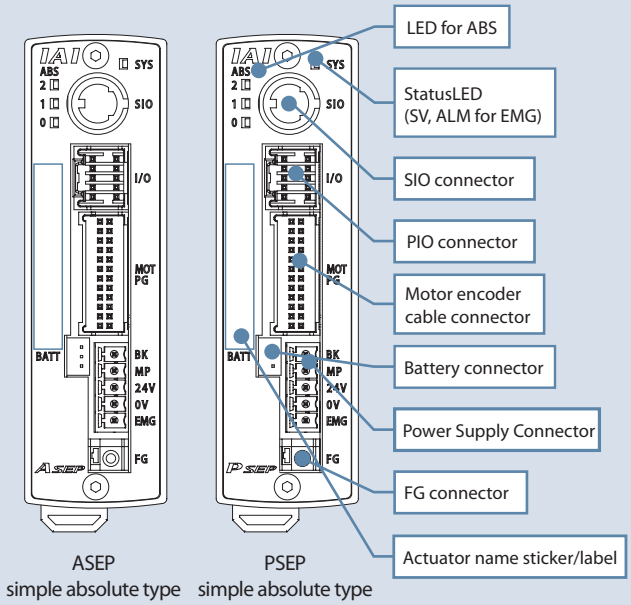
(*1) Inrush current flows for approximately 1 to 2ms after power is turned on. It is approximately 5 to 12 times greater than the rated current. Note that the inrush current varies according to the impedance of the power supply line.
(*2) In a position data change movement pattern, two position data points have been set for each of the extending and retracting edges.
(*3) A simple absolute type controller cannot be used with a linear motor type.
(*4) After the power is turned on, an excitation detection operation is performed. The current reaches its maximum level when this happens. (Usually 100ms.)
However, if the motor drive power supply is temporarily interrupted and then resumed, a current of approximately 6.0A will flow. (Approx. 1 to 2ms)
(*5) During an execution of pole sense and in case of collision or constraint the current reaches its maximum level and the above mentioned current is required. The longest time is approx. 10 seconds during during an execution of pole sense.
(*6) During acceleration or deceleration and in case of collision or constraint the current reaches its maximum level. The longest time of current flow is in case of collision and constraint.
Until the end of detection of overload the above mentioned current is required.
(*7) Not including the bottom surface.

Names of Each Part

ASEP, PSEP Incremental type

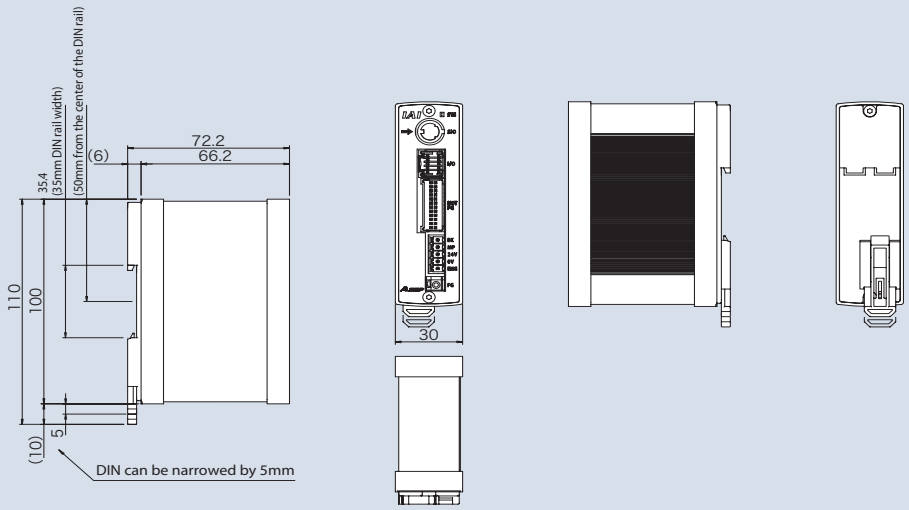


ASEP, PSEP Simple absolute type

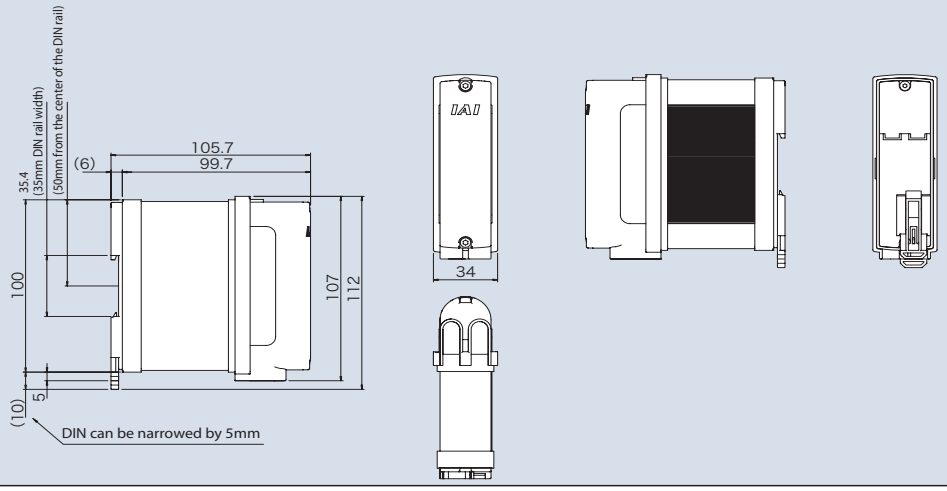


External Dimensions

Standard type



Dustproof type



Absolute battery unit for SEP controller

Description Products that come with PSEP/ASEP Simple Absolute type.
Battery unit for backing up current position data with battery.

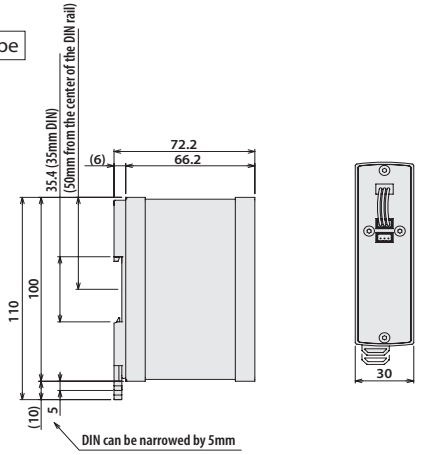
Model **SEP-ABU** (standard type)
SEP-ABU-W (dustproof type)

Specifications

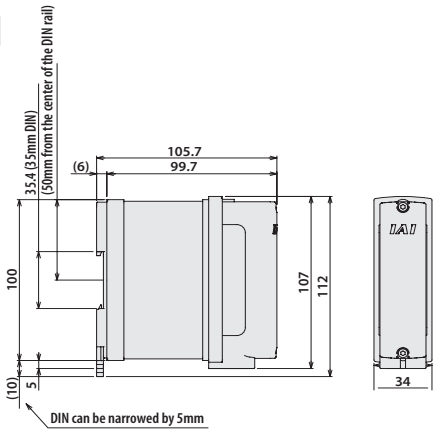
Item	Specifications			
Ambient operating temperature and humidity	0 to 40°C (about 20°C), 95% RH or below (no condensation)			
Ambient operating environment	Free from corrosive gases.			
Absolute Battery (*1)	Model: AB-7 (Ni-MH battery/life about 3 years)			
Cable (*1) for connection between the controller and the absolute battery unit	Model: CB-APSEP-AB005 (length 0.5m)			
Weight	Standard type: about 230g/dustproof type: about 260g			
Allowable encoder RPM during data retention (*2)	800rpm	400rpm	200rpm	100rpm
Position data retention time (*2)	120h	240h	360h	480h

(*1) Absolute battery unit comes with the cable for connecting between the absolute battery unit and the controller
(*2) Position data retention time changes with the allowable encoder RPMs during data retention.
(800rpm→120h, 400rpm→240h, 200rpm→360h, 100rpm→480h)

Standard type



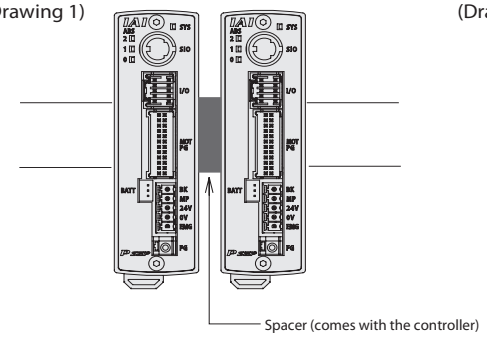
Dustproof type



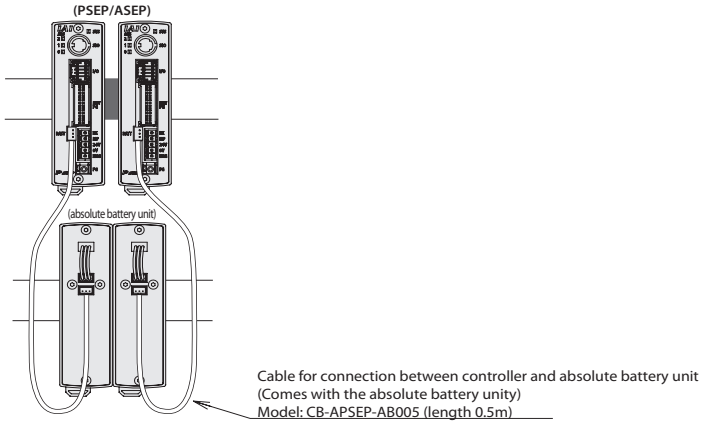
Precautions related to controllers and options:

- As a countermeasure for heat dissipation, please insert a spacer to prevent controllers from sticking together when attaching the controller to the DIN rail. (See Drawing 1.)
- Please put the absolute battery in a place under the controller when attaching the absolute battery unit and the controller. (See Drawing 2.) When you cannot place it below due to space considerations, take care to position it so that the temperature around the controller is kept at 40˚C or less.

(Drawing 1)



(Drawing 2)



- Teaching box for PCON/ACON/SCON (CON-T-ENG, RCM-E, etc.) cannot be used in PSEP/ASEP. Please use the dedicated SEP-PT-ENG for PSEP/ASEP. Also, the PC compatible software (RCM-101-MW/USB-EU) currently cannot be used with PSEP/ASEP.
- The SEP-PT-ENG cannot communicate with a link connection to the controller. (Please use it in direct connection to the controller.)

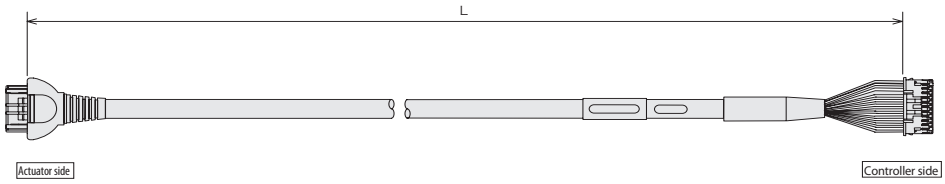
Maintenance parts

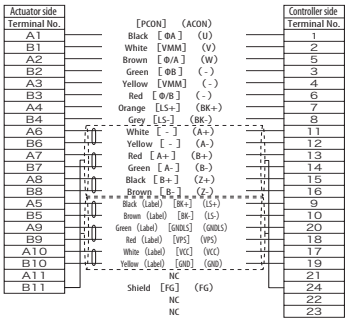
Please refer to the models listed below if a cable needs to be exchanged, etc., after your purchase.

(RCP3/RCA2) - (PSEP/ASEP) Integrated motor/P3-A3-encoder cable

Model **CB-APSEP-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

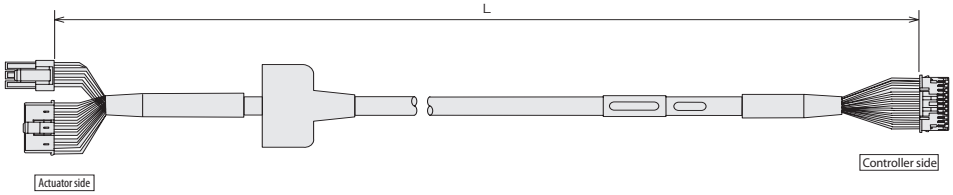


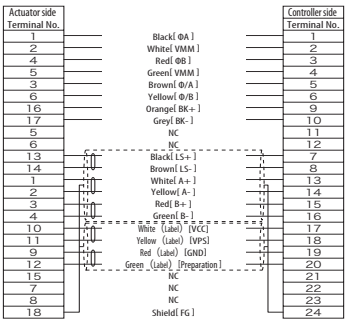


(RCP2) - (PSEP) Motor/P3-encoder cable

Model **CB-PSEP-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

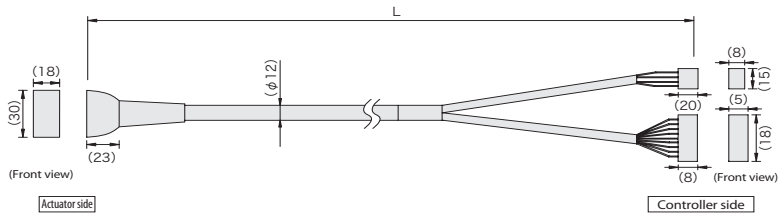


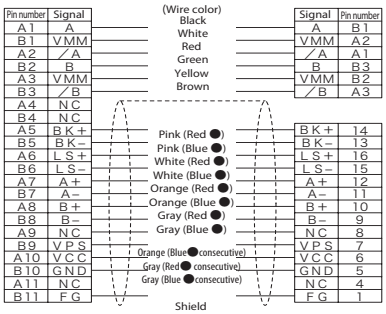


(RCP3) - (PCON/RPCON/PSEL) Motor/P1-encoder cable

Model **CB-PCS-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

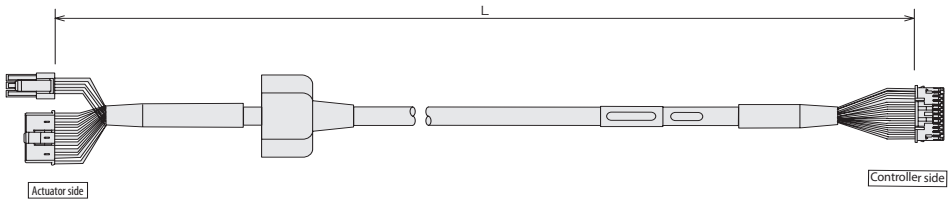


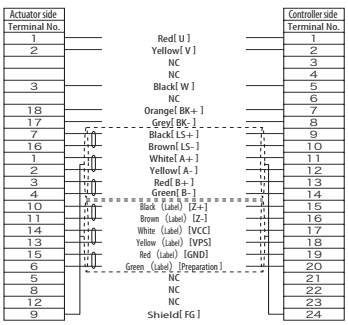


(RCA) - (ASEP) Motor/A3-encoder cable

Model **CB-ASEP-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

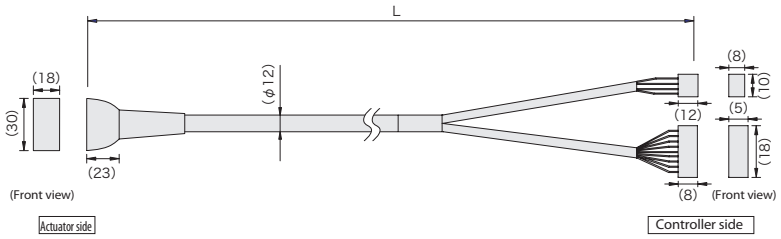




(RCA2) - (ACON/RACON/ASEL) - Motor/A1-encoder cable

Model **CB-ACS-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

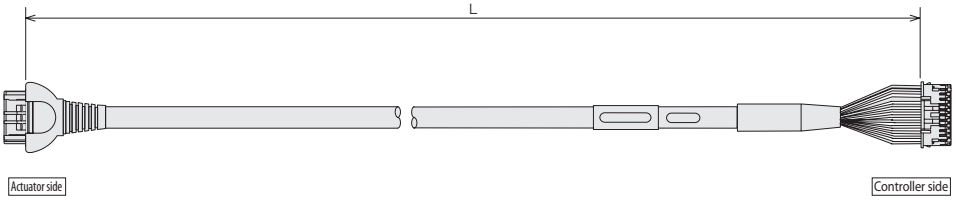


Pin number	Signal	(Wire color)	Signal	Pin number
A1	U	Red	U	1
B1	V	Yellow	V	2
A2	W	Black	W	3
B2	NC			
A3	NC			
B3	NC			
A4	BK+	Yellow (Red ●)	BK+	16
B4	BK−	Yellow (Blue ●)	BK−	15
A5	LS+	Pink (Red ●)	LS+	18
B5	LS−	Pink (Blue ●)	LS−	17
A6	A+	White (Red ●)	A+	14
B6	A−	White (Blue ●)	A−	13
A7	B+	Orange (Red ●)	B+	12
B7	B−	Orange (Blue ●)	B−	11
A8	Z+	Gray (Red ●)	Z+	10
B8	Z−	Gray (Blue ●)	Z−	9
A9	−	Orange (Red● consecutive)	−	8
B9	/PS	Orange (Blue● consecutive)	/PS	7
A10	VCC	Gray (Red● consecutive)	VCC	6
B10	GND	Gray (Blue● consecutive)	GND	5
A11	NC		NC	
B11	FG	Shield	FG	1

(RCP2 small rotary) - (PSEP) - Small rotary motor/P3-encoder cable

Model **CB-RPSEP-MPA □□□**

*□□□ indicated the cable length (L) Lengths up to 20m can be specified Example) 080=8m

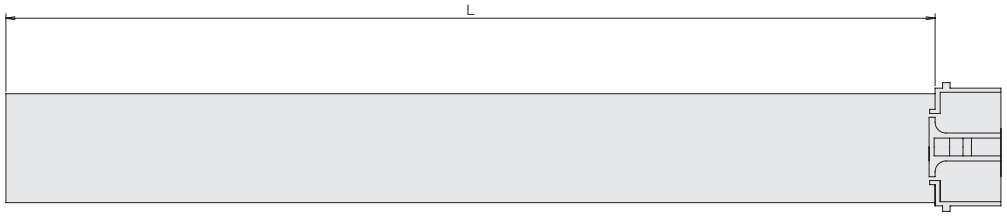


Actuator side Terminal No.		Controller side Terminal No.
A1	Black[ΦA]	1
B1	White[VMM]	2
A2	Brown[Φ/A]	5
B2	Green[ΦB]	3
A3	Yellow[VMM]	4
B3	Red[Φ/B]	6
A6	Orange[LS+]	7
B6	Grey[LS-]	8
A7	Red[A+]	13
B7	Green[A-]	14
A8	Black[B+]	15
B8	Brown[B-]	16
A4	NC	7
B4	NC	8
A5	Black (Label) [BK+]	9
B5	Brown (Label) [BK-]	10
A9	Green (Label) [GND(LS)]	20
B9	Red (Label) [VPS]	18
A10	White (Label) [VCC]	17
B10	Yellow (Label) [GND]	19
A11	NC	21
B11	Shield[FG] (FG)	24
	NC	22
	NC	23

I/O cable for PSEP-C/ASEP-C

Model **CB-APSEP-PIO □□□**

*Enter the cable length (L) for □□□, up to a maximum compatible length of 10m. Example) 080=8m



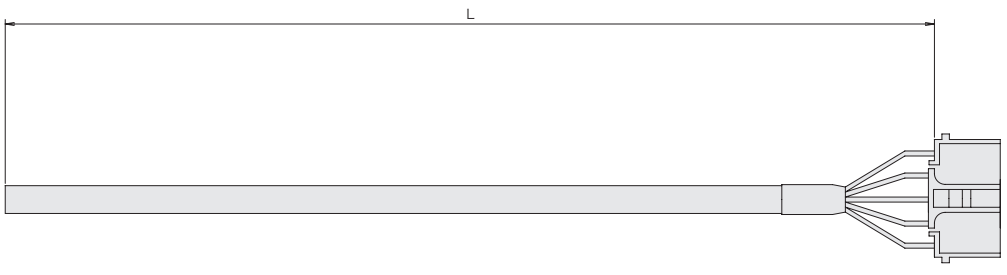
51353-1000 (MOLEX)

No.	Signal	Color	Wiring
1	24V	Brown	Flat Cable (crimped)
2	0V	Red	
3	IN0	Orange	
4	IN1	Yellow	
5	IN2	Green	
6	IN3	Blue	
7	OUT0	Purple	
8	OUT1	Grey	
9	OUT2	White	
10	OUT3	Black	

I/O cable for PSEP-CW/ASEP-CW

Model **CB-APSEPW-PIO □□□**

*Enter the cable length (L) for □□□, up to a maximum compatible length of 10m. Example) 080=8m



51353-1000 (MOLEX)

No.	Signal	Color	Wiring
1	24V	Brown	Cable (crimped)
2	0V	Brown-White	
3	IN0	Red	
4	IN1	Red-White	
5	IN2	Yellow	
6	IN3	Yellow-White	
7	OUT0	Green	
8	OUT1	Green-White	
9	OUT2	Black	
10	OUT3	Black-White	

RCP3&RCA2&RCL Series
Miniature Type
Catalogue No. 1109-E

The information contained in this catalog is subject to change without notice for the purpose of product inprovement

ISO 9001

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